

# Service Manual

**COMPACT**  
**disc**  
DIGITAL AUDIO

**DIGITAL**

**MASH\***  
multi-stage noise shaping

Compact Disc Changer  
**SL-PD449**

Colour

(K) ... Black Type

Area

Suffix for Model No.	Area	Colour
(P)	U.S.A.	(K)



- ※ • Technics (or Panasonic) developed the world's first MASH type DAC and ADC. MASH technology was invented by NTT (LSI Labs).  
• MASH is a trademark of NTT.

## RAE0113Z MECHANISM SERIES

### ■ SPECIFICATIONS

#### ■ AUDIO

No. of channels	2 (left and right, stereo)
Frequency response	2-20,000 Hz, ±1 dB
Output voltage	2 V (at 0 dB)
Dynamic range	92 dB
S/N	100 dB
Total harmonic distortion	0.007 % (1 kHz, 0 dB)
Wow and flutter	Below measurable limit
DA converter	MASH (1 bit)
Output impedance	Approx. 1 kΩ
Load impedance	More than 10 kΩ

#### ■ PICKUP

Wavelength 780 nm

#### ■ GENERAL

Power consumption	11 W
Power supply	AC 120 V, 60 Hz
Dimensions (W × H × D)	360 × 125 × 370 mm (14-3/16" × 4-15/16" × 14-9/16")
Weight	4.1 kg (9.1 lb.)

#### Note:

Design and specifications are subject to change without notice.  
Weight and dimensions are approximate.

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**⚠ WARNING**

This service literature is designed for experienced repair technicians only and is not designed for use by the general public. It does not contain warnings or cautions to advise non-technical individuals of potential dangers in attempting to service a product. Products powered by electricity should be serviced or repaired only by experienced professional technicians. Any attempt to service or repair the product or products dealt with in this service literature by anyone else could result in serious injury or death.

**■ PRECAUTION OF LASER DIODE**

**CAUTION:** This unit utilizes a class 1 laser. Invisible laser radiation is emitted from the optical pickup lens when the unit is turned on:

1. Do not look directly into the pickup lens.
2. Do not use optical instruments to look at the pickup lens.
3. Do not adjust the preset variable resistor on the optical pickup.
4. Do not disassemble the optical pickup unit.
5. If the optical pickup is replaced, use the manufactures specified replacement pickup only.
6. Use of control or adjustments or performance of procedures other than those specified herin may result in hazardous radiation exposure.

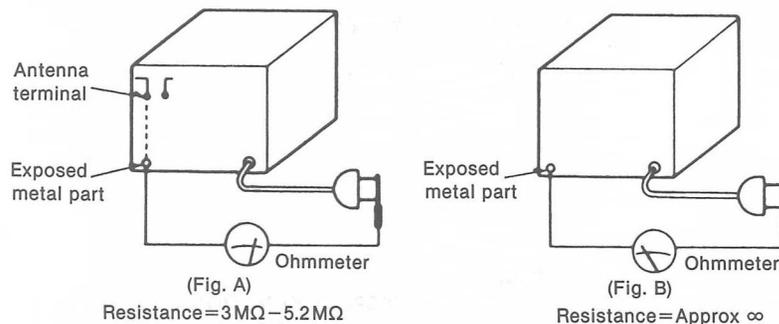
**■ SAFETY PRECAUTION** (This "safety precaution" is applied only in U.S.A.)

1. Before servicing, unplug the power cord to prevent an electric shock.
2. When replacing parts, use only manufacturer's recommended components for safety.
3. Check the condition of the power cord. Replace if wear or damage is evident.
4. After servicing, be sure to restore the lead dress, insulation barriers, insulation papers, shields, etc.
5. Before returning the serviced equipment to the customer, be sure to make the following insulation resistance test to prevent the customer from being exposed to a shock hazard.

**• INSULATION RESISTANCE TEST**

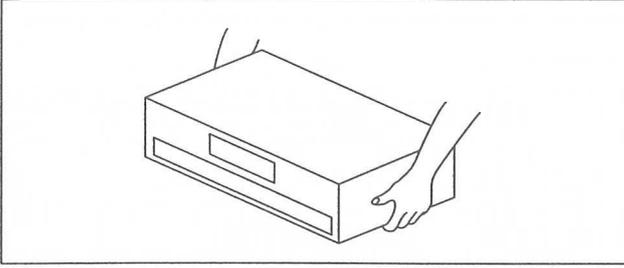
1. Unplug the power cord and short the two prongs of the plug with a jumper wire.
2. Turn on the power switch.
3. Measure the resistance value with ohmmeter between the jumpered AC plug and each exposed metal cabinet part, such as screwheads antenna, control shafts, handle brackets, etc. Equipment with antenna terminals should read between  $3\text{M}\Omega$  and  $5.2\text{M}\Omega$  to all exposed parts. (Fig. A) Equipment without antenna terminals should read approximately infinity to all exposed parts. (Fig. B)

**Note:** Some exposed parts may be isolated from the chassis by design. These will read infinity.



4. If the measurement is outside the specified limits, there is a possibility of a shock hazard. The equipment should be repaired and rechecked before it is returned to the customer.

## CAUTIONS CONCERNING THE MOVING OF THIS UNIT



### CAUTION

Before moving the changer to another location, be sure to carry out the "Preparations for moving the unit" described below.

Failure to do so will expose the compact discs and the changer to the risk of severe damage.

### Preparations for moving the unit

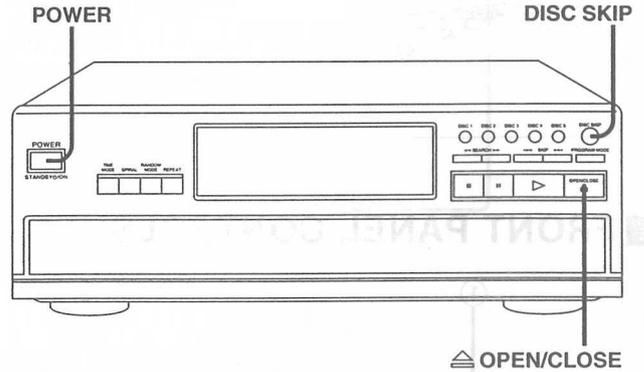
All of the discs must be removed so that the trays are completely empty.

Use the following procedure.

- ① Press **POWER** to switch off the unit.
- ② Press **POWER** to switch on the unit.  
(If there is a disc in the play section, it will be returned to the disc tray at this time.)
- ③ Press **OPEN/CLOSE** to open the loading drawer.

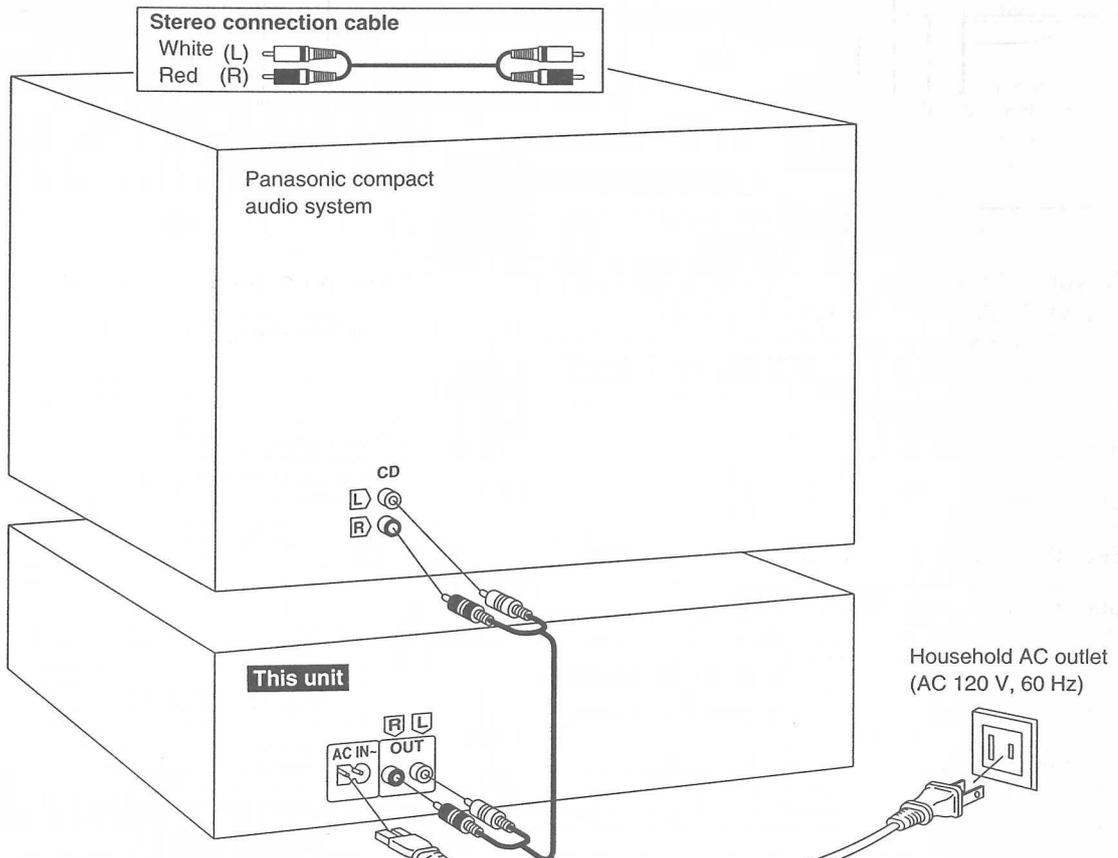
- ④ Press **DISC SKIP** to rotate the disc trays and remove the discs from all disc trays.
- ⑤ Press **OPEN/CLOSE** to close the loading drawer.
- ⑥ Press **POWER** to switch off the unit.

If you have pressed a wrong button by mistake, return to step ①.



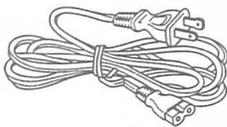
## CONNECTIONS

Before connecting the changer to your audio system, make sure that the power of the changer and all other system components are turned off.

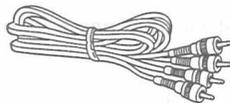


## ACCESSORIES

AC power supply  
cord ..... 1 pc.  
(SJA172)



Stereo connection  
cable ..... 1 pc.  
(SJP2249-3)



Remote control  
transmitter ..... 1 pc.  
(RAK-SL142WH)

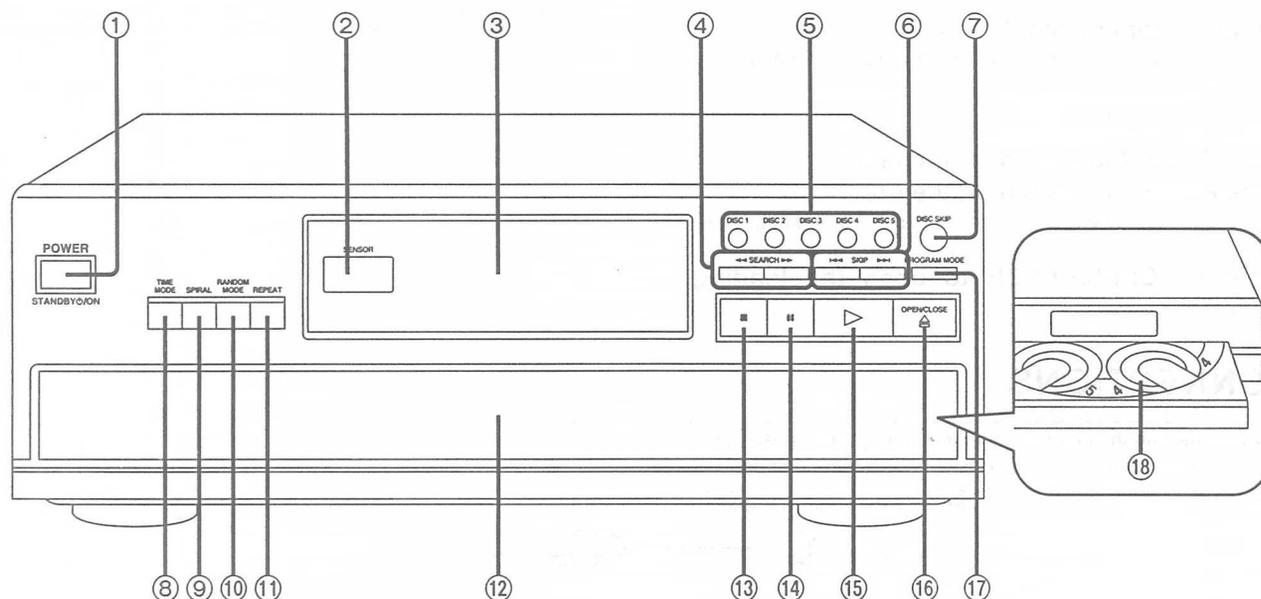


Batteries for  
remote control  
transmitter ..... 2 pcs.  
(UM-4, "AAA", R03)



**Note:** These are available  
on sale route.

## FRONT PANEL CONTROLS



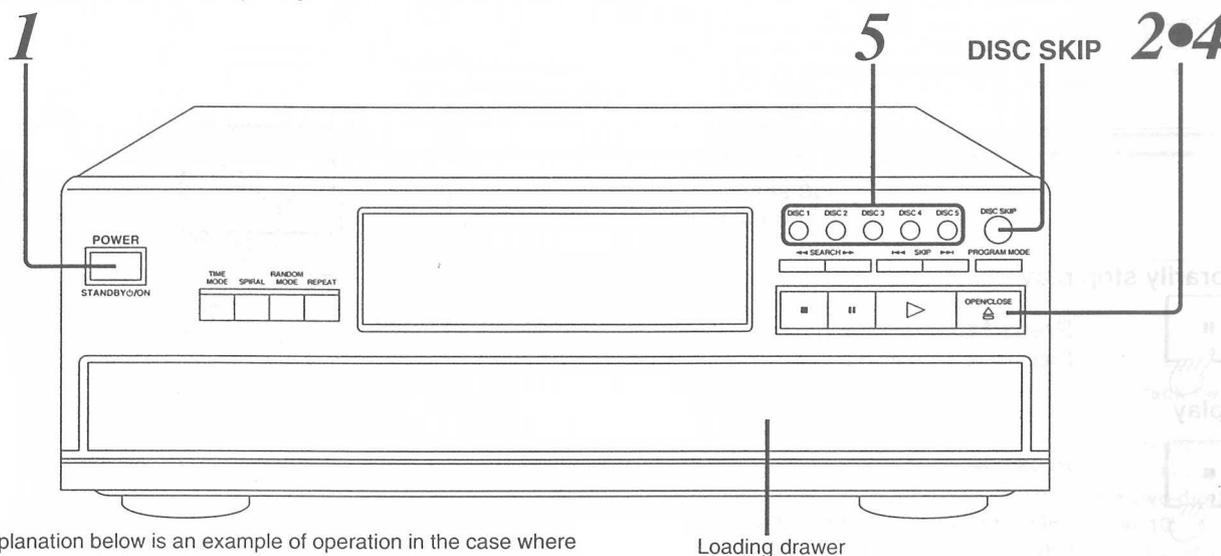
No.	Name
①	<b>Power "STANDBY <math>\odot</math>/ON" switch (POWER, STANDBY <math>\odot</math>/ON)</b> Press to switch the unit from on to standby mode or vice versa. In standby mode, the unit is still consuming a small amount of power.
②	<b>Remote control signal sensor (SENSOR)</b>
③	<b>Display</b>
④	<b>Search buttons (<math>\blacktriangleleft</math> SEARCH <math>\blacktriangleright</math>)</b>
⑤	<b>Disc buttons (DISC 1-5)</b>
⑥	<b>Skip buttons (<math>\blacktriangleleft</math> SKIP <math>\blacktriangleright</math>)</b>
⑦	<b>Disc skip button (DISC SKIP)</b>
⑧	<b>Time mode button (TIME MODE)</b>
⑨	<b>Spiral button (SPIRAL)</b>

No.	Name
⑩	<b>Random mode button (RANDOM MODE)</b>
⑪	<b>Repeat button (REPEAT)</b>
⑫	<b>Loading drawer</b>
⑬	<b>Stop button (<math>\blacksquare</math>)</b>
⑭	<b>Pause button (<math>\parallel</math>)</b>
⑮	<b>Play button (<math>\blacktriangleright</math>)</b>
⑯	<b>Loading drawer open/close button (<math>\triangle</math> OPEN/CLOSE)</b>
⑰	<b>Program mode button (PROGRAM MODE)</b>
⑱	<b>Disc trays (1-5)</b>

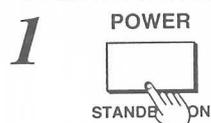
## BASIC OPERATIONS

### Sequential play

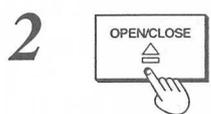
All of the discs will be played, beginning from track 1 on the selected disc.



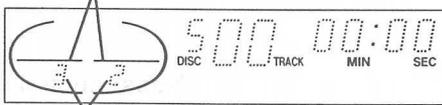
The explanation below is an example of operation in the case where all five disc trays in the changer are holding CDs.



**Press POWER.**  
The unit will switch on.



**Press OPEN/CLOSE to open the loading drawer.**  
Indicates that the loading drawer is open.

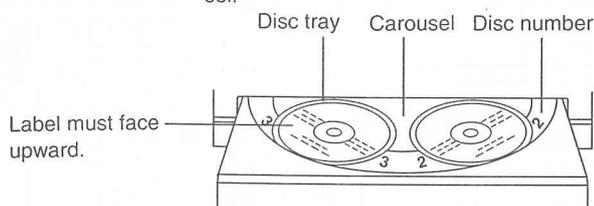


Numbers of the trays in which discs are loaded.

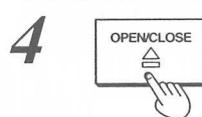


**Load the disc(s) on the disc tray(s).**

The discs can be loaded two at a time by pressing DISC SKIP to rotate the carousel.



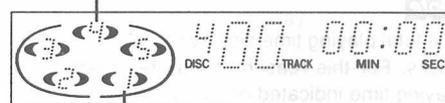
Do not load 3" (8 cm) and 5" (12 cm) discs on the same disc tray.



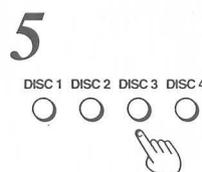
**Press OPEN/CLOSE again to close the loading drawer.**

Do not attempt to close the drawer by hand.

Current play position (The numeral illuminates with a red color.)



Illuminates when a disc is in the disc tray. If there is no disc in the disc tray, the indication disappears when the disc tray comes to the play position.

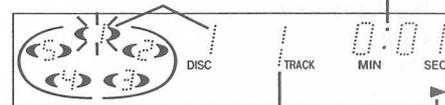


**Press the desired disc button (1-5).**

Play will begin from the selected disc.

If a disc is not on the selected disc tray, the changer plays the disc at the next number.

Disc number in play Elapsed play time

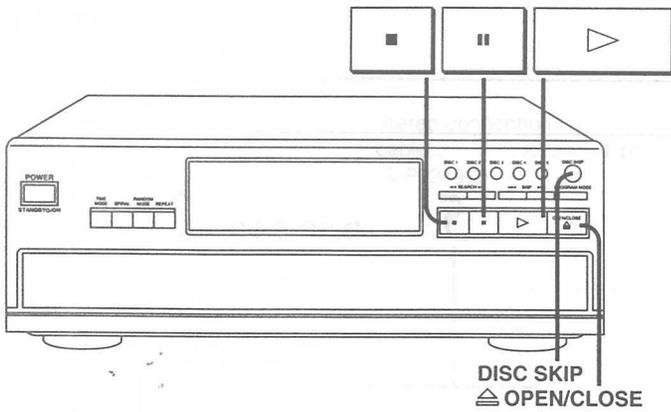


Track number in play Play indicator

The changer plays all the tracks on all the discs in order and stops automatically when the last track on the last disc finishes playing. The first disc will then be at the playing position.

### CAUTION

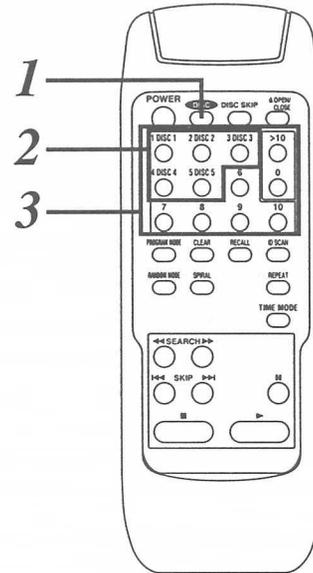
Do not touch the loading drawer and carousel while they are in motion, and do not attempt to rotate the carousel by hand; doing so could result in incorrect operation of the unit and/or damage to the discs.



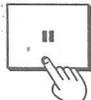
## DIRECT ACCESS PLAY

(Available only from the remote control)

This function involves starting play from a specific track on a specific disc and playing all discs on the five-disc tray in sequence.

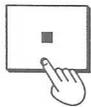


### To temporarily stop play

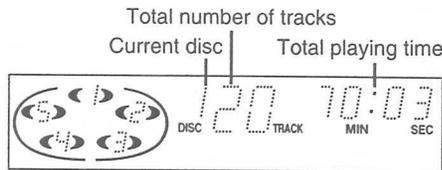


Press **||**.  
Press **▷** to resume play.

### To stop play



Press **■**.  
The display will show the total number of tracks and the total playing time of the current disc.



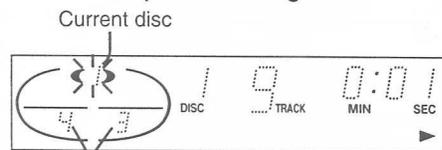
**Note**

The total playing time displayed includes the silent sections between tracks. For this reason, it may be a few seconds longer than the playing time indicated on the disc.

### To exchange discs during play

While playing a disc, it is possible to change the other discs without interrupting play.

① Press **△** OPEN/CLOSE to open the loading drawer.



Discs which can be changed.

② Press DISC SKIP to rotate the disc trays and exchange the discs.

The carousel will move by one disc tray. Pressing again moves the carousel in the opposite direction by two disc trays.

③ Press **△** OPEN/CLOSE to close the loading drawer.

**Note**

If you play a disc with the loading drawer open, discs other than the current disc cannot be played.

**CAUTION**

Do not move this changer with a compact disc inside the unit. If a disc comes off the disc tray, it might be scratched or the changer might become incapable of playing.

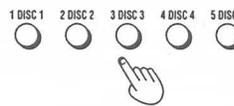
(Refer to "Cautions concerning the moving of this unit" on page 3.)

1



Press DISC.

2

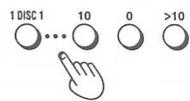


Press the numeric button (1–5) to select the disc.

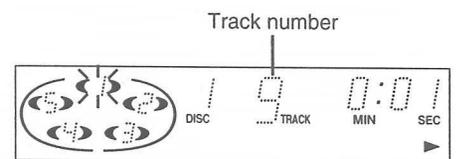
If the disc only is selected, play will begin its first track.

If a disc is not on the selected disc tray, the changer plays the disc at the next number.

3



Press the numeric button(s) to select the track.



To select a track between 1 and 10:

Press the corresponding number on the numeric button.

To select a two-digit track number over 10:

First press >10, and then press the numbers for the two digits.

For example; number 20:

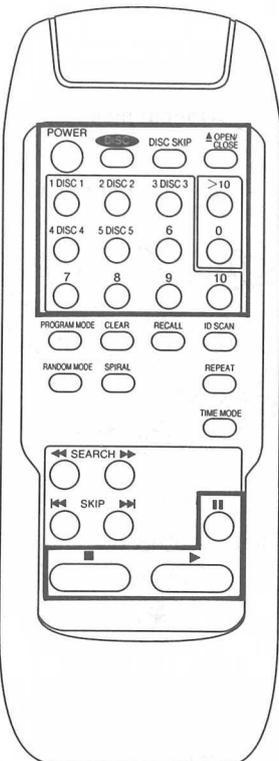
Press >10, then 2, and then 0.

Play begins at the track selected and continues through the end of the last disc.

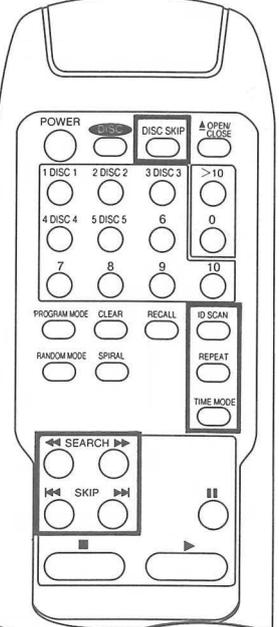
The changer will stop automatically when the last track on the last disc finishes playing.

## REMOTE CONTROL OPERATION

### Basic operation

	<b>To OFF/ON the main unit</b>	POWER 												
	<b>To open/close the loading drawer</b>													
	<b>To rotate the carousel</b>	DISC SKIP 												
	<b>To select the desired disc number</b>	 → <table style="display: inline-table; vertical-align: middle;"> <tr> <td>1 DISC 1</td> <td>2 DISC 2</td> <td>3 DISC 3</td> </tr> <tr> <td>4 DISC 4</td> <td>5 DISC 5</td> <td>6</td> </tr> <tr> <td>7</td> <td>8</td> <td>9</td> </tr> <tr> <td>0</td> <td>&gt;10</td> <td></td> </tr> </table>	1 DISC 1	2 DISC 2	3 DISC 3	4 DISC 4	5 DISC 5	6	7	8	9	0	>10	
	1 DISC 1	2 DISC 2	3 DISC 3											
	4 DISC 4	5 DISC 5	6											
	7	8	9											
0	>10													
<b>To select the desired track number</b>	<table style="display: inline-table; vertical-align: middle;"> <tr> <td>1 DISC 1</td> <td>2 DISC 2</td> <td>3 DISC 3</td> <td>&gt;10</td> </tr> <tr> <td>4 DISC 4</td> <td>5 DISC 5</td> <td>6</td> <td>0</td> </tr> <tr> <td>7</td> <td>8</td> <td>9</td> <td>10</td> </tr> </table> <p> <b>To select a track between 1 and 10:</b>            Press the corresponding number on the keypad.  <b>To select a two-digit track number over 10:</b>            First press &gt;10, and then press the numbers for the two digits.         </p>	1 DISC 1	2 DISC 2	3 DISC 3	>10	4 DISC 4	5 DISC 5	6	0	7	8	9	10	
1 DISC 1	2 DISC 2	3 DISC 3	>10											
4 DISC 4	5 DISC 5	6	0											
7	8	9	10											
<b>To start play</b>														
<b>To stop play temporarily</b>	 Press ► button to resume play.													
<b>To stop play</b>														

### Other functions

	<b>To skip discs</b>	DISC SKIP 
	<b>To skip tracks</b>	
	<b>To search for a desired place</b>	(In the play or pause mode) 
	<b>To start ID scan</b>	ID SCAN To cancel ID scan, press this button again. 
	<b>To repeat play</b>	REPEAT To cancel repeat mode, press this button again. 
	<b>To select time mode</b>	TIME MODE 

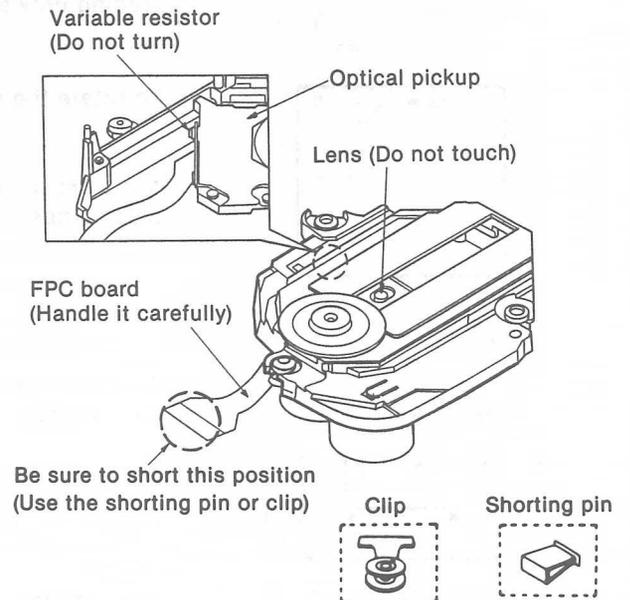
## HANDLING PRECAUTIONS FOR TRAVERSE DECK

The laser diode in the traverse deck (optical pickup) may break down due to potential difference caused by static electricity of clothes or human body.

So, be careful of electrostatic breakdown during repair of the traverse deck (optical pickup).

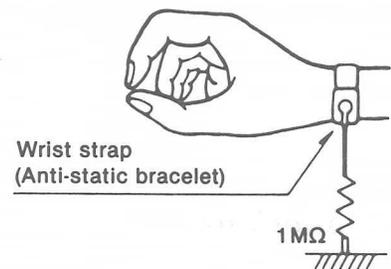
### • Handling of traverse deck (optical pickup)

1. Do not subject the traverse deck (optical pickup) to static electricity as it is extremely sensitive to electrical shock.
2. To prevent the breakdown of the laser diode, an antistatic shorting pin is inserted into the flexible board (FPC board).  
When removing or connecting the short pin, finish the job in as short time as possible.
3. Take care not to apply excessive stress to the flexible board (FPC board).
4. Do not turn the variable resistor (laser power adjustment). It has already been adjusted.



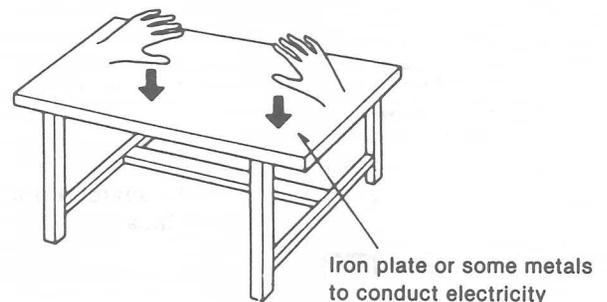
### • Grounding for electrostatic breakdown prevention

1. Human body grounding  
Use the anti-static wrist strap to discharge the static electricity from your body.
2. Work table grounding  
Put a conductive material (sheet) or steel sheet on the area where the optical pickup is placed, and ground the sheet.



### Caution:

The static electricity of your clothes will not be grounded through the wrist strap. So, take care not to let your clothes touch the traverse deck (optical pickup).



## ■ OPERATION CHECKS AND MAIN COMPONENT REPLACEMENT PROCEDURES

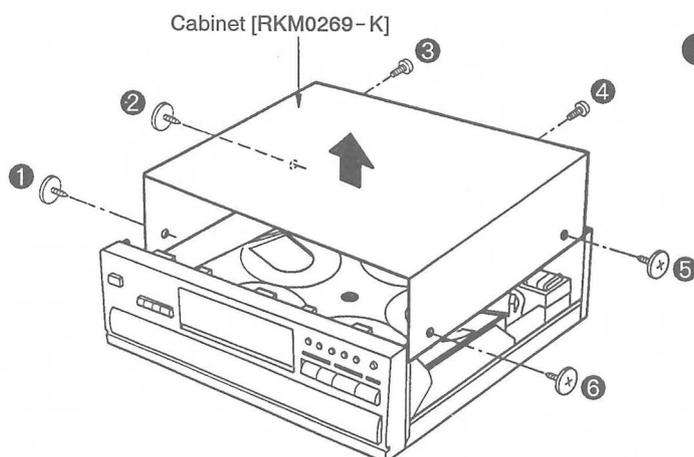
### NOTE

1. This section describes procedures for checking the operation of the major printed circuit boards and replacing the main components.
2. For reassembly after operation checks or replacement, reverse the respective procedures. Special reassembly procedures are described only when required.
3. Select items from the following index when checks or replacement are required.
4. Illustrated screws are equivalent to actual size.
5. [ ] indicates parts No.

### ● Contents

1. Checking for operation P.C.B. and power switch P.C.B. . . . .	page. 10.
2. Checking for the main P.C.B. . . . .	10~13.
3. Replacement for the belt and tray motor ass'y. . . . .	13.
4. Replacement for the belt and loading motor ass'y. . . . .	14.
5. Replacement for the drive gear(1), drive gear(2) and drive lever. . . . .	14.
6. Replacement for the pulley gear, drive cam and reduction gear. . . . .	15.
7. Checking for the servo P.C.B. . . . .	15~17.
8. Replacement for the traverse deck ass'y. . . . .	17,18.

### 1. Common disassembly procedures (Follow this procedure prior to other disassembly.)

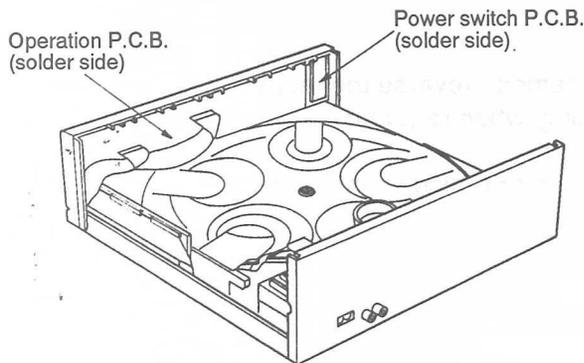


**Step 1** Remove the 6 screws.

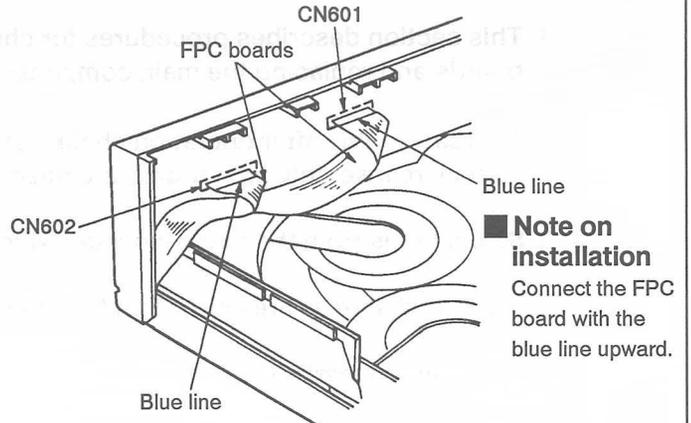
	<b>1, 2, 5, 6</b>
	[SNE2129-3] (Black)
	<b>3, 4</b>
	[XTBS3+8JFZ1] (Black)

## 2. Checking for the operation P.C.B. and power switch P.C.B.

**Step 1** Follow the disassembly procedure described in item 1 on page 9.

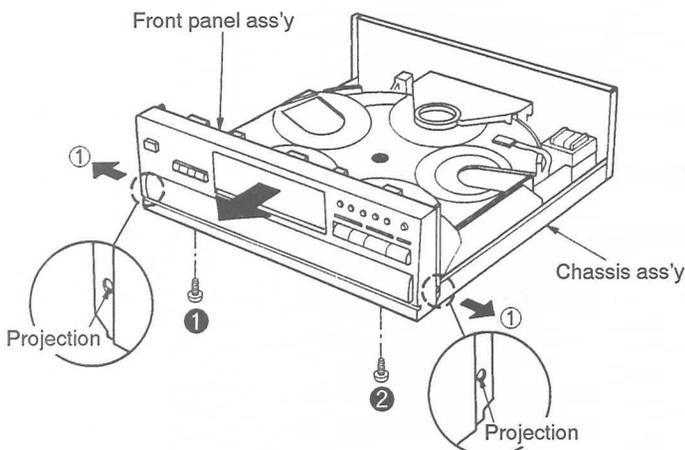


**Step 2** Pull out the FPC boards from connectors.

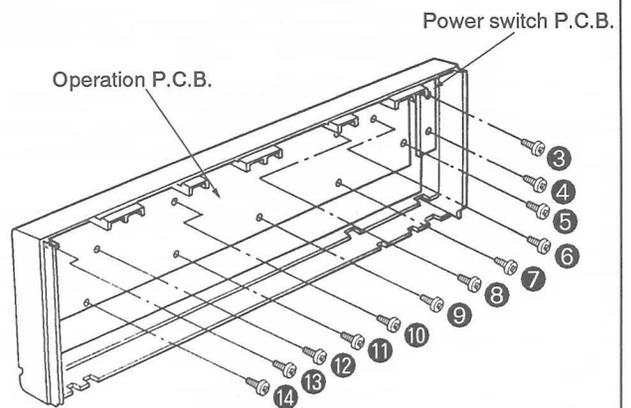


**Step 3** Remove the 2 screws (1, 2).

**Step 4** Pull the front panel ass'y in both direction of arrow ① to unlock it from the projections of the chassis ass'y.



**Step 5** Remove the 12 screws.

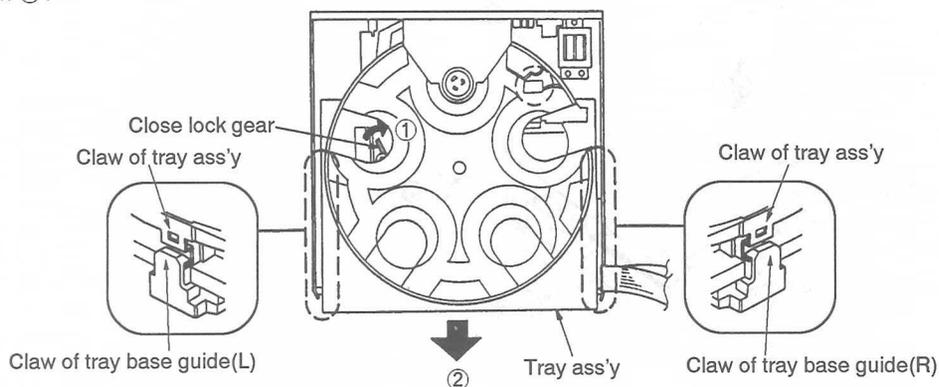


## 3. Checking for the main P.C.B.

**Step 1** Perform the **Step 1** ~ **Step 4** in item 2 on page 10.

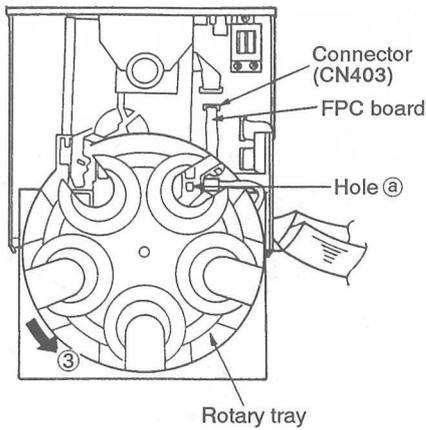
**Step 2** Keep the close lock gear pressed in the direction of arrow ①, and move the tray ass'y in the direction of arrow ②.

**Step 3** Fit the claw of tray ass'y in the claw of tray base guide(L) and tray base guide(R).



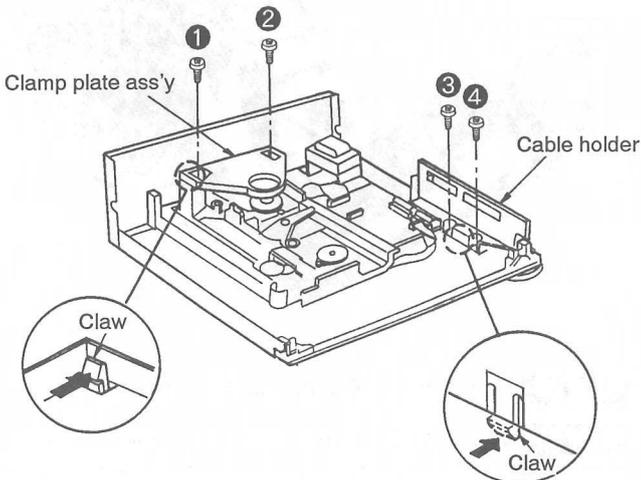
**Step 4** Pull out the FPC board from connector.

**Step 5** Rotate the rotary tray to the position that can be confirmed the hole ③ in the direction of arrow ③.

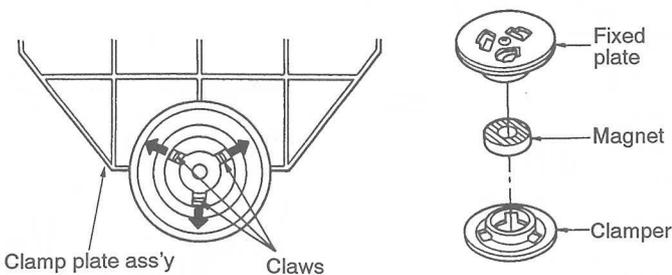


**Step 7** Remove the 2 screws and claw, and then remove the clamp plate ass'y.

**Step 8** Remove the 2 screws and claw, and then remove the cable holder.

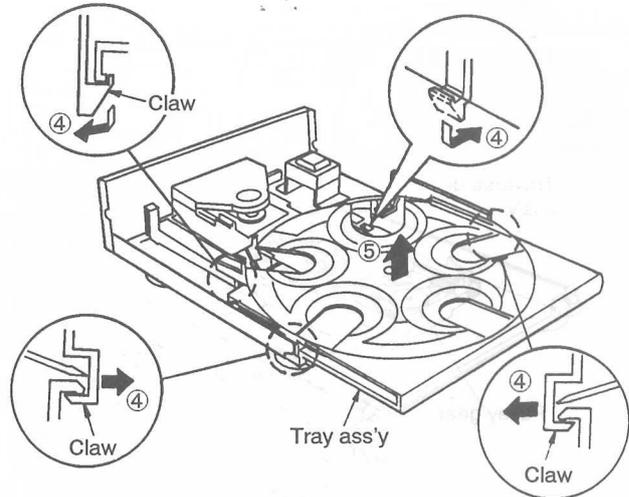


**Step 10** Release the 3 claws, and then remove the fixed plate, magnet and clamper.

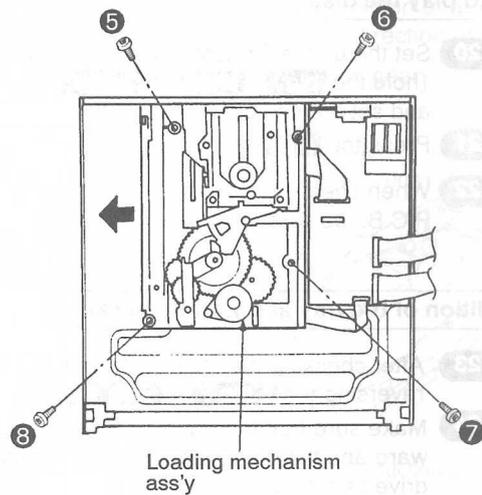


1, 2 [XTB3+10JFZ] (Black)	11 ~ 13 [XTB3+20J]
3 ~ 10 [XTB3+8JFZ] (Black)	14, 15 [XTBS3+8JFZ1] (Black)

**Step 6** Push and release the 4 claws in the direction of arrow ④, and then remove the tray ass'y in the direction of arrow ⑤.



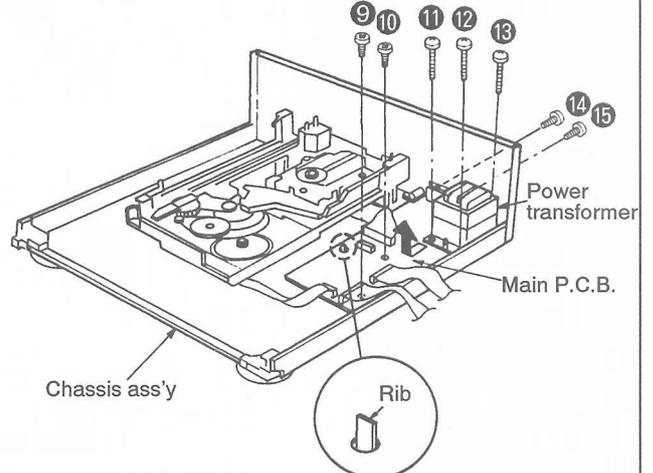
**Step 9** Remove the 4 screws, and then move the mechanism ass'y in the direction of arrow.



**Step 11** Remove the 7 screws.

**Step 12** Remove the power transformer.

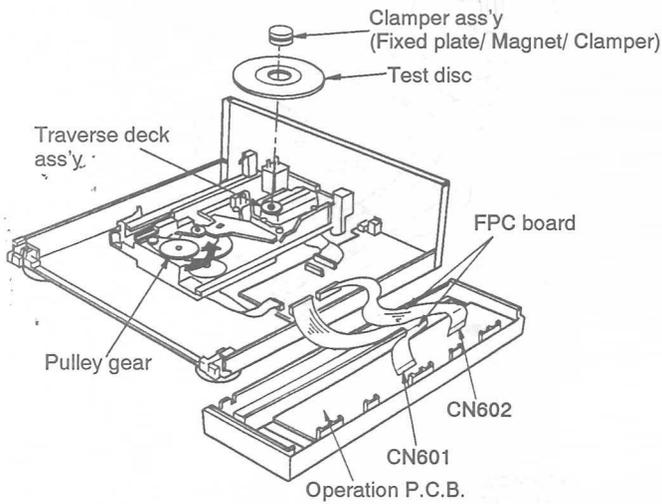
**Step 13** Lift up the main P.C.B. to release the rib of chassis ass'y, and then remove the main P.C.B. in the direction of arrow.



**Step 14** Rotate the pulley gear in the direction of arrow until traverse deck ass'y comes up.

**Step 15** Place the test disc and secure it by using the clamber ass'y.

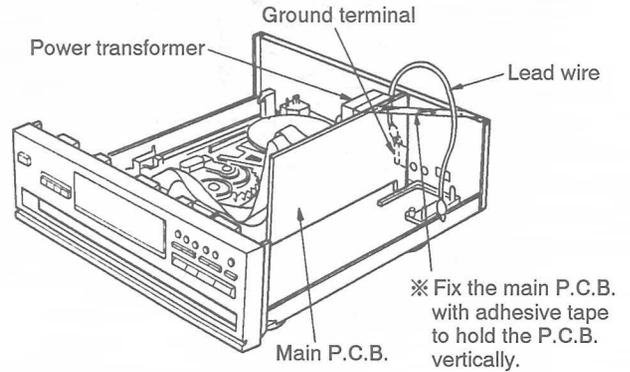
**Step 16** Connect the 2 FPC board.



**Step 17** Set up the main P.C.B.

**Step 18** Connect the main P.C.B. ground terminal (line out terminal) to the chassis ass'y with a lead wire.

**Step 19** Install the power transformer on the main P.C.B.

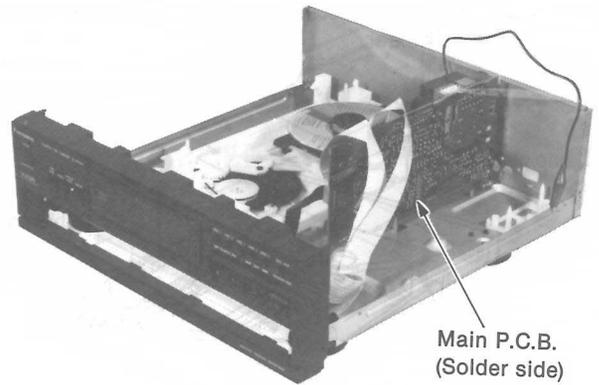


**How to play the disc**

**Step 20** Set the unit in the test mode as follows: (hold the **play**, **stop** and **disc 1** keys(3 keys) on and set the power switch to ON.)

**Step 21** Press the **play** key and play the test disc.

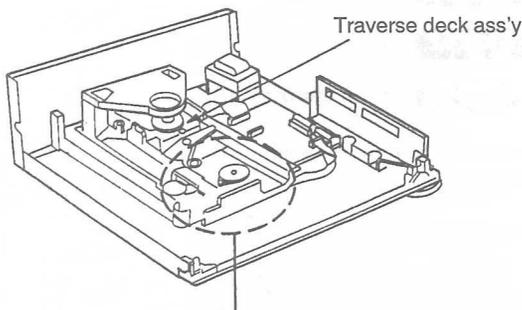
**Step 22** When checking the soldered surface of the main P.C.B., do as shown right.



**Installation of the tray ass'y after checking**

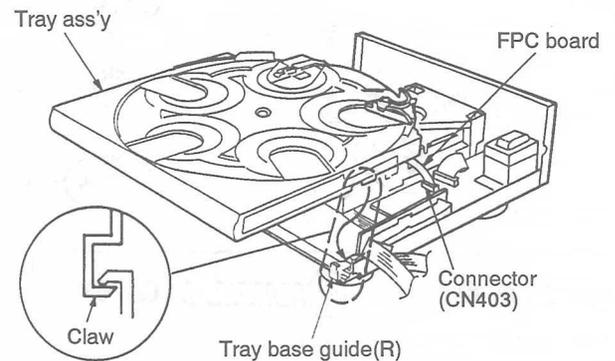
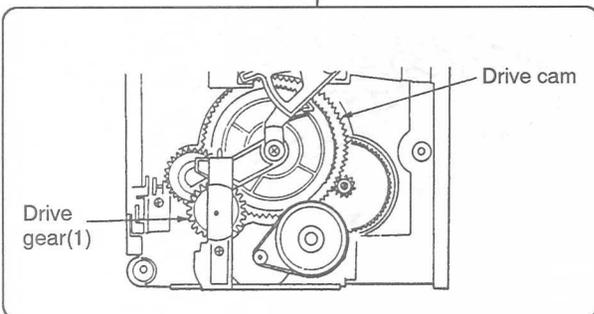
**Step 23** After checking the main P.C.B., reassemble by reversing the **Step 7** ~ **Step 19**.

**Step 24** Make sure that the traverse deck ass'y, falls down ward and the drive gear(1) is not engaged to the drive cam gear.



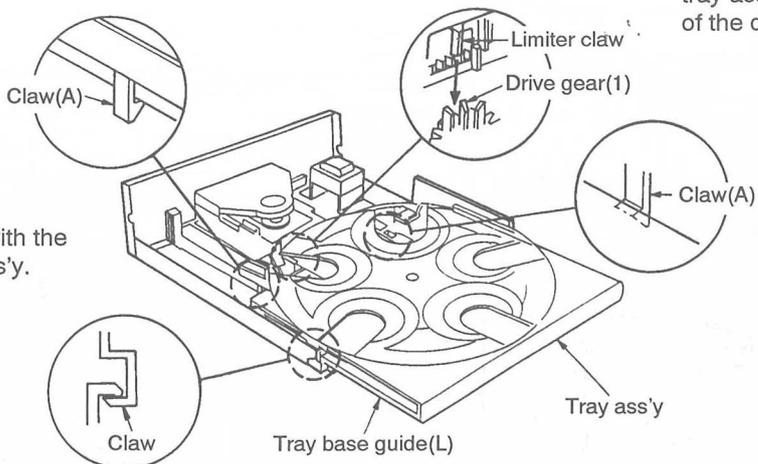
**Step 25** Attach the FPC board to the connector.

**Step 26** Fit the claws on the right side of the tray ass'y underneath the claws on the tray base guide(R).



**Step 27** Fit the claws on the right side of the tray ass'y underneath the claws on the tray base guide(L).

**Step 28** Fit the limiter claw on the tray ass'y between the teeth of the drive gear(1).



**Step 29** Catch the 2 claws(A) with the loading mechanism ass'y.

**Step 30** After installing the tray ass'y, check that it moves smoothly.

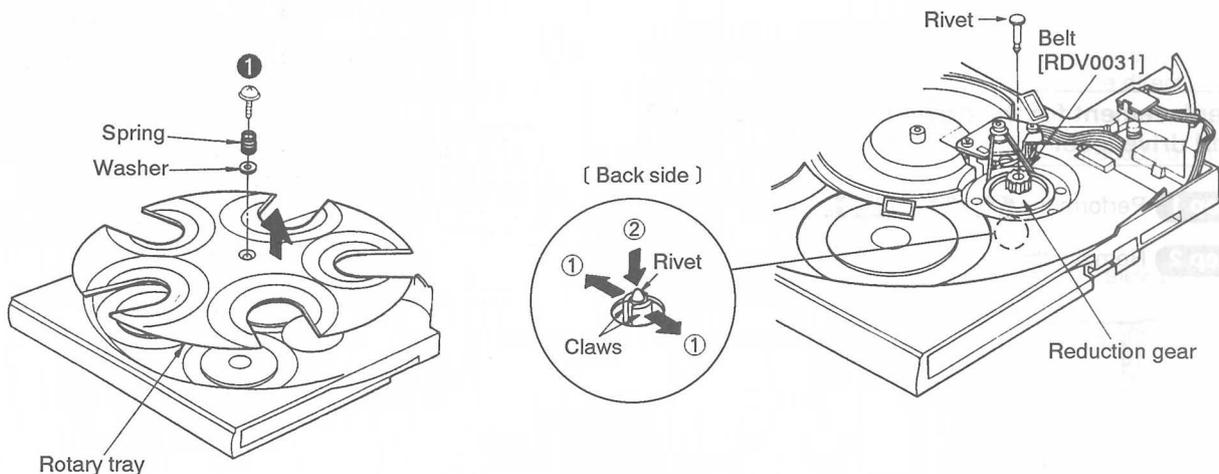
#### 4. Replacement for the belt and tray motor ass'y

**Step 3** Release the 2 claws in the direction of arrow ①, and then push the rivet in the direction of arrow ②.

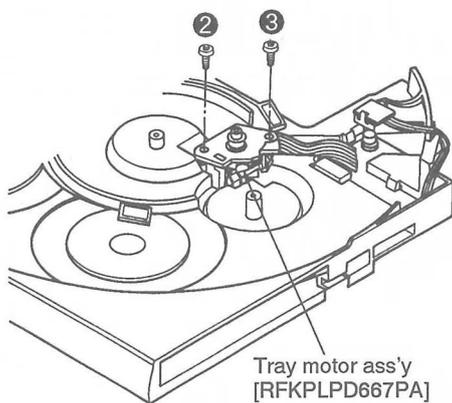
**Step 4** Remove the belt and reduction gear.

**Step 1** Perform the **Step 1** ~ **Step 6** in item 3 on page 10,11.

**Step 2** Remove the 1 screw and then remove the rotary tray.

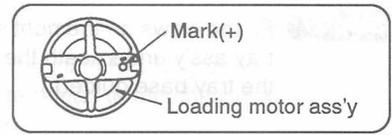
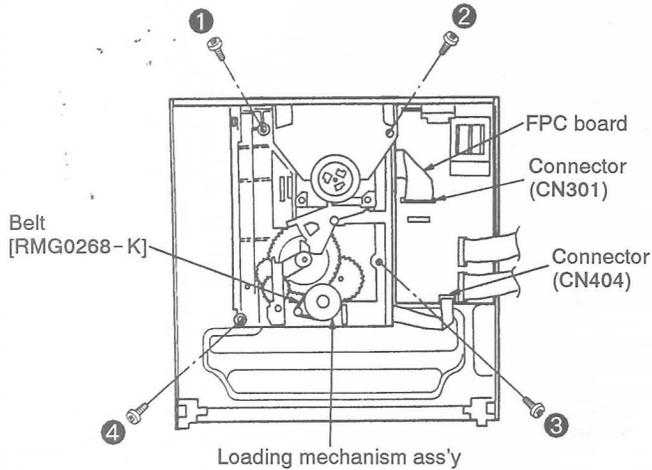


**Step 6** Remove the 2 screws.

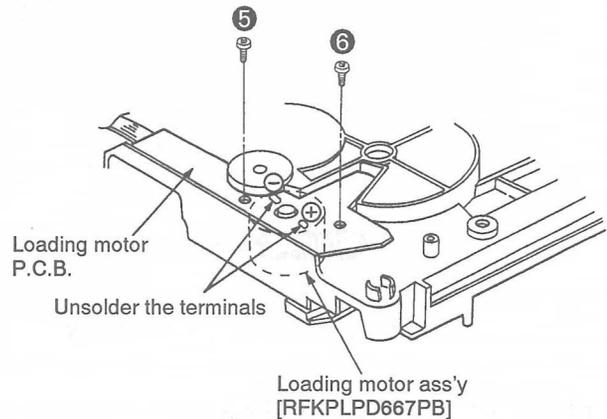


### 5. Replacement for the belt and loading motor ass'y

- Step 1** Perform the **Step 1 ~ Step 6** in item 3 on page 10,11.
- Step 2** Remove the belt.
- Step 3** Remove the 4 screws and connector.

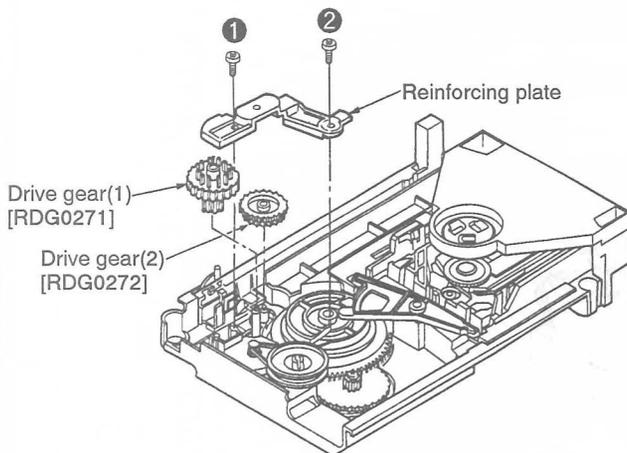


- Step 4** Unsolder the terminals of the loading motor ass'y.
- Step 5** Remove the 2 screws and then remove the loading motor P.C.B. and loading motor ass'y.

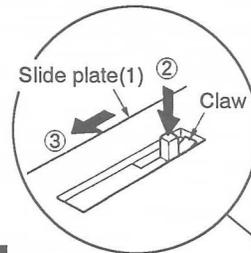


### 6. Replacement for the drive gear(1), drive gear(2) and drive lever

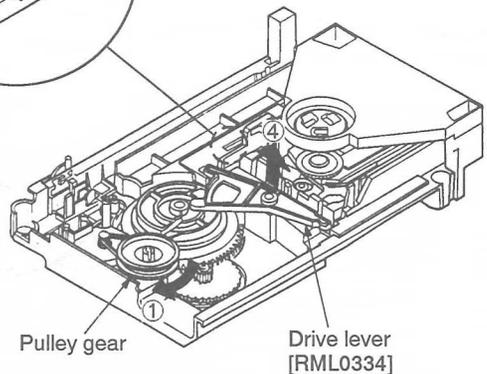
- Step 1** Perform the **Step 1 ~ Step 6** in item 3 on page 10,11.
- Step 2** Remove the 2 screws.



- Step 3** Rotate the pulley gear to full position in the direction of arrow ①.
- Step 4** Push the claw in the direction of arrow ②, and then move the slide plate(1) in the direction of arrow ③.
- Step 5** Remove the drive lever in the direction of arrow ④.



**NOTE**  
Be careful not to damage the claw because the claw is breakable.

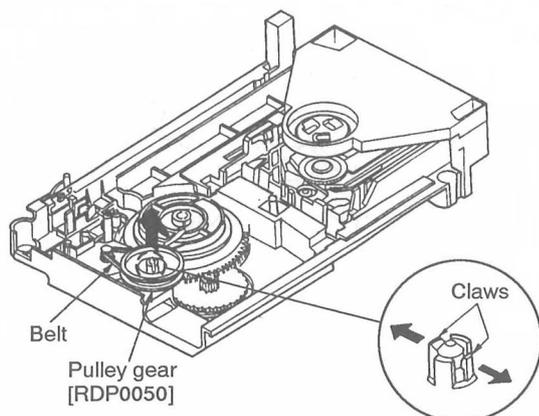


## 7. Replacement for the pulley gear, drive cam and reduction gear

**Step 1** Perform the **Step 1** ~ **Step 5** in item 6 on page 14.

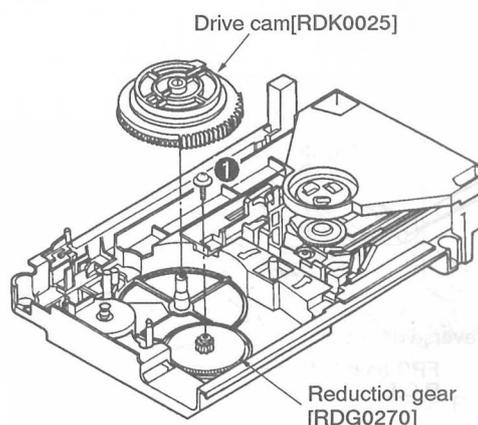
**Step 2** Remove the belt.

**Step 3** Release the 2 claws, and then the remove the pulley gear.



**Step 4** Remove the drive cam .

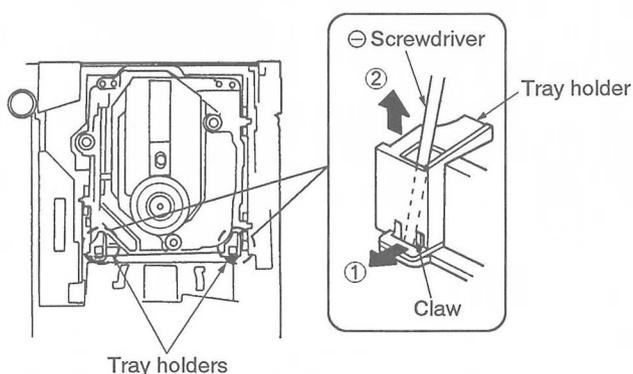
**Step 5** Remove the 1 screw and reduction gear.



## 8. Checking for the servo P.C.B.

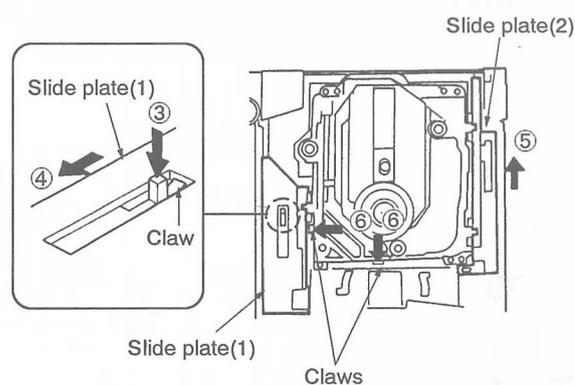
**Step 1** Perform the **Step 1** ~ **Step 10** in item 3 (on page 10,11) and item 6(on page 14) .

**Step 2** While pushing the claw of tray holders in the direction of arrow ① using the ⊖ screwdriver, remove the tray holder in the direction of arrow ② .

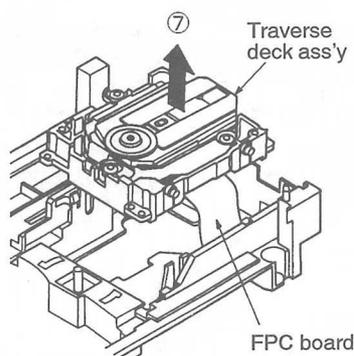


**Step 3** Push the claw in the direction of arrow ③ , and then move the slide plate(1) in the direction of arrow ④ .

**Step 4** Move the slide plate(2) in the direction of arrow ⑤ .



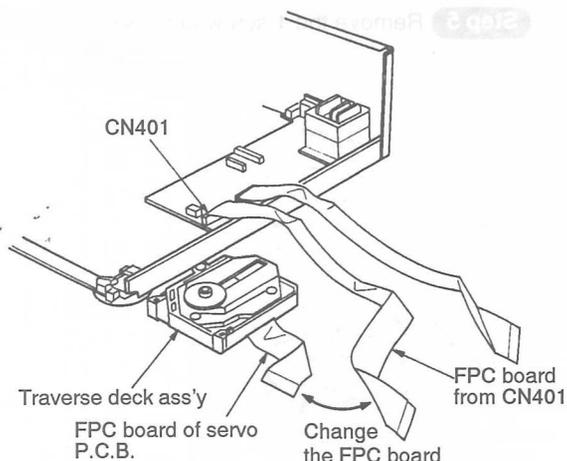
**Step 5** Release the 2 claws in the direction of arrow ⑥ , and then remove the traverse deck ass'y in the direction of arrow ⑦ .



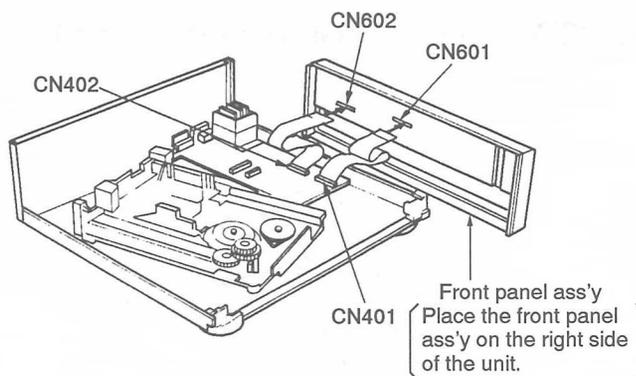
### NOTE

Be careful not to scratch or bend the FPC board.

**Step 6** Replace the FPC board of servo P.C.B. to the FPC board(CN401) of main P.C.B.



**Step 7** Connect the FPC boards as shown in above.  
 ( Between CN401 and CN601 )  
 ( Between CN402 and CN602 )



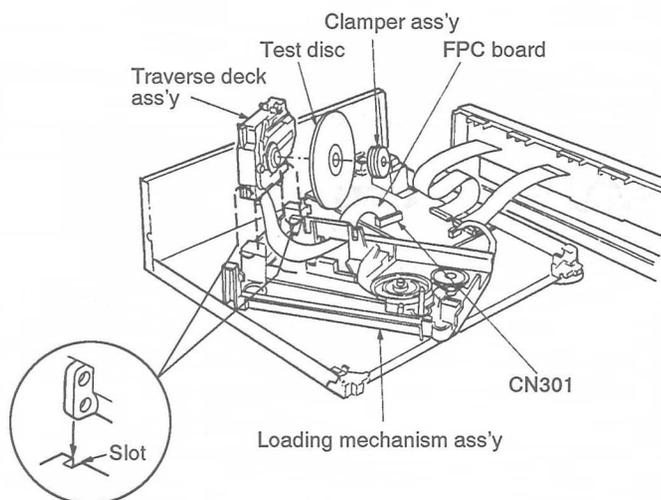
**Step 8** Insert the traverse deck in the slot of loading mechanism ass'y.

**Step 9** Connect the FPC board of servo P.C.B. to the connector(CN301) of main P.C.B.

**Step 10** Set the test disc on the traverse deck ass'y, and then fix the traverse deck ass'y with clamper ass'y.

**NOTE**

After completing the check, restore the replaced FPC boards to their original positions.

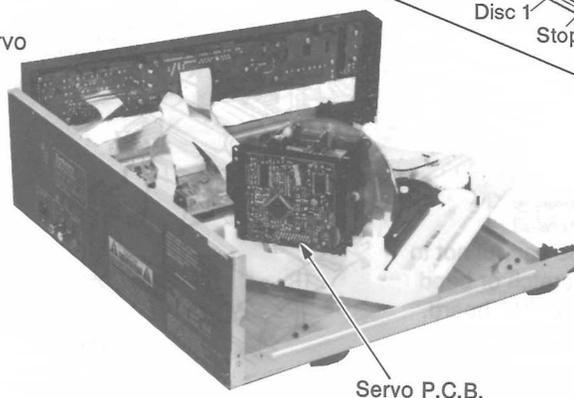
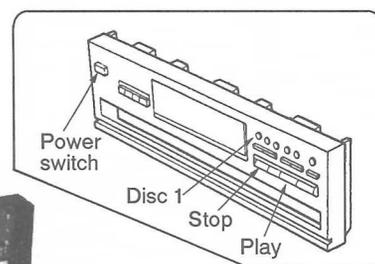


**How to play the disc**

**Step 11** Set the unit in the test mode as follows:  
 (hold the **play**, **stop** and **disc 1** keys(3 keys)  
 on and set the power switch to ON.)

**Step 12** Press the **play** key and play the test disc.

**Step 13** When checking the soldered surface of the servo P.C.B., do as shown right.

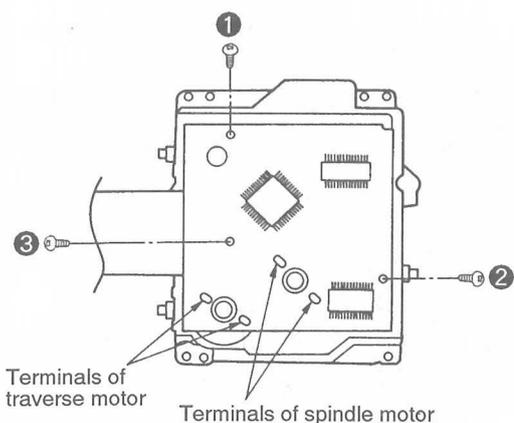


## 9. Replacement for the traverse deck ass'y

**Step 1** Perform the **Step 1** ~ **Step 5** in item 8 on page 15.

**Step 2** Remove the 3 screws.

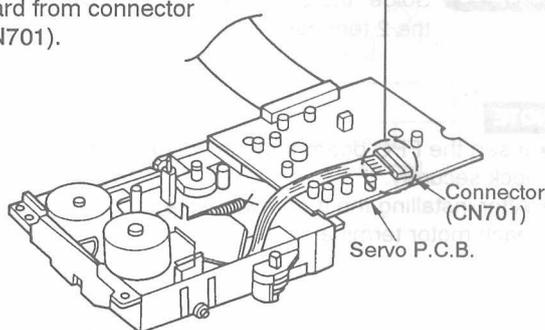
**Step 3** Unsolder the traverse motor and spindle motor terminals.



1. Push the top of the connector in the direction of arrow ①.
2. Remove the FPC board in the direction of arrow ②.

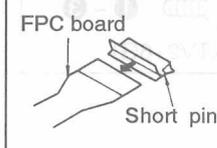


**Step 4** Remove the FPC board from connector (CN701).

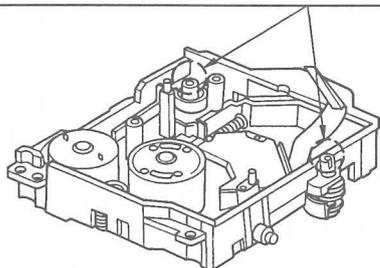
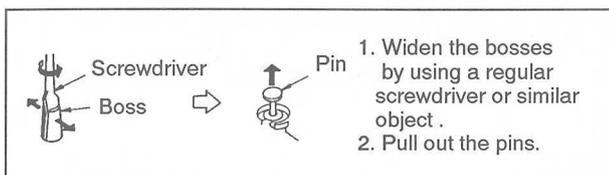


**NOTE**

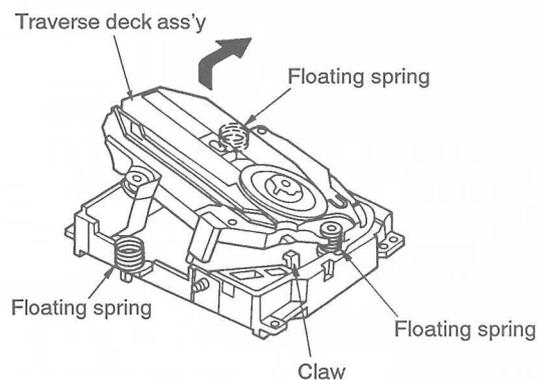
Insert a short pin into the traverse unit FPC board.  
(Refer to "handling precautions for traverse deck" on page 8.)



**Step 5** Remove the 2 pins.



**Step 6** Release the claw, and then remove the traverse deck ass'y in the direction of arrow.



**NOTE**

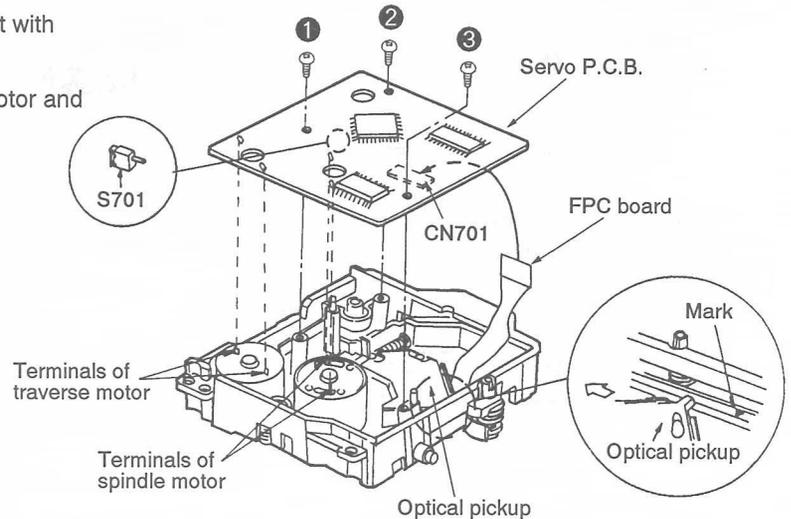
Be careful not to lose the 3 floating springs because those will also be removed on removal of the traverse deck ass'y.

### Installation of servo P.C.B. after replacement

- Step 7** When installing servo P.C.B., move the optical pickup to the more external side than the mark (▲).  
(When the optical pickup is not moved, the switch (S701) on the servo P.C.B. may be broken.)
- Step 8** Connect the FPC board to the connector(CN701).
- Step 9** Install the servo P.C.B. to the traverse unit with 3 screws.
- Step 10** Solder the 2 terminals of the traverse motor and the 2 terminals of the spindle motor.

#### NOTE

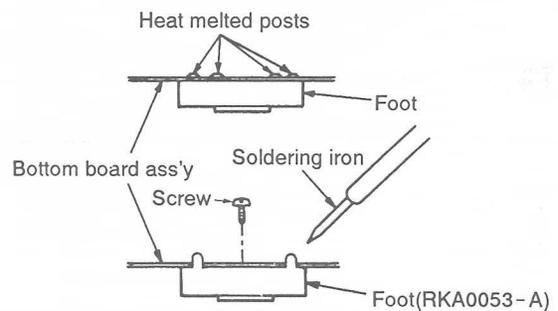
- Insert the FPC board into the connector and lock securely.
- After installing the motor with screws, solder each motor terminal.



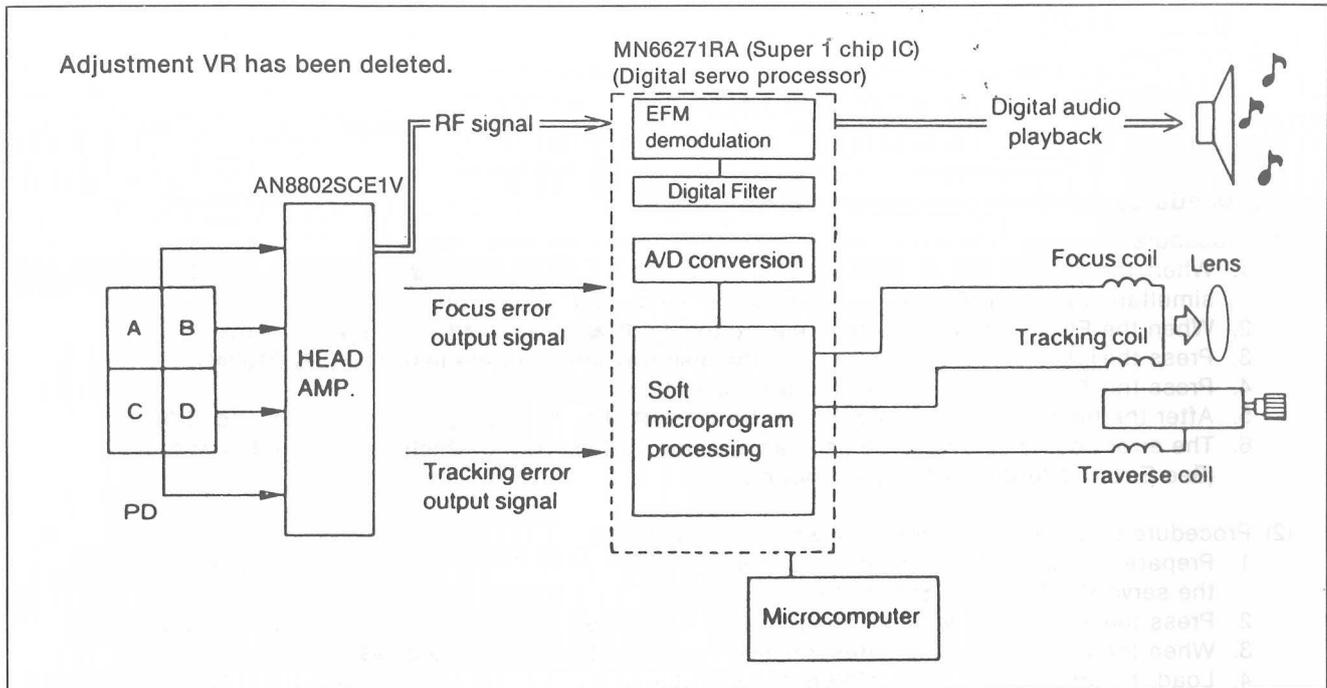
[XTV2+6G]

## REPLACEMENT OF THE FOOT

1. Remove the 4 heat melted posts on the Bottom board ass'y with a pair of nippers or similar tool.
2. To replace the foot (RKA0053-K) on the Bottom board ass'y melt the 4 posts with a soldering iron or install it with a screw (XTB3+6J).

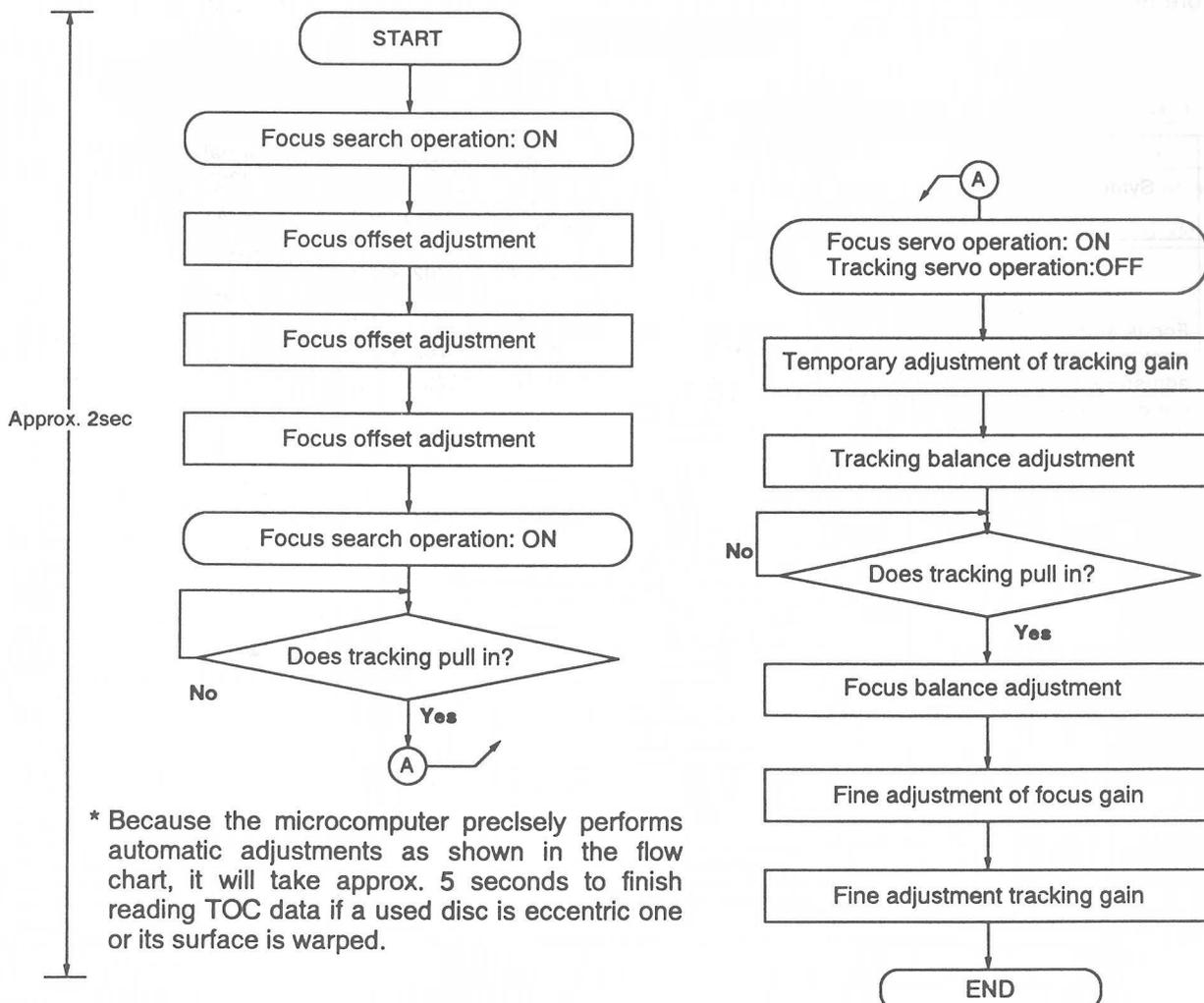


## DIGITAL SERVO SYSTEM



The following flow chart shows the sequence of automatic adjustments.

### ● Flow chart automatic adjustment sequence



## ■ DISPLAY FUNCTION OF AUTOMATICALLY-ADJUSTED RESULTS (SELF-CHECK FUNCTION)

The unit contains a function which displays the result of the automatically adjustment of the servo circuits (tracking, focus servo, etc.) as an error code on the FL display.

The error code display serves as a repair guide showing the automatically adjustment circuit is at fault. The procedures for displaying the error codes are given below.

### • Procedures to display the error code

#### (1) Procedure to display the error code before disassembly (finished unit)

1. When the **POWER** key is pressed while holding down the **STOP (■)**, **PAUSE (■)** and **PLAY (▷)** keys simultaneously, the FL display illuminates, release the power turns on.
2. When the FL display illuminates, release the **STOP (■)**, **PAUSE (■)** and **PLAY (▷)** keys.
3. Press the **OPEN/CLOSE (△)** key to open the disc tray and load the test disc (SZZP1054C).
4. Press the **PLAY (▷)** key to start the play operation.
5. After the time display appears, press the **STOP (■)** key to display the error code. (e.g. E-0)
6. The error code display can be used as a repair guide showing which servo circuit is at fault. (See Error Code Based Troubleshooting.)

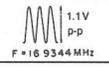
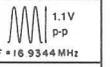
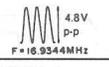
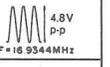
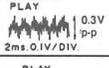
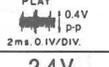
#### (2) Procedure to display the error code when disassembled

1. Prepare the unit as described in "Checking for the main P.C.B." on pages 10~13 and "Checking for the servo P.C.B." on pages 15, 16.
2. Press the **POWER** key while holding down the **STOP (■)**, **PLAY (▷)** and **DISC 1** keys simultaneously.
3. When the FL display illuminates, release the **STOP (■)**, **PLAY (▷)** and **DISC 1** keys.
4. Load the test disc (SZZP1054C) on the turntable and secure it with the clamper ass'y.
5. Perform steps 4 and 5 in section (1) above.

### • Error code based troubleshooting

※ The unit is satisfactory if the error code is E-0 of E-2.

※ Before testing, check that the test disc is free of scratches and dirt and optical pickup is clean.

FL error code display	Symptom	Probable cause	Signal to check		Normal the values of voltage and waveform	
			Signal name	Location	PLAY	STOP
E-1	Focus and tracking offset adjustments did not complete in the specified time period.	① Clocks X1 and X2, power supply VDD, and reset/RST, all on IC702 ② MDATA, MCLK, MLD, and SENSE signals to/from the mechanism controller	MDATA	IC702 ⑧ pin		4.8V
			MCLK	IC702 ⑦ pin		4.8V
			MLD	IC702 ⑨ pin		0V
			SENSE	IC702 ⑩ pin	0V	0V
			/RST	IC702 ⑱ pin	4.9V	4.9V
			X1	IC702 ⑤⑨ pin		
X2	IC702 ⑤⑨ pin					
E-3 E-5 E-7 E-9 E-B E-D E-F	Disc play unstable	① Scratches or contaminants on disc surface ② Focus and tracking servo circuits (check waveforms, voltages, and part constants.) ③ Spindle driver circuit ④ Optical pickup	FE	IC702 ⑳ pin		2.4V
			TE	IC702 ⑲ pin		2.4V
			FOD	IC702 ⑳ pin	2.4V	2.4V
			TRD	IC702 ⑳ pin	2.4V	2.4V
			KICK	IC702 ⑳ pin	2.4V	2.4V
			/FLOCK	IC702 ⑰ pin	0V	4.9V
			/RF DET	IC702 ⑲ pin	0V	4.8V
			RF	TJ701		3.4V
			STAT	IC702 ⑰ pin	3.5V	0V

FL error code display	Symptom	Probable cause	Signal to check		Normal the values of voltage and waveform	
			Signal name	Location	PLAY	STOP
E-4 E-6 E-C E-E	Best Eye (PD Balance) adjustment diode not complete in the specified time period.	① Scratches or contaminants on disc surface ② Focus and Tracking servo circuit (check waveforms, voltages, and part constants.) ③ Optical pickup	FBAL	IC702 ② pin	2.5 ± 1.25V	2.5 ± 1.25V
			RF	TJ701		3.4V
			FE	IC702 ③ pin		0V
			/TLOCK	IC702 ⑫ pin	0V	0V
			OFT	IC702 ⑮ pin	0V	0V
E-8 E-A	Focus or Tracking gain adjustment did not complete in the specified time period.	① Scratches or contaminants on disc surface ② Focus and Tracking servo circuit (check waveforms, voltages, and part constants.) ③ Optical pickup	FE	IC702 ③ pin		2.4V
			TE	IC702 ⑬ pin		2.4V
			/TLOCK	IC702 ⑫ pin	0V	0V
			OFT	IC702 ⑮ pin	0V	0V

## MEASUREMENTS AND ADJUSTMENTS

**Warning:** This product uses a laser diode. Refer to caution statements on page 2.

### Measuring Instruments and Special Tools

- \* Test discs
  1. Playability test disc (SZZP1054C)
  2. Uneven test disc (SZZP1056C)
- \* Musical program disc (ordinary)
- \* Dual-beam oscilloscope with bandwidth of 30MHz or better (with EXT. trigger and 1:1 probe).
- \* Allen wrench (M2.0) (SZZP1101C)
- \* Lock paint (RZZ0L01)

### PREPARATION

1. Remove the cabinet and front panel ass'y (refer to "operation checks and main component replacement procedures" Item No. 1, 2 [step 1~4]).
2. Set the power switch to ON and press the open/close key to close the loading drawer.
3. Press the play key and when the traverse deck reaches it's height position, set the power switch to OFF.
4. Remove the tray ass'y (refer to "operation checks and main component replacement procedures" Item No. 3 [step 1~6]).
5. Remove the clamp plate, fixed plate, magnet and clamber (refer to "operation checks and main component replacement procedures" Item No. 3 [step 1~8, 10]).
6. Place the test disc and secure it by using clamber ass'y. (Refer to Fig. 1) (refer to "operation checks and main component replacement procedures" Item No. 3 [step 10]).
7. Set the unit in the test mode as follows: (hold the **play**, **stop** and **disc 1** keys (3 keys) on and set the power switch to ON.)
8. Press the **play** key and play the test disc.
9. Follow the adjustment procedure.

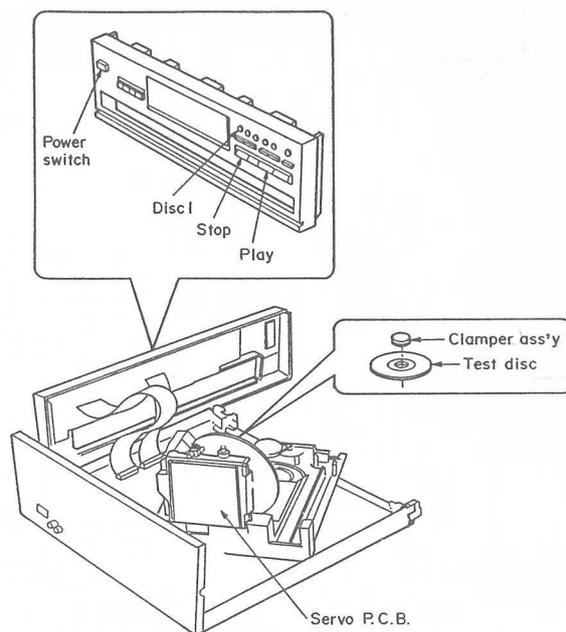
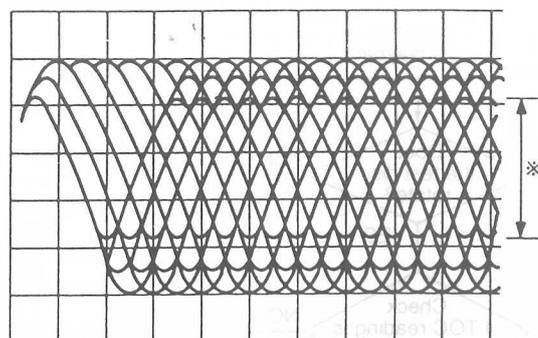


Fig. 1

**(1) MECHANICAL ADJUSTMENT**

1. Connect the oscilloscope's CH. 1 probe across **TJ701** (RF) and **TJ702** (VREF) on the servo P.C.B. (Refer to Fig. 3)  
**Oscilloscope setting:** VOLT ..... 200mV  
 SWEEP ..... 0.5 $\mu$ s.  
 Input coupling..... AC
2. Switch the player power **ON**, and play track **19** on the test disc (SZZP1056C). (Playing any other track will prevent the HEX screws from being accessed.)
3. Leave the player in play mode and place it as shown Fig. 3.
4. Alternately adjust the two HEX screws with the 2.0mm allen wrench (SZZP1101C) until the vertical fluctuation of RF signal is minimized and the eye pattern is most stretched. (Refer to Fig. 2)
5. After completing the adjustment, lock the HEX screws with lock paint (RZZ0L01).



\* Most stretched eye pattern.

Fig. 2

**(2) CHECK OF PLAY OPERATION AFTER ADJUSTMENT**

\* **Checking Skip Search**

1. Play an ordinary musical program disc.
2. Press the skip button to check for normal skip search operation (in both the forward and reverse directions).

\* **Checking Manual Search**

1. Play an ordinary musical program disc.
2. Press the manual search button to check for smooth manual search operations at either low or high speed (in both the forward and reverse directions).

\* **Checking Playability**

1. Play the 0.7mm black dot and the 0.7mm wedge on the playability test disc (SZZP1054C) and verify that no sound skip or noise occurs.
2. Play the middle tracks of the uneven test disc (SZZP1056C) and verify that no sound skip or noise occurs.

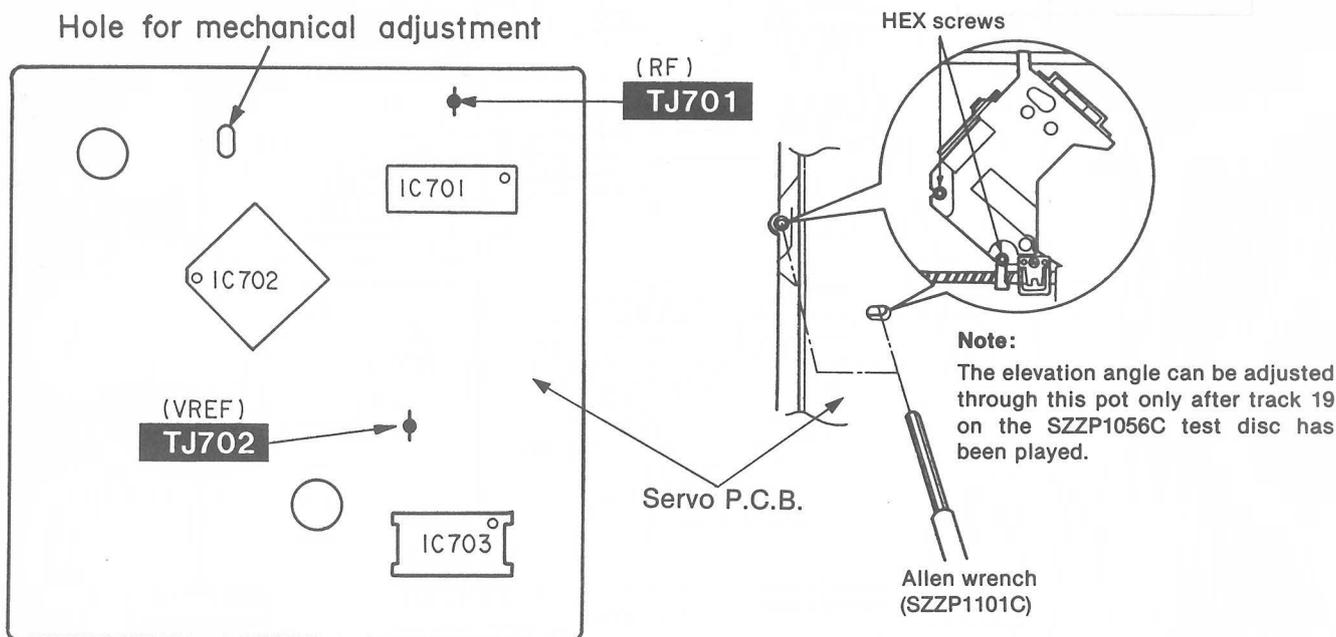
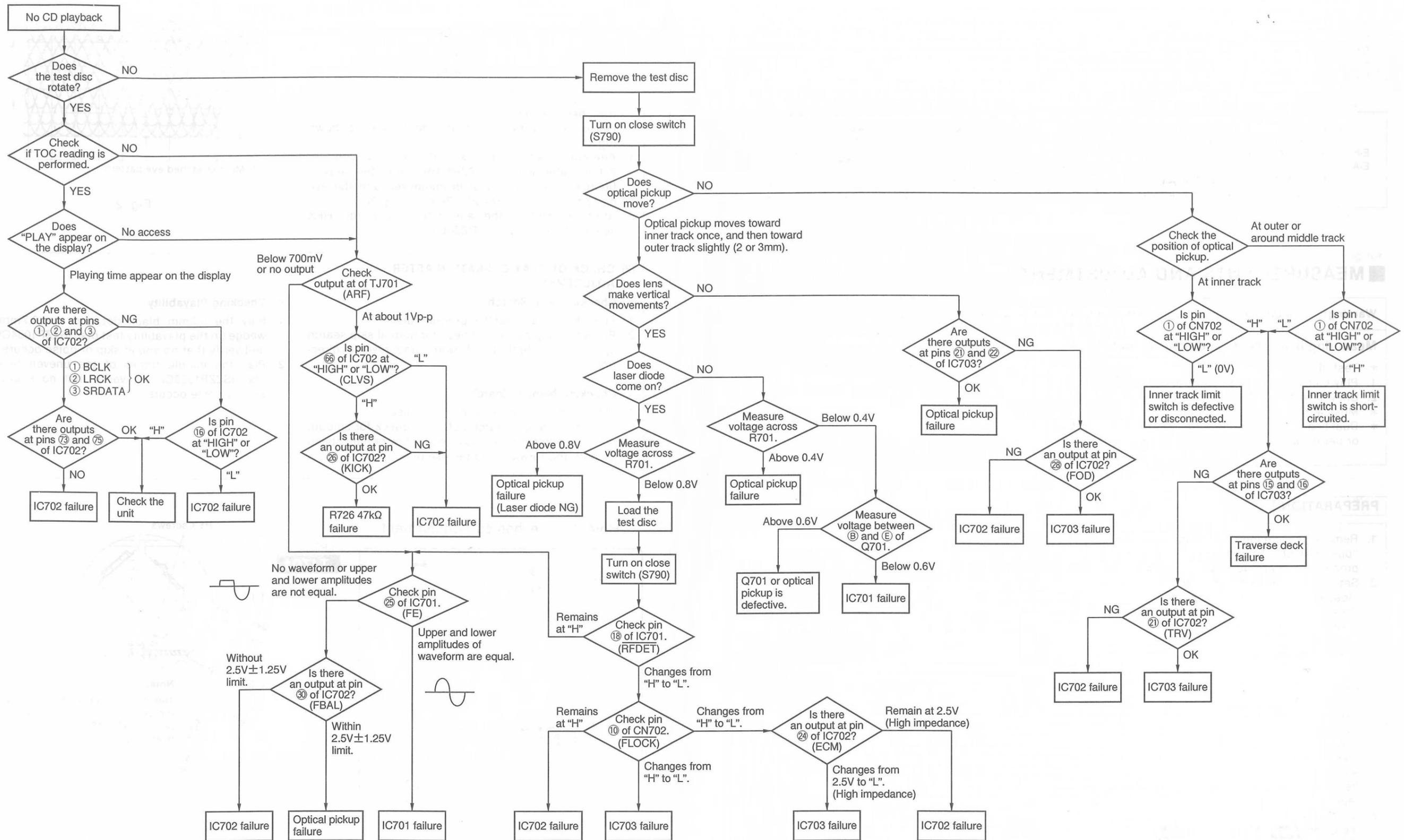


Fig. 3

■ TROUBLESHOOTING GUIDE



## ■ TERMINAL FUNCTION OF IC'S

### • IC701 (AN8802SCE1V): Servo amp

Pin No.	Mark	I/O Division	Function
1	PDAD	I	Photo detector Bch input without delay
2	PDA	I	Photo detector Ach input without delay
3	LPD	I	Laser PD signal
4	LD	O	Laser power auto control output
5	AMPI	I	RF amp terminal
6	V <sub>CC</sub>	I	Power supply terminal
7	AMPO	O	RF amp signal
8	CAGC	I	AGC detection capacitor input
9	ARF	O	RF signal
10	CENV	I	RF detect capacitor connection terminal
11	CEA	I	HPF-AMP capacitor connection terminal
12	GND	—	GND terminal
13	LDON	I	LD APC ON/OFF ("H": ON, "L": OFF)
14	TES	I	Tracking error shunt input ("H": shunt)
15	PLAY	I	Play signal ("H": ON, "L": OFF)
16	WVEL	I	Double velocity ("H": double, "L": single)

Pin No.	Mark	I/O Division	Function
17	BDO	O	Dropout detection control
18	/RFDET	O	RF det. signal ("L": det.)
19	CROSS	O	Tracking error zero cross output
20	OFTR	O	Off track detection ("H": det.)
21	VDET	O	Oscillation det. signal ("H": det.)
22	ENV	O	Envelope output terminal
23	TEBPF	I	Oscillation detect input terminal (Not used, open)
24	TE	O	Tracking error signal
25	FE	O	Focusing error signal
26	PTO	O	Potention amp output
27	PTI	I	Potention amp input
28	TBAL	I	Tracking balance adj. input
29	FBAL	I	Focus balance adj. input
30	VREF	O	Reference voltage output
31	PDB	I	Photo detector Ach input with delay
32	PDBD	I	Photo detector Bch input with delay

### • IC703 (AN8389SE1): Focus coil/tracking coil/traverse motor/spindle motor

Pin No.	Mark	I/O Division	Function
1	V <sub>CC</sub>	I	Power supply terminal
2	VREF	I	Reference voltage input
3	IN4	I	Motor driver (4) input
4	IN3	I	Motor driver (3) input
5	GND	—	GND terminal
6	NC	—	No used, connected to GND
7	NRESET	O	Reset terminal
8	GND	—	GND terminal
9	IN2	I	Motor driver (2) input
10	PC2	I	PC2 (power cut) input
11	IN1	I	Motor driver (1) input
12	PC1	I	PC1 (power cut) input (Not used, open)

Pin No.	Mark	I/O Division	Function
13	PV <sub>CC1</sub>	I	Driver power supply (1)
14	PGND1	—	Driver GND terminal (1)
15	D1-	O	Motor driver (1) output terminal (-)
16	D1+	O	Motor driver (1) output terminal (+)
17	D2-	O	Motor driver (2) output terminal (-)
18	D2+	O	Motor driver (2) output terminal (+)
19	D3-	O	Motor driver (3) output terminal (-)
20	D3+	O	Motor driver (3) output terminal (+)
21	D4-	O	Motor driver (4) output terminal (-)
22	D4+	O	Motor driver (4) output terminal (+)
23	PGND2	—	Driver GND terminal (2)
24	PV <sub>CC2</sub>	I	Driver power supply (2)

• IC702 (MN66271RA): Servo processor/digital signal processor/digital filter/D/A converter

Pin No.	Mark	I/O Division	Function
1	BCLK	O	Serial bit clock terminal
2	LRCK	O	L/R discriminating signal
3	SRDATA	O	Serial data (Not used, open)
4	DV <sub>DD1</sub>	I	Power supply (digital circuit) terminal
5	DV <sub>SS1</sub>	—	GND (digital circuit) terminal
6	TX	O	Digital audio interface signal
7	MCLK	I	Command clock signal
8	MDATA	I	Command data signal
9	MLD	I	Command load signal ("L": LOAD)
10	SENSE	O	Sense signal (OFT, FESL, NACEND, NAJEND, POSAD, SFG)
11	/FLOCK	O	Optical servo condition (focus) ("L": lead-in)
12	/TLOCK	O	Optical servo condition (tracking) ("L": lead-in)
13	BLKCK	O	Sub-code block clock (f=75 Hz) (Not used, open)
14	SQCK	I	Sub-code Q register clock
15	SUBQ	O	Sub-code Q data
16	DMUTE	I	Muting input ("H": MUTE) (Not used, connected to GND)
17	STAT	O	Status signal (CRC, CUE, CLVS, TTSTOP, FCLV, SQCK)
18	/RST	I	Reset signal ("L": reset)
19	SMCK	O	System clock (f=4.2336 MHz) (Not used, open)
20	PMCK	O	Frequency division clock signal (Not used, open) ( $f = \frac{1}{1.92} \times ck = 88.2 \text{ kHz}$ )
21	TRV	O	Traverse servo control

Pin No.	Mark	I/O Division	Function
22	TVD	O	Traverse drive signal
23	PC	O	Turntable motor drive signal ("L": ON)
24	ECM	O	Turntable motor drive signal (Forced mode)
25	ECS	O	Turntable motor drive signal (Servo error signal)
26	KICK	O	Kick pulse output
27	TRD	O	Tracking drive signal output
28	FOD	O	Focus drive signal output
29	VREF	I	D/A drive output (TVD, ECS, TRD, FOD, FBAL, TBAL) normal voltage input terminal
30	FBAL	O	Focus balance adj. output (Not used, open)
31	TBAL	O	Tracking balance adj. output
32	FE	I	Focus error signal (analog input)
33	TE	I	Tracking error signal (analog input)
34	RFENV	I	RF envelope signal
35	VDET	I	Oscillation det. signal ("H": det.)
36	OFT	I	Off track signal ("H": Off track)
37	TRCRS	I	Track cross signal input
38	/RFDET	I	RF detection signal ("L": detection)
39	BDO	I	Dropout detection signal ("H": dropout)
40	LDON	O	Laser power control ("H": ON)
41	TES	O	Tracking error shunt output ("H": dropout)
42	PLAY	O	Play signal ("H": play)

Pin No.	Mark	I/O Division	Function
43	WVEL	O	Double velocity status signal ("H": double)
44	ARF	I	RF signal input
45	IREF	I	Reference current input
46	DRF	I	DSL bias terminal (Not used, open)
47	DSLFL	I/O	DSL loop filter terminal
48	PLLF	I/O	PLL loop filter terminal
49	VCOF	I/O	VCO loop filter terminal (Not used, open)
50	AV <sub>DD2</sub>	I	Power supply (analog circuit) terminal (2)
51	AV <sub>SS2</sub>	—	GND (analog circuit) terminal
52	EFM	O	EFM signal (Not used, open)
53	PCK	O	PLL extract clock (f=4.3218MHz)
54	PDO	O	Phase compared signal of EFM and PCK (Not used, open)
55	SUBC	O	Sub-code serial output data (Not used, open)
56	SBCK	I	Sub-code serial output clock (Not used, connected to GND)
57	V <sub>SS</sub>	—	GND terminal
58	X1	I	Crystal oscillator terminal (f=16.9344MHz)
59	X2	O	
60	V <sub>DD</sub>	I	Power supply terminal
61	BYTCK	O	Byte clock signal (Not used, open)
62	/CLDCK	O	Sub-code frame clock signal (f CLDCK=7.35kHz: Normal) (Not used, open)

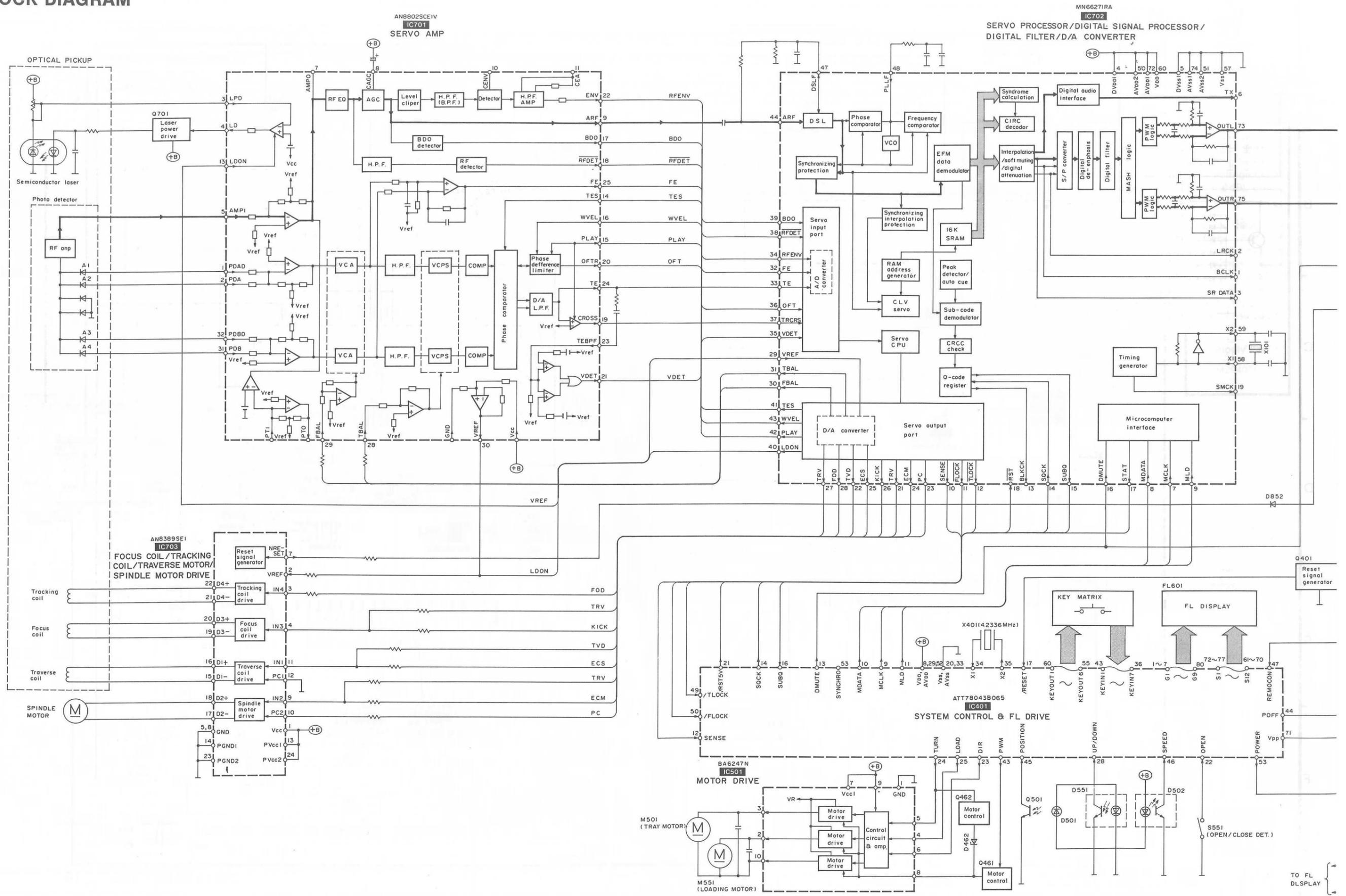
Pin No.	Mark	I/O Division	Function
63	FCLK	O	Crystal frame clock (Not used, open)
64	IPFLAG	O	Interpolation flag terminal
65	FLAG	O	Flag terminal
66	CLVS	O	Turntable servo phase synchro signal ("H": CLV, "L": Rough servo) (Not used, open)
67	CRC	O	Sub-code CRC check terminal ("H": OK, "L": NG)
68	DEMPH	O	De-emphasis ON signal ("H": ON) (Not used, open)
69	RESY	O	Re-synchronizing signal of frame sync. (Not used, open)
70	/RST2	I	Reset terminal after "MASH" circuit
71	/TEST	I	Test terminal (Normal: "H")
72	AV <sub>DD1</sub>	I	Power supply (analog circuit) terminal (1)
73	OUTL	O	Lch audio signal
74	AV <sub>SS1</sub>	—	GND (analog circuit) terminal (1)
75	OUTR	O	Rch audio signal
76	RSEL	I	Polarity direction control terminal of RF signal
77	CSEL	I	Frequency control terminal of crystal oscillator (Not used, connected to GND)
78	PSEL	I	Test terminal (Normal: "L")
79	MSEL	I	"SMCK" terminal frequency select ("L": SMCK=4.2336MHz)
80	SSEL	I	"SUBQ" terminal mode select ("H": Q code buffer)

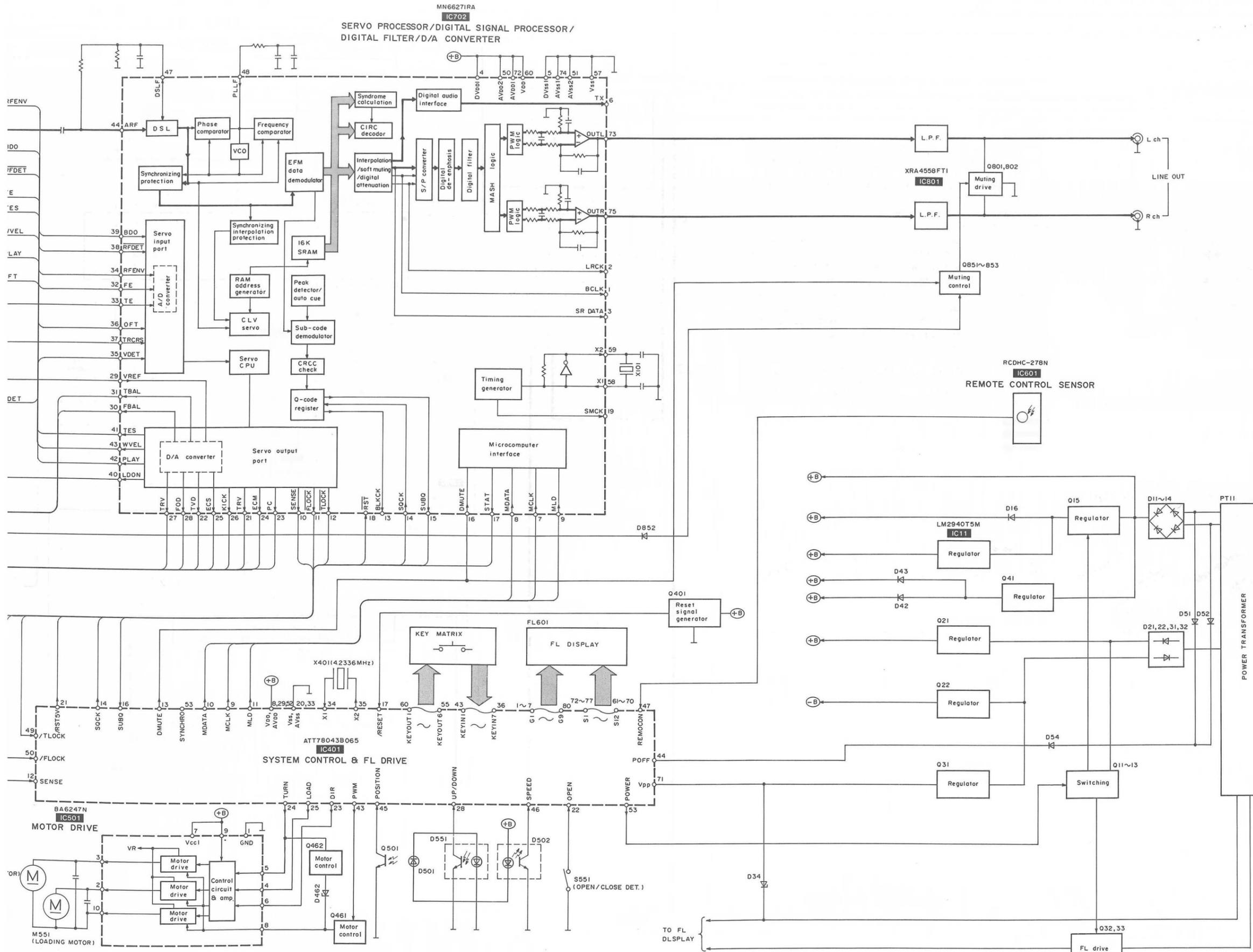
## • IC401 (ATT78043B065): System control &amp; FL drive

Pin No.	Mark	I/O Division	Function
1 └ 7	G7 └ G1	O	Grid signal of FL display
8	VDD	I	Power supply terminal
9	MCLK	O	Command clock signal
10	MDATA	O	Command data signal
11	MLD	O	Command load signal ("L" LOAD)
12	SENSE	I	Sense signal
13	DMUTE	O	Muting control signal
14	SQCK	O	Sub-code Q register clock
15	NC	—	Not connected
16	SUBQ	I	Sub-code Q data
17	/RESET	I	Reset signal input
18	ZSENSE	—	Not used, connected to GND
19	REC. EN	I	Synchro. rec. control terminal
20	AVSS	—	GND terminal
21	/RSTSV	O	Reset signal output
22	OPEN	I	Open detect terminal
23	DIR	O	Motor control signal
24	TRUN	O	
25	LOAD	O	Motor control signal
26	DAC	—	Not used, open
27	RESTSW	I	Rest position de
28	UP/DOWN	I	Traverse deck up/down det. terminal
29	AVDD	I	Power supply terminal
30	AVREF	I	Power supply terminal
31	XT1	—	Not used, connected to GND

Pin No.	Mark	I/O Division	Function
32	XT2	—	Not used, open
33	VSS	—	GND terminal
34	X1	I	Crystal Osc terminal (F: 4.2336MHz)
35	X2	O	
36 └ 42	KEYIN 7 └ KEYIN 1	I	Key return signal
43	PWM	O	Motor control signal
44	POFF	I	Power det. terminal
45	POSITION	I	Rotary tray position det. terminal
46	SPEED	I	Loading motor speed sensor signal
47	REMOCON	I	Remote control signal input
48	IC	—	Not used, connected to GND
49	/TLOCK	I	Optical servo condition (tracking) input
50	/FLOCK	I	Optical servo condition (focus) input
51	STAT	I	Status signal (CRC, CUE, CLVS, TTSTOP, FCLV, SQCK)
52	VDD	I	Power supply terminal
53	POWER	O	Power ON/OFF output terminal
54	SYNCHRO	—	Not used, open
55 └ 60	KEYOUT 6 └ KEYOUT 1	O	Key scan signal
61 └ 70	S16 └ S7	O	Segment signal of FL display
71	VPP	I	Power supply terminal
72 └ 77	S6 └ S1	O	Segment signal of FL display
78	EXDATA	—	Not used, open
79	EXCLK	—	Not used, open
80	G8	O	Grid signal of FL display

# BLOCK DIAGRAM





Note: Audio signal

# SCHEMATIC DIAGRAM (Parts list on pages 46~48.)

(This schematic diagram may be modified at any time with the development of new technology.)

**Note:**

- S551 : Open/close det. switch.
- S601 : Time mode (TIME MODE) switch.
- S602 : Spiral (SPIRAL) switch.
- S603 : Random mode (RANDOM MODE) switch.
- S604 : Repeat (REPEAT) switch.
- S607 : Stop (■) switch.
- S608 : Pause (▣) switch.
- S609 : Play (▷) switch.
- S610~S614 : Disc (DISC 1~5) switches.  
[S610: 1, S611: 2, S612: 3, S613: 4, S614: 5]
- S615 : Disc skip (DISC SKIP) switch.
- S616 : Program mode (PROGRAM MODE) switch.
- S617, 618 : Search (SEARCH) switches.  
[S617: ◀◀, S618: ▶▶]
- S619, 620 : Skip (SKIP) switches.  
[S619: ◀◀◀, S620: ▶▶▶]
- S621 : Loading drawer open/close (△ OPEN/CLOSE) switch.
- S631 : Power "STANDBY ◊ ON" (POWER, STANDBY ◊ ON) switch.
- S701 : Rest detector switch.

- Put a conductive mat on the work table.
- Do not touch the pins of IC or LSI with fingers directly.
- The voltage value and waveforms are the reference voltage of this unit measured by DC electronic voltmeter (high impedance) and oscilloscope on the basis of chassis.

Accordingly, there may arise some error in voltage values and waveforms depending upon the internal impedance of the tester or the measuring unit.

\*The parenthesized are the values of voltage generated during playing (Test disc 1kHz, L+R, 0dB), others are voltage values in stop mode.

- Important safety notice:  
Components identified by △ mark have special characteristics important for safety. Furthermore, special parts which have purposes of fire-retardant (resistors), high-quality sound (capacitors), low-noise (resistors), etc. are used as occasion calls. When replacing any of components, be sure to use only manufacturer's specified parts shown in the parts list.
- The supply part number is described alone in the replacement parts.

**Caution!**

IC and LSI are sensitive to static electricity. Secondary trouble can be prevented by taking care during repair.

- Cover the parts boxes made of plastics with aluminum foil.
- Ground the soldering iron.

Part No.	Production Part No.	Supply Part No.
IC11	LM2940T5M	LM2940T5

- : Positive voltage lines and
- : Negative voltage lines.
- : audio signal lines.

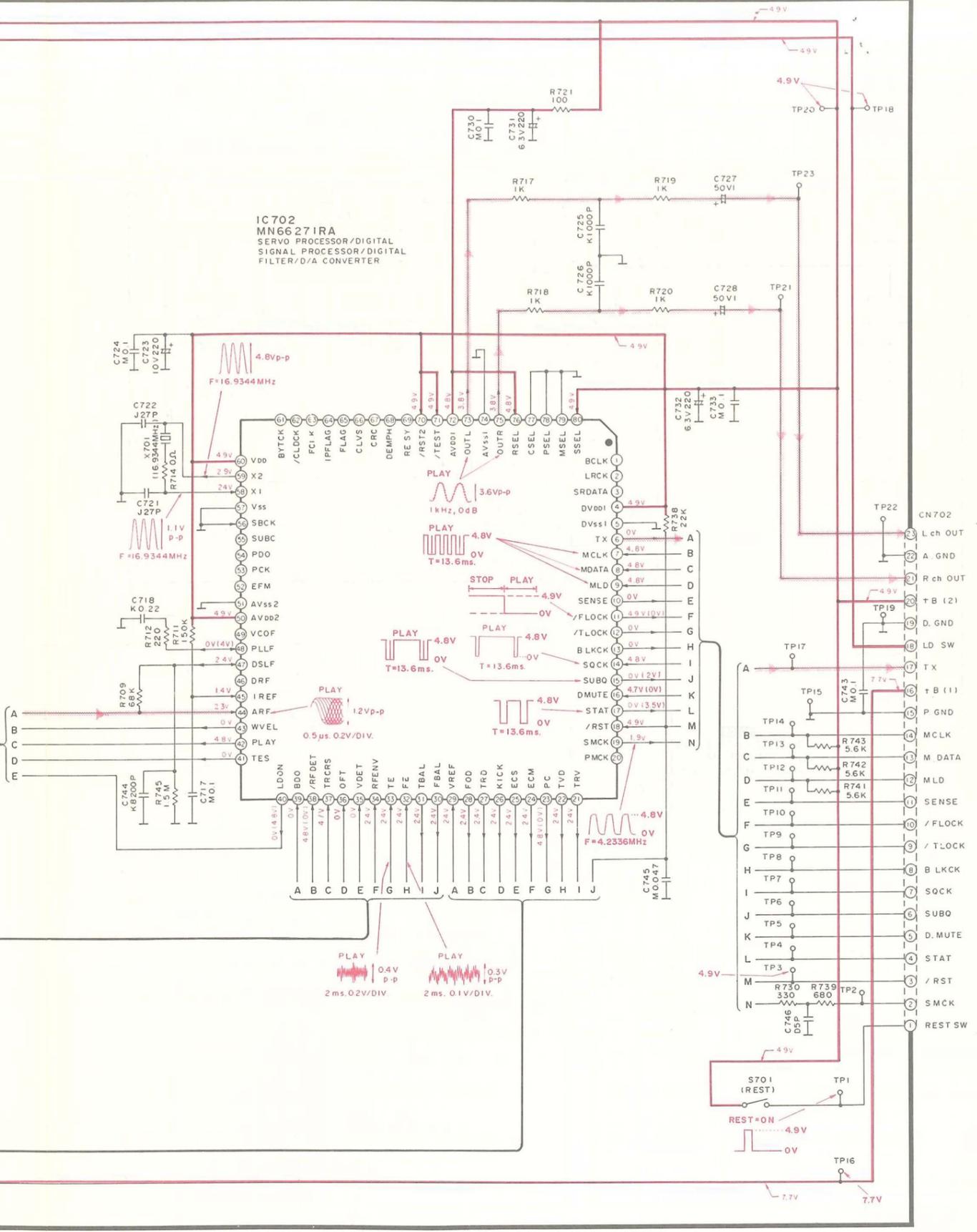
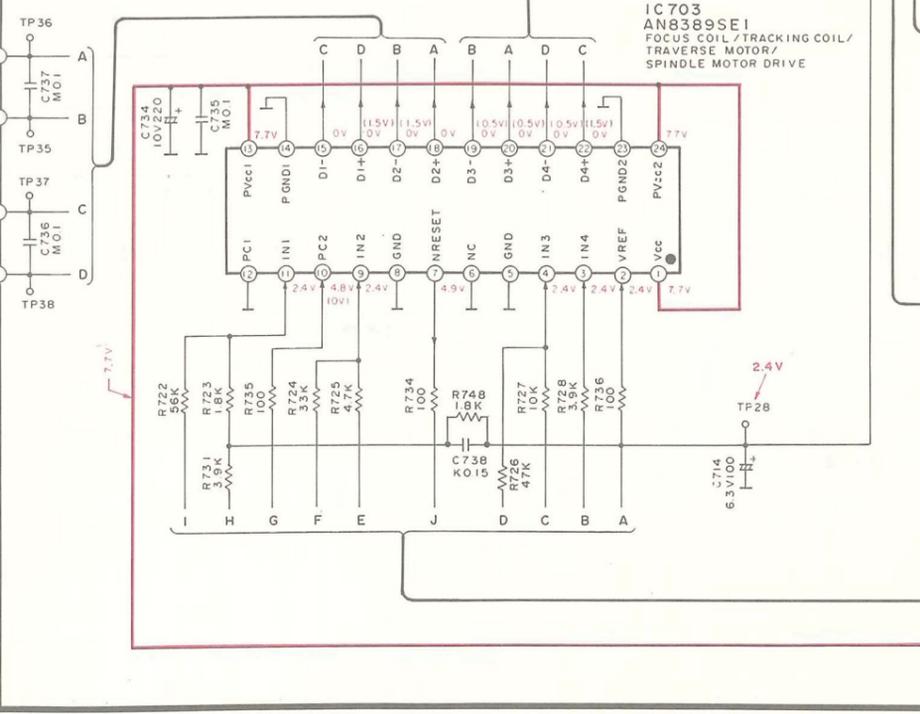
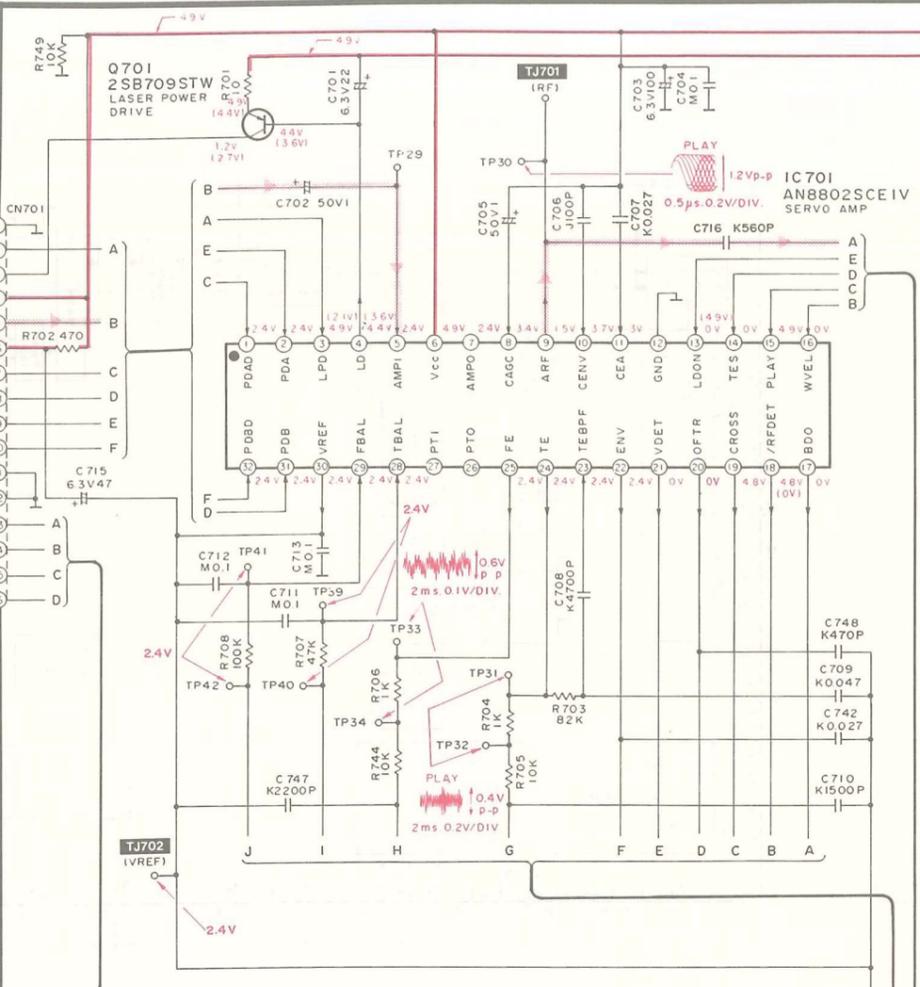
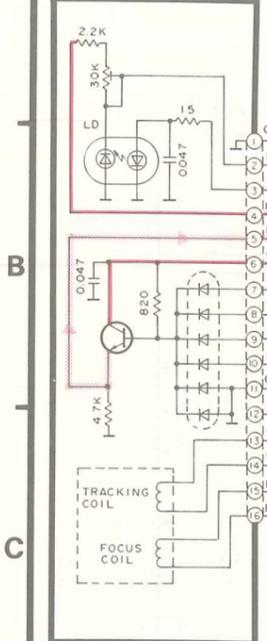
**Terminal guide of IC's, transistors and diodes.**

<p>XRA4558FT1</p>	<p>AN8802SCE1V</p>	<p>AN8389SE1</p>	<p>MN66271RA</p>	<p>ATT78043B065</p>	<p>BA6247N</p>
<p>LM2940T5M</p> <p>I. Vin G. GND O. Vout</p>	<p>E C B</p>	<p>2SA1309AIQST 2SC3311AIQST 2SD1450RSTTA UN4112TA UN4114TA UN4212TA UN4214TA UN4215TA</p>	<p>2SD2037EFTA</p> <p>B C E</p>	<p>2SB1238QSTV6 2SD1862QRTV6</p> <p>B C E</p>	<p>PT381</p> <p>Cathode Anode Ca A</p>
<p>2SB709S</p> <p>B C E</p>	<p>Ca Cathode Anode</p>	<p>MA4051MTA MA4056MTA MA4062MTA MA4068HTA MA4091MTA</p>	<p>MA4100MTA MA4270MTA</p> <p>Ca Cathode Anode</p>	<p>RL1N4003N02</p> <p>Ca Cathode Anode</p>	<p>MA165TA 1SS291TA</p> <p>Ca Cathode Anode</p>
<p>GL380</p> <p>Anode Cathode A Ca</p>	<p>RCDHC-278N</p> <p>3 2 1</p>	<p>RSQGP1S53V</p> <p>A E C Ca Ca C A Ca E</p>	<p>SG-206S</p> <p>A E C Ca Ca C A Ca E</p>		

1 2 3 4 5 6 7 8 9

A SERVO CIRCUIT

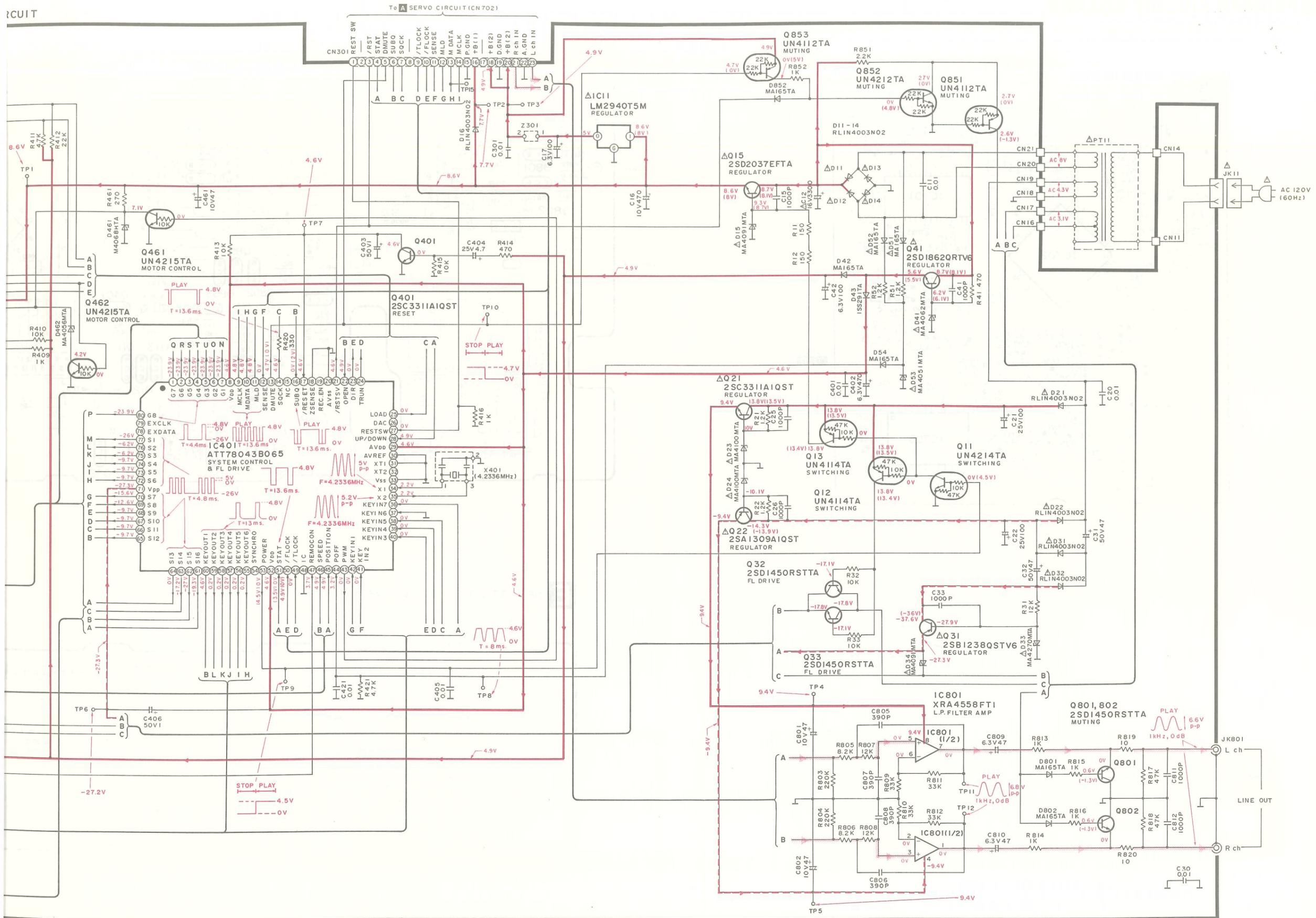
A OPTICAL PICKUP



A B C D E F G



ICUIT

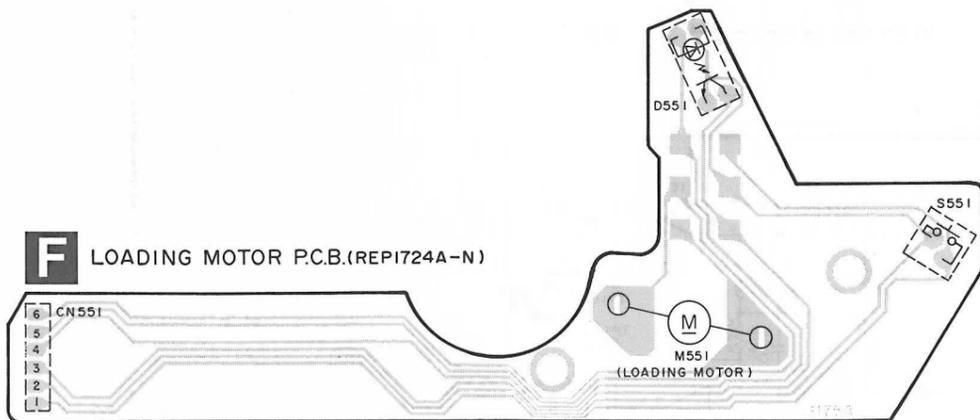
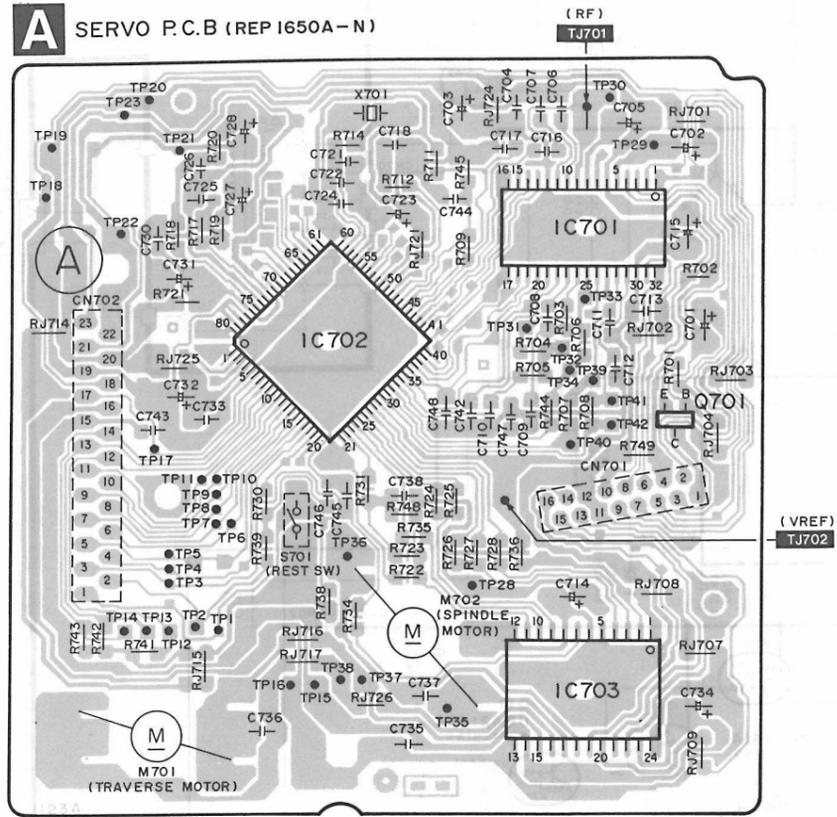


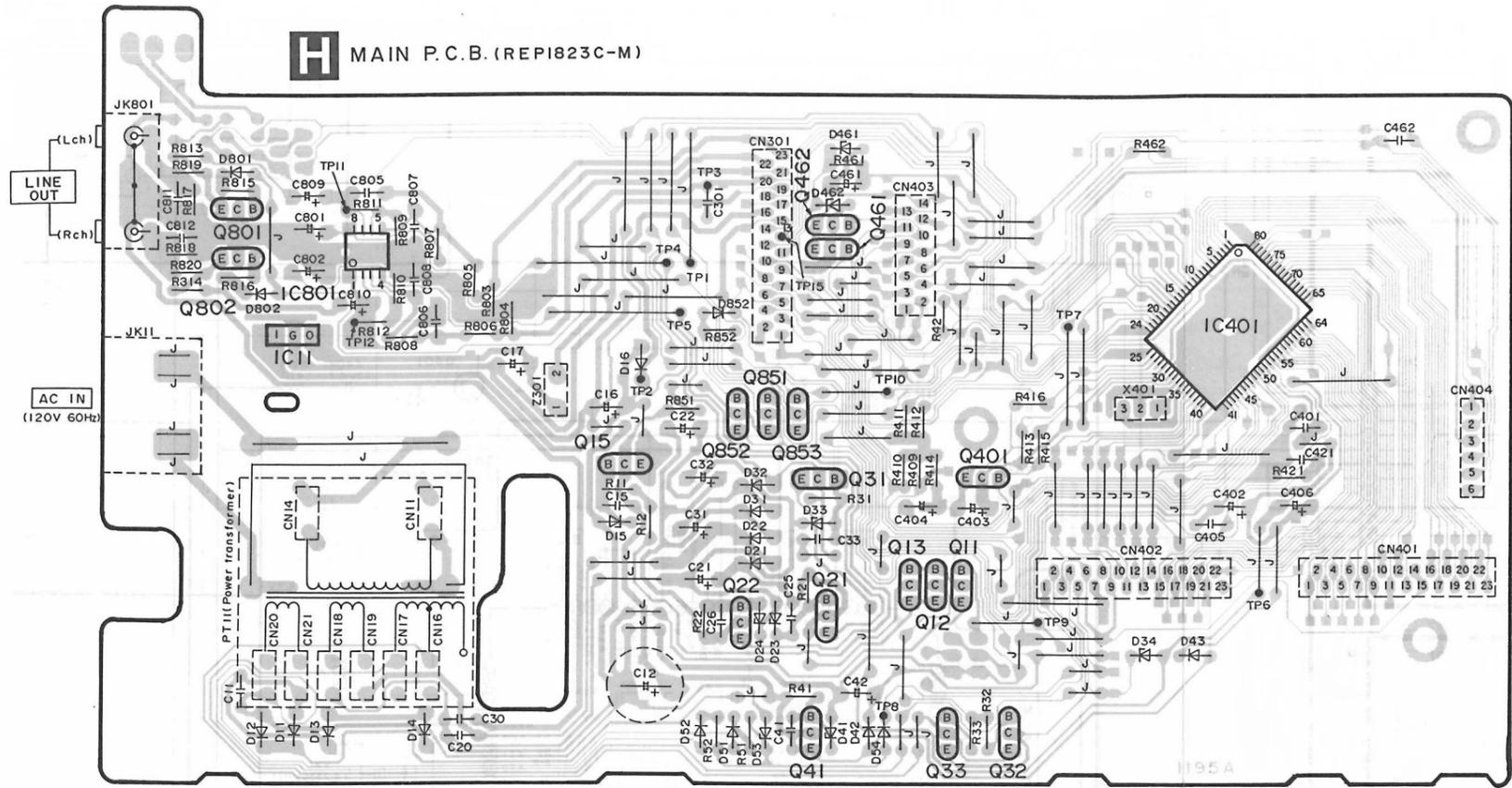
1 2 3 4 5

**PRINTED CIRCUIT BOARDS**

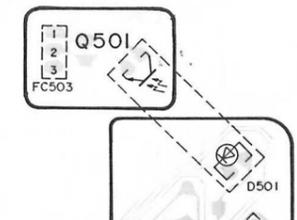
(This printed circuit board diagram may be modified at any time with the development of new technology)

A  
B  
C  
D  
E  
F  
G

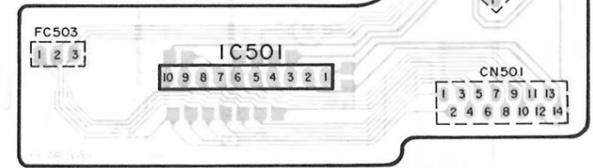




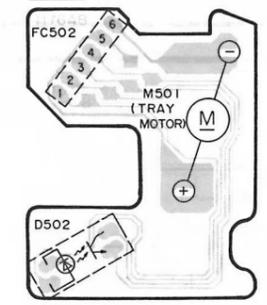
**D** PHOTO TRANSISTOR P.C.B. (REPI725A-N)



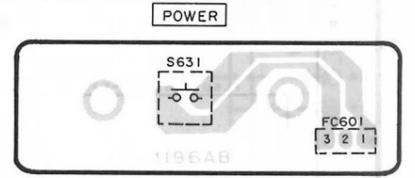
**G** SENSOR P.C.B. (REPI725A-N)



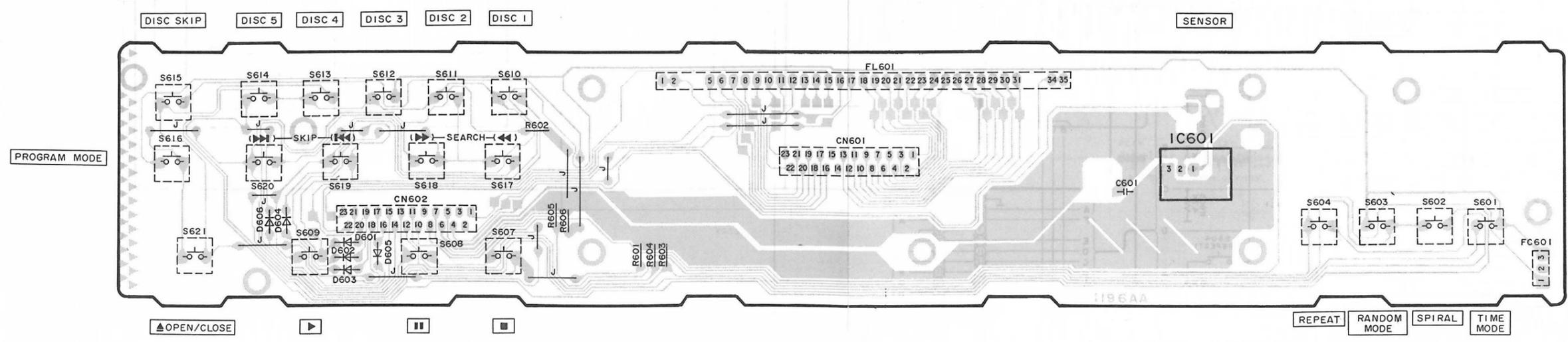
**B** TRAY MOTOR P.C.B. (REPI725A-N)



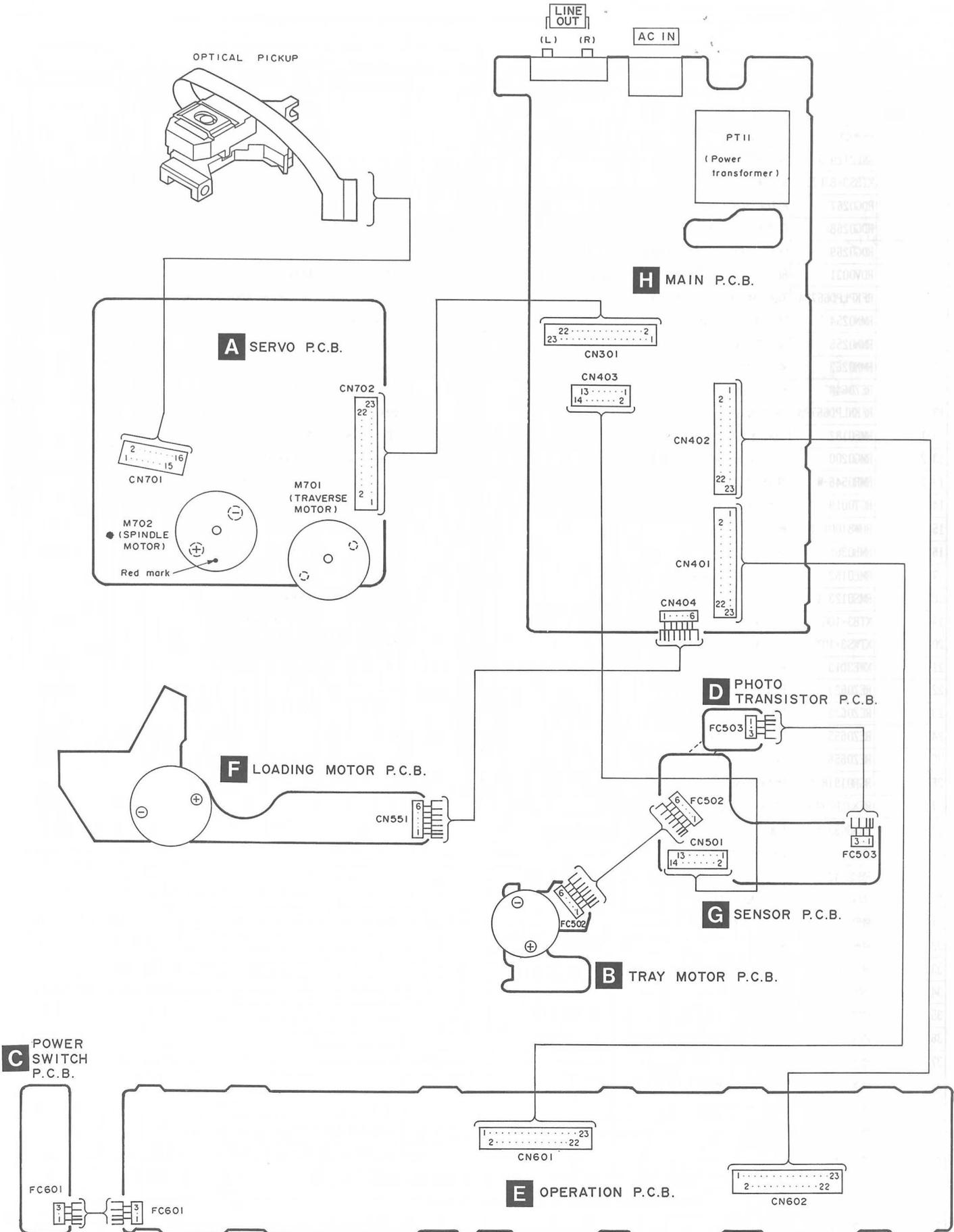
**C** POWER SWITCH P.C.B. (REPI824C-S)



**E** OPERATION P.C.B. (REPI824C-S)



# WIRING CONNECTION DIAGRAM

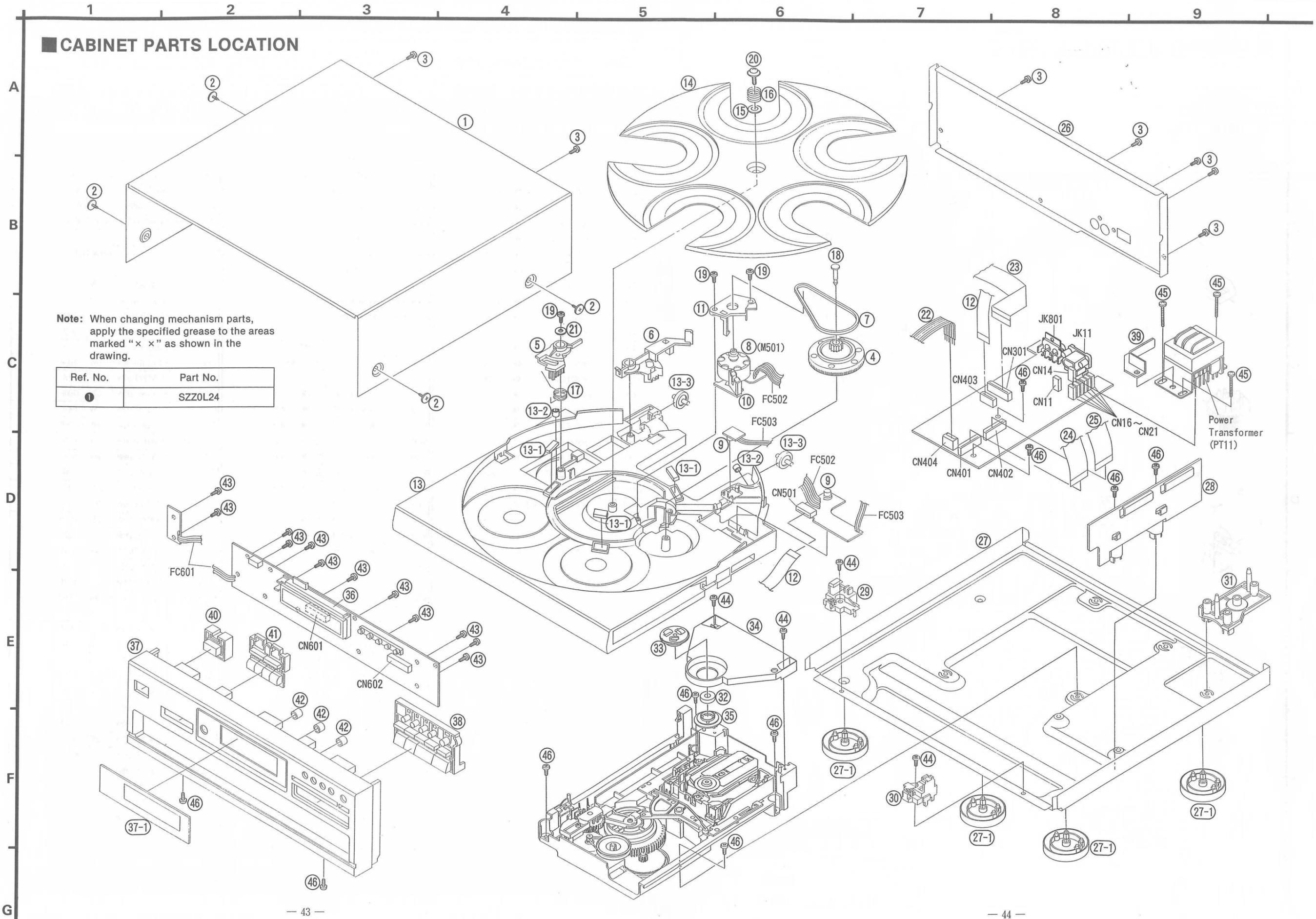


# REPLACEMENT PARTS LIST

Notes : \* Warning: This product uses a laser diode. Refer to caution statements on page 2.

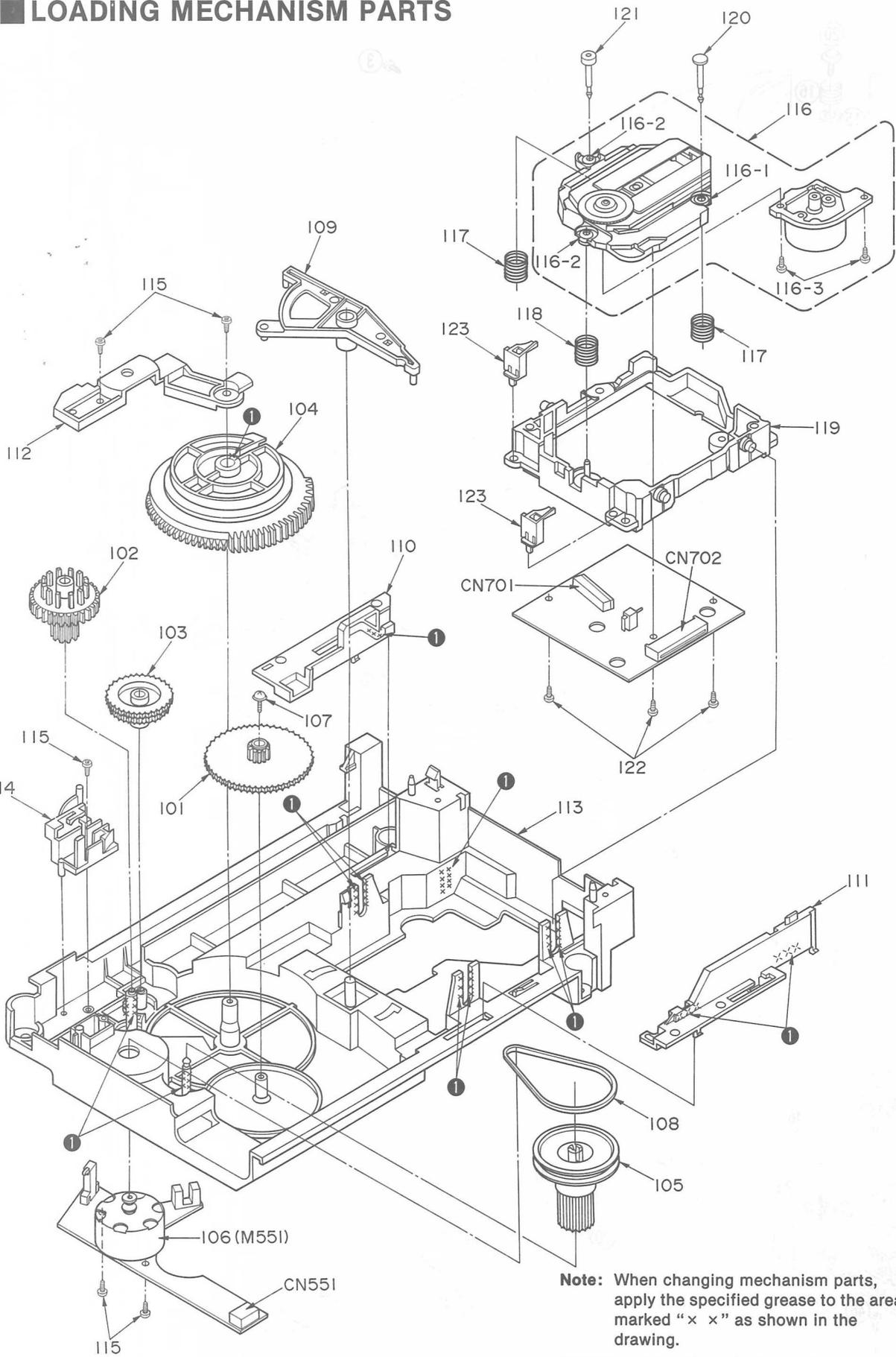
Ref. No.	Part No.	Part Name & Description	Remarks	Ref. No.	Part No.	Part Name & Description	Remarks
		CABINET AND CHASSIS		45	XTB3+20J	SCREW	
				46	XTB3+8JFZ	SCREW	
						LOADING MECHANISM	
1	RKMO269-K	CABINET		101	RDG0270	REDUCTION GEAR	
2	SNE2129-3	SCREW		102	RDG0271	DRIVE GEAR(1)	
3	XTBS3+8JFZ1	SCREW		103	RDG0272	DRIVE GEAR(2)	
4	RDG0267	REDUCTION GEAR		104	RDK0025	DRIVE CAM	
5	RDG0268	CLOSE LOCK GEAR		105	RDPO050	PULLEY GEAR	
6	RDG0269	OPEN LOCK GEAR		106	RFKPLPD667PB	LOADING MOTOR(M551) ASS' Y	
7	RDV0031	BELT		107	RHD26019	SCREW	
8	RFKPLPD667PA	TRAY MOTOR(M501) ASS' Y		108	RMG0268-K	BELT	
9	RMNO254	LED HOLDER(D501, Q501)		109	RML0334	DRIVE LEVER	
10	RMNO255	SENSOR HOLDER(D502)		110	RMM0117	SLIDE PLATE(1)	
11	RMNO263	MOTOR HOLDER		111	RMM0118	SLIDE PLATE(2)	
12	REZ0648	FLAT CABLE(14P)		112	RMRO746-W	REINFORCING PLATE	
13	RFKNLPD667PA	TRAY ASS' Y		113	RFKNLPD667PB	MECHANISM BASE ASS' Y	
13-1	RMFO182	TRAY FELT		114	RXQ0346	SLIDER ASS' Y	
13-2	RMGO200	SILENT RUBBER		115	XTB3+10JFZ	SCREW	
13-3	RMRO546-W	TRAY ROLLER		116	RAE0113Z	TRAVERSE DECK ASS' Y	
14	RGTO019	ROATARY TRAY		116-1	SHGD112	FLOATING RUBBER(1)	
15	RHW81001-1	WASHER		116-2	SHGD113-1	FLOATING RUBBER(2)	
16	RMBO365	SPRING		116-3	XQS17+A35FZ	SCREW	
17	RME0152	LOCK GEAR SPRING		117	RME0109	FLOATING SPRING(1)	
18	RMS0123-1	RIVET		118	RME0142	FLOATING SPRING(2)	
19	XTB3+10G	SCREW		119	FMRO698-K	TRAVERSE CHASSIS	
20	XTWS3+10T	SCREW		120	RMS0123-1	TRAVERSE FIXED PIN(1)	
21	XWE3D13	WASHER		121	RMS0350	TRAVERSE FIXED PIN(2)	
22	REZ0623	FLAT CABLE(6P)		122	XTV2+6G	SCREW	
23	REZ0635	FPC BOARD(23P)		123	RMX0094	TRAY HOLDER	
24	REZ0655	FPC BOARD(23P)					
25	REZ0656	FPC BOARD(23P)					
26	RGRO191B-A	REAR PANEL					
27	RFKJLPD349PK	CHASSIS ASS' Y					
27-1	RKA0053-K	FOOT					
28	FMRO767-W	CABLE HOLDER					
29	FMRO742-K	TRAY BASE GUIDE(L)					
30	FMRO743-K	TRAY BASE GUIDE(R)					
31	FMRO766-W	TRANSFORMER BASE					
32	RHM245ZA	MAGNET					
33	FMRO334	FIXED PLATE					
34	FMRO744-W	CLAMP PLATE					
35	FMRO761-W	CLAMPER					
36	FMNO185-1	FL HOLDER					
37	RFKGLPD449PK	FRONT PANEL ASS' Y					
37-1	RGK0611G-K	FRONT ORNAMENT PLATE					
38	RGU1046-K	MAIN BUTTON					
39	FMRO778-K	TRANSFORMER COVER					
40	RGU1015-K	POWER BUTTON					
41	RGU1017-K	SUB BUTTON					
42	RMGO200	STOPPER TUBE					
43	XTB26+8J	SCREW					
44	XTB3+10JFZ	SCREW					

■ CABINET PARTS LOCATION



LOADING MECHANISM PARTS

A  
B  
C  
D  
E  
F  
G



**Note:** When changing mechanism parts, apply the specified grease to the areas marked "x x" as shown in the drawing.

Ref. No.	Part No.
①	SZZ0L24

## RESISTORS AND CAPACITORS

Notes : \* Capacity values are in microfarads (uF) unless specified otherwise, P=Pico-farads (pF) F=Farads (F)  
\* Resistance values are in ohms, unless specified otherwise, 1K=1,000 (OHM), 1M=1,000k (OHM)

Ref. No.	Part No.	Values & Remarks	Ref. No.	Part No.	Values & Remarks	Ref. No.	Part No.	Values & Remarks
		RESISTORS	C402	ECA0JM471B	6.3V 470U			
			C403	ECEA1HKA010B	50V 1U	R714	ERJ6GEY0R00A	CHIP JUMPER
			C404	ECEA1EKA4R7B	25V 4.7U	RJ701-704	ERJ8GEY0R00A	CHIP JUMPER
R11, 12	ERDS2TJ151	1/4W 150	C405	ECBT1C103NS5	16V 0.01U	RJ707-709	ERJ8GEY0R00A	CHIP JUMPER
R21, 22	ERDS2TJ122	1/4W 1.2K	C406	ECEA1HKA010B	50V 1U	RJ714-717	ERJ8GEY0R00A	CHIP JUMPER
R31	ERDS2TJ123	1/4W 12K	C421	ECBT1C103NS5	16V 0.01U	RJ721	ERJ6GEY0R00A	CHIP JUMPER
R32, 33	ERDS2TJ103	1/4W 10K	C461	ECEA1AKA470B	10V 47U	RJ724-726	ERJ6GEY0R00A	CHIP JUMPER
R41	ERDS2TJ471	1/4W 470	C462	ECBT1C103NS5	16V 0.01U			
R51, 52	ERDS2TJ122	1/4W 1.2K	C601	ECFRIE104ZF5	25V 0.1U			CAPACITORS
R409	ERDS2TJ102	1/4W 1K	C801, 802	ECEA1AKA470B	10V 47U	C701	ECEA0JKA220	6.3V 22U
R410	ERDS2TJ103	1/4W 10K	C805-808	ECCRIH391J5	50V 390P	C702	ECEA1HKA010I	50V 1U
R411	ERDS2TJ472	1/4W 4.7K	C809, 810	ECEA0JKA470B	6.3V 47U	C703	ECEA0JKA101I	6.3V 100U
R412	ERDS2TJ223	1/4W 22K	C811, 812	ECBT1H102KB5	50V 1000P	C704	ECUZ1E104MBN	25V 0.1U
R413	ERDS2TJ103	1/4W 10K			<SERVO P. C. B>	C705	ECEA1HKA010I	50V 1U
R414	ERDS2TJ471	1/4W 470			RESISTORS	C706	ECUE1H101JCN	50V 100P
R415	ERDS2TJ103	1/4W 10K				C707	ECUV1E273KBN	25V 0.027U
R416	ERDS2TJ102	1/4W 1K	R701	ERJ6GEYJ100	1/10W 10	C708	ECUE1H472KBN	50V 4700P
R420	ERDS2TJ331	1/4W 330	R702	ERJ6GEYJ471V	1/10W 470	C709	ECUE1C473KBN	16V 0.047U
R421	ERDS2TJ472	1/4W 4.7K	R703	ERJ6GEYJ823	1/10W 82K	C710	ECUE1H152KBN	50V 1500P
R461	ERDS2TJ271	1/4W 270	R704	ERJ6GEYJ102A	1/10W 1K	C711, 712	ECUW1E104ZFN	25V 0.1U
R462	ERDS2TJ221	1/4W 220	R705	ERJ6GEYJ103V	1/10W 10K	C713	ECUV1C104MBM	16V 0.1U
R601-606	ERDS2TJ472	1/4W 4.7K	R706	ERJ6GEYJ102A	1/10W 1K	C714	ECEA0JKA101I	6.3V 100U
R803, 804	ERDS2TJ224T	1/4W 220K	R707	ERJ6GEYJ473V	1/10W 47K	C715	ECEA0JKA470I	6.3V 47U
R805, 806	ERDS2TJ822	1/4W 8.2K	R708	ERJ6GEYJ104V	1/10W 100K	C716	ECUE1H561KBN	50V 560P
R807, 808	ERDS2TJ123	1/4W 12K	R709	ERJ6GEYJ683V	1/10W 68K	C717	ECUW1E104ZFN	25V 0.1U
R809-812	ERDS2TJ333	1/4W 33K	R711	ERJ6GEYJ154V	1/10W 150K	C718	ECUV1C224KBM	16V 0.22U
R813-816	ERDS2TJ102	1/4W 1K	R712	ERJ6GEYJ221V	1/10W 220	C721, 722	ECUE1H270JCN	50V 27P
R817, 818	ERDS2TJ473	1/4W 47K	R717-720	ERJ6GEYJ102A	1/10W 1K	C723	ECEA1AKA221I	10V 220U
R819, 820	ERDS2TJ100	1/4W 10	R721	ERJ6GEYJ101V	1/10W 100	C724	ECUV1C104MBM	16V 0.1U
R851	ERDS2TJ222	1/4W 2.2K	R722	ERJ6GEYJ563V	1/10W 56K	C725, 726	ECUE1H102KBN	50V 1000P
R852	ERDS2TJ102	1/4W 1K	R723	ERJ6GEYJ182V	1/10W 1.8K	C727, 728	ECEA1HPK010I	50V 1U
		CAPACITORS	R724	ERJ6GEYJ333V	1/10W 33K	C730	ECUW1E104ZFN	25V 0.1U
			R725	ERJ6GEYJ472V	1/10W 4.7K	C731, 732	ECEA0JK221I	6.3V 220U
C11	ECBT1E103ZF	25V 0.01U	R726	ERJ6GEYJ473V	1/10W 47K	C733	ECUZ1E104MBN	25V 0.1U
C12	ECEA1CU332B	16V 3300U $\Delta$	R727	ERJ6GEYJ103V	1/10W 10K	C734	ECEA1AKA221I	10V 220U
C15	ECBT1H102KB5	50V 1000P	R728	ERJ6GEYJ392V	1/10W 3.9K	C735-737	ECUW1E104ZFN	25V 0.1U
C16	RCE1AM471BV	10V 470U	R730	ERJ6GEYJ331V	1/10W 330	C738	ECUV1C154KBN	16V 0.15U
C17	ECEA0JKA101B	6.3V 100U	R731	ERJ6GEYJ392V	1/10W 3.9K	C742	ECUV1E273KBN	25V 0.027U
C20	ECBT1E103ZF	25V 0.01U	R734-736	ERJ6GEYJ101V	1/10W 100	C743	ECUW1E104ZFN	25V 0.1U
C21, 22	ECA1EM101B	25V 100U	R738	ERJ6GEYJ223V	1/10W 22K	C744	ECUE1E822KBN	25V 8200P
C25, 26	ECBT1H102KB5	50V 1000P	R739	ERJ6GEYJ681V	1/10W 680	C745	ECUE1C473MBN	16V 0.047U
C30	ECBT1E103ZF	25V 0.01U	R741-743	ERJ6GEYJ562V	1/10W 5.6K	C746	ECUE1H050DCN	50V 5P
C31, 32	ECA1HM470B	50V 47U	R744	ERJ6GEYJ103V	1/10W 10K	C747	ECUE1H222KBN	50V 2200P
C33	ECBT1H102KB5	50V 1000P	R745	ERJ6GEYJ155V	1/10W 1.5M	C748	ECUV1H471KBM	50V 470P
C41	ECBT1H102KB5	50V 1000P	R748	ERJ6GEYJ182V	1/10W 1.8K			
C42	ECEA0JKA101B	6.3V 100U	R749	ERJ8GEYJ103V	1/8W 10K			
C301	ECBT1C103NS5	16V 0.01U						
C401	ECBT1C103NS5	16V 0.01U			CHIP JUMPERS			

## REPLACEMENT PARTS LIST

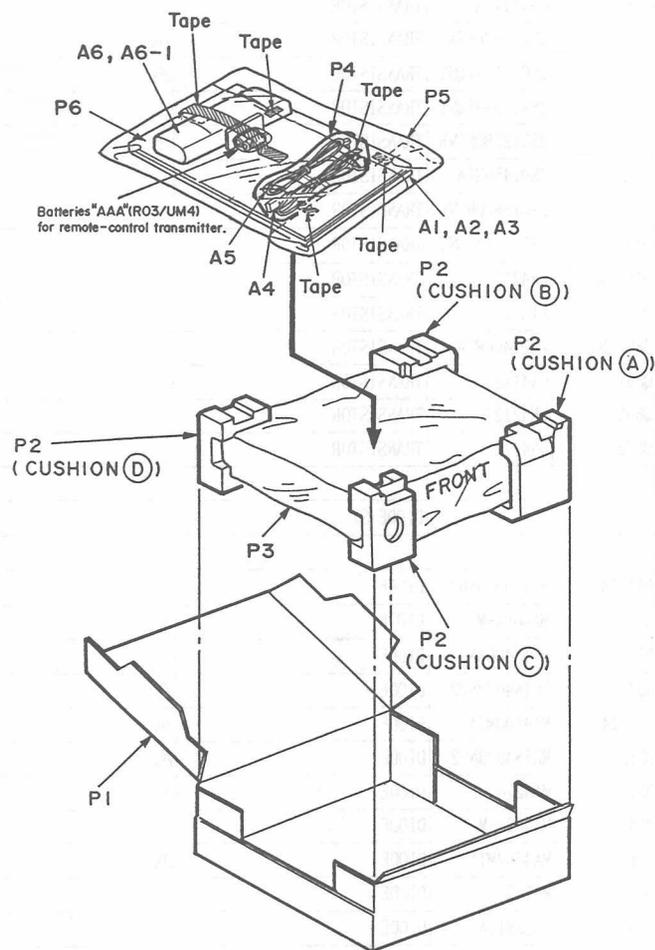
**Notes:** \*Important safety notice:  
 Components identified by  $\Delta$  mark have special characteristics important for safety.  
 Furthermore, special parts which have purposes of fire-retardant (resistors), high-quality sound (capacitors), low-noise (resistors), etc. are used.  
 When replacing any of components, be sure to use only manufacturer's specified parts shown in the parts list.  
 \*Remote Control Ass'y: Supply period for three years from termination of production.  
 \*The "(SF)" mark denotes the standard part.

Ref. No.	Part No.	Part Name & Description	Remarks	Ref. No.	Part No.	Part Name & Description	Remarks
		INTEGRATED CIRCUIT(S)		D502	RSQGP1S53V	DIODE	
				D551	SG-206S	DIODE	
				D601-606	MA165	DIODE	
IC11	LM2940T5	REGULATOR	$\Delta$	D801, 802	MA165	DIODE	
IC401	ATT78043B065	SYSTEM CONTROL&FL DRIVE		D852	MA165	DIODE	
IC501	BA6247N	MOTOR DRIVE				TRANSFORMER(S)	
IC601	RCDHC-278N	REMOTE CONTROL SENSOR					
IC801	XRA4558FT1	L. P. F.		PT11	RTP1K4C014-X	POWER TRANSFORMER	$\Delta$
		TRANSISTOR(S)				COMPONENT COMBINATION(S)	
Q11	UN4214TA	TRANSISTOR		Z301	BL02RN2R65T2	COMBINATION PART	
Q12, 13	UN4114TA	TRANSISTOR				OSCILLATOR(S)	
Q15	2SD2037EFTA	TRANSISTOR	$\Delta$	X401	RSXY4M23M01T	OSCILLATOR (4. 2336MHz)	
Q21	2SC3311AIQST	TRANSISTOR	$\Delta$			DISPLAY TUBE(S)	
Q22	2SA1309AIQST	TRANSISTOR	$\Delta$	FL601	RSL0170-F	DISPLAY TUBE	
Q31	2SB1238QSTV6	TRANSISTOR	$\Delta$			SWITCH(ES)	
Q32, 33	2SD1450RTA	TRANSISTOR		S551	RSH1A005	OPEN/CLOSE DETECTOR	
Q41	2SD1862QRTV6	TRANSISTOR	$\Delta$	S601	EVQ21405R	TIME MODE	
Q401	2SC3311AIQST	TRANSISTOR		S602	EVQ21405R	SPIRAL	
Q461, 462	UN4215	TRANSISTOR		S603	EVQ21405R	RANDOM MODE	
Q501	PT381TB	TRANSISTOR		S604	EVQ21405R	REPEAT	
Q801, 802	2SD1450RTA	TRANSISTOR		S607	EVQ21405R	STOP	
Q851	UN4112	TRANSISTOR		S608	EVQ21405R	PAUSE	
Q852	UN4212TA	TRANSISTOR		S609	EVQ21405R	PLAY	
Q853	UN4112	TRANSISTOR		S610	EVQ21405R	DISC 1	
		DIODE(S)		S611	EVQ21405R	DISC 2	
D11-14	RL1N4003N02	DIODE	$\Delta$	S612	EVQ21405R	DISC 3	
D15	MA4091-M	DIODE	$\Delta$	S613	EVQ21405R	DISC 4	
D16	RL1N4003N02	DIODE		S614	EVQ21405R	DISC 5	
D21, 22	RL1N4003N02	DIODE	$\Delta$	S615	EVQ21405R	DISC SKIP	
D23, 24	MA4100MTA	DIODE	$\Delta$	S616	EVQ21405R	PROGRAM MODE	
D31, 32	RL1N4003N02	DIODE	$\Delta$	S617	EVQ21405R	REV. SEARCH	
D33	MA4270	DIODE	$\Delta$	S618	EVQ21405R	FWD. SEARCH	
D34	MA4091-M	DIODE		S619	EVQ21405R	REV. SKIP	
D41	MA4062MTA	DIODE	$\Delta$	S620	EVQ21405R	FWD. SKIP	
D42	MA165	DIODE		S621	EVQ21405R	OPEN/CLOSE	
D43	1SS291TA	DIODE		S631	EVQ21405R	POWER	
D51, 52	MA165	DIODE	$\Delta$				
D53	MA4051MTA	DIODE	$\Delta$				
D54	MA165	DIODE					
D461	MA4068HTA	DIODE					
D462	MA4056MTA	DIODE					
D501	GL380TB	L. E. D.					

Ref. No.	Part No.	Part Name & Description	Remarks
		CONNECTOR (S)	
CN11	RJS1A1101T1	CONNECTOR (1P)	
CN14	RJS1A1101T1	CONNECTOR (1P)	
CN16-21	RJS1A1101T1	CONNECTOR (1P)	
CN301	RJS1A6823	CONNECTOR (23P)	
CN401, 402	RJS1A6823	CONNECTOR (23P)	
CN403	RJS1A6814	CONNECTOR (14P)	
CN404	RJS1A6606	CONNECTOR (6P)	
CN501	RJS1A6714	CONNECTOR (14P)	
CN551	RJS2A1506	CONNECTOR (6P)	
CN601, 602	RJS1A6223-1	CONNECTOR (23P)	
		JACK (S)	
JK11	SJSD16	AC INLET	△
JK801	RJH3201N	LINE OUT	
		FLAT CABLE (S)	
FC502	REZ0612	FLAT CABLE (6P)	
FC503	REZ0613	FLAT CABLE (3P)	
FC601	REZ0610	FLAT CABLE (3P)	
		<SERVO P. C. B.>	
		INTEGRATED CIRCUIT (S)	
IC701	AN8802SCE1V	SERVO AMP	
IC702	MN66271RA	SERVO PROCESSOR	
IC703	AN8389SE1	MOTOR DRIVE	
		TRANSISTOR (S)	
Q701	2SB709S	TRANSISTOR	
		OSCILLATOR (S)	
X701	RSXZ16M9M02T	OSCILLATOR (16.9344MHz)	
		SWITCH (ES)	
S701	RSM0006-P	REST DETECTOR	
		CONNECTOR (S) AND SOCKET (S)	
CN701	RJU035T016-1	SOCKET (16P)	
CN702	RJS1A6723-1Q	CONNECTOR (23P)	
		PACKING MATERIAL	
P1	RPG2191	PACKING CASE	
P2	RPNO781	CUSHION	

Ref. No.	Part No.	Part Name & Description	Remarks
P3	XZB60X65A01Z	PROTECTION BAG (UNIT)	
P4	XZB22X20C03	PROTECTION BAG (CORD)	
P5	XZB24X33C04	PROTECTION BAG (F. B.)	
P6	RPQ0164	PAD	
		ACCESSORIES	
A1	RFKSLPD449PK	INSTRUCTION MANUAL ASS'Y	
A2	RQA0093	WARRANTY CARD	
A3	RQCB0391	SERVICENTER LIST	
A4	SJA172	AC POWER SUPPLY CORD	△ (SF)
A5	SJP2249-3	STEREO CONNECTION CABLE	
A6	RAK-SL142WH	REMOTE CONTROL TRANSMITTER	
A6-1	RKK0057-K	BATTERY COVER	FOR R/C TRANSMITTER

### PACKAGING



(CUSHION (A), (B), (C), (D) Part NO.: RPN0781)