DIRECT DRIVE STEREO TURNTABLE

# PL-510 KLT, KCT, KUT PL-5105

KLT, KUT

⟨ART-163-0⟩

# Service Manual



**PIONEER**®

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# 1. SPECIFICATIONS

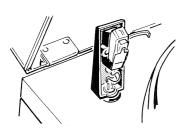
MOTOR AND TURNTABLE
MotorDC servo motorTurntable Drive.Direct driveSpeedTwo speeds; 33-1/3 rpm, 45 rpmWow and flutter0.03% (WRMS) or lessS/N.60 dB (JIS) or more(with Pioneer cartridge model PC-135)Turntable platter30cm diam. aluminum alloyMoment of inertia240kg-cm² (including rubber mat)
TONEARM
Tonearm type
SUBFUNCTIONS
Anti-skating force control Plug-in type headshell Oil-damped arm elevator Hinges (Free-adjustable) Lateral balance weight Fine speed adjusters(33-1/3 rpm, 45 rpm: using the stroboscope for turntable speed adjustment).
ACCESSORY GROUP
Headshell
MISCELLANEOUS
Power requirements
Specifications and the design subject to possible modification without notice due to improvements.

# 2. PANEL FACILITIES

# Headshell Stand

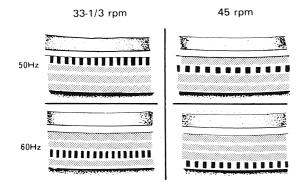
A spare headshell can be stored in this stand. Align the headshell pins with the stand grooves and insert.

Observe that the headshell length is not greater than the height of the dust cover. This stand can also be used for storing the 45 rpm adaptor.



# Stroboscope -

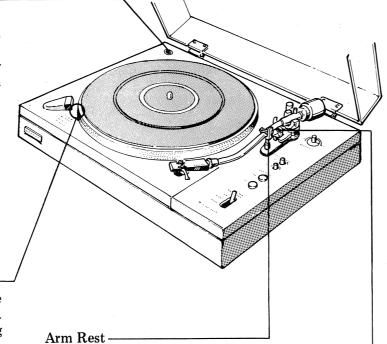
Fine adjustments of rotation speed can be performed with the aid of the stroboscope. Adjust the SPEED control knobs while observing the pattern indicated bellow. If the rotation is fast, the pattern will appear to move toward the left, while movement toward the right indicates slow speed. Correct speed is obtained when the pattern appears to be stationary.



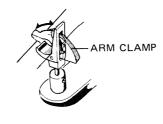
# 45 rpm Adaptor

Place on center shaft when playing 45 rpm EP records.



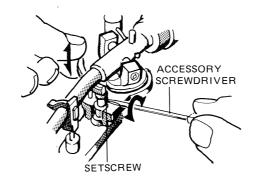


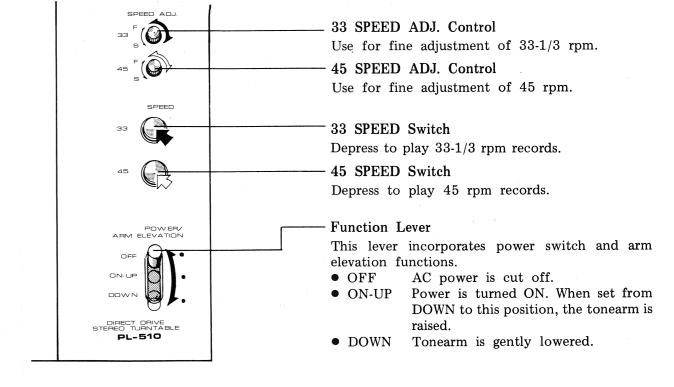
Supports the tonearm when not playing a record. At the end of a playing session, engage the clamp as illustrated below.



## **Arm Elevation**

Arm elevation may require adjustment according to cartridge height. If necessary use the accessory screwdriver to loosen the setscrew and adjust (see figure).





# **OPERATION**

- 1. Remove stylus cover.
- 2. Set function lever to ON-UP. Strobe lamp lights and platter rotates.
- 3. Depress SPEED button (33 or 45) according to type of record.
- 4. Employ SPEED ADJ. controls and stroboscope to adjust rotating speed (required only once per listening session).

  Stroboscope adjustment instructions are located on page 5.
- 5. Disengage arm clamp and gently position the tonearm over the desired portion of the record.
- Set function lever to DOWN.
  Stylus will be gently lowered onto the record.
- 7. Adjust volume and tone controls of the stereo amplifier as desired.
- 8. At the end of the record, or to interrupt the record, set the function lever to ON-UP. The stylus will be raised from the record.
- 9. Return tonearm to arm rest and engage clamp.

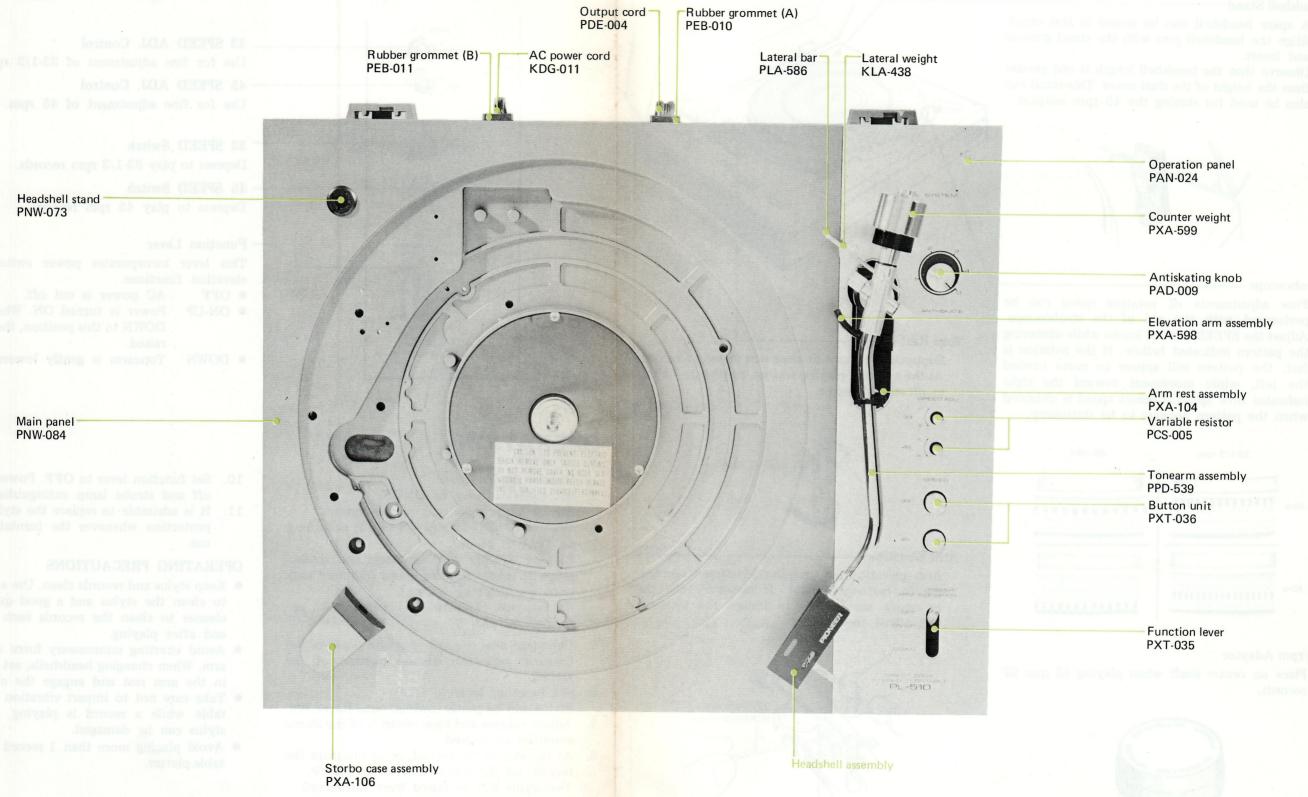
- 10. Set function lever to OFF. Power will be cut off and strobe lamp extinguished.
- 11. It is advisable to replace the stylus cover for protection whenever the turntable is not in use.

# OPERATING PRECAUTIONS

- Keep stylus and records clean. Use a stylus brush to clean the stylus and a good quality record cleaner to clean the records each time before and after playing.
- Avoid exerting unnecessary force on the tonearm. When changing headshells, set the tonearm in the arm rest and engage the clamp.
- Take care not to impart vibration to the turntable while a record is playing. Record and stylus can be damaged.
- Avoid placing more than 1 record on the turntable platter.

# 3. PARTS LOCATIONS

# 3.1 TOP VIEW



Wire-PXT-523

Microswitch KSF-016

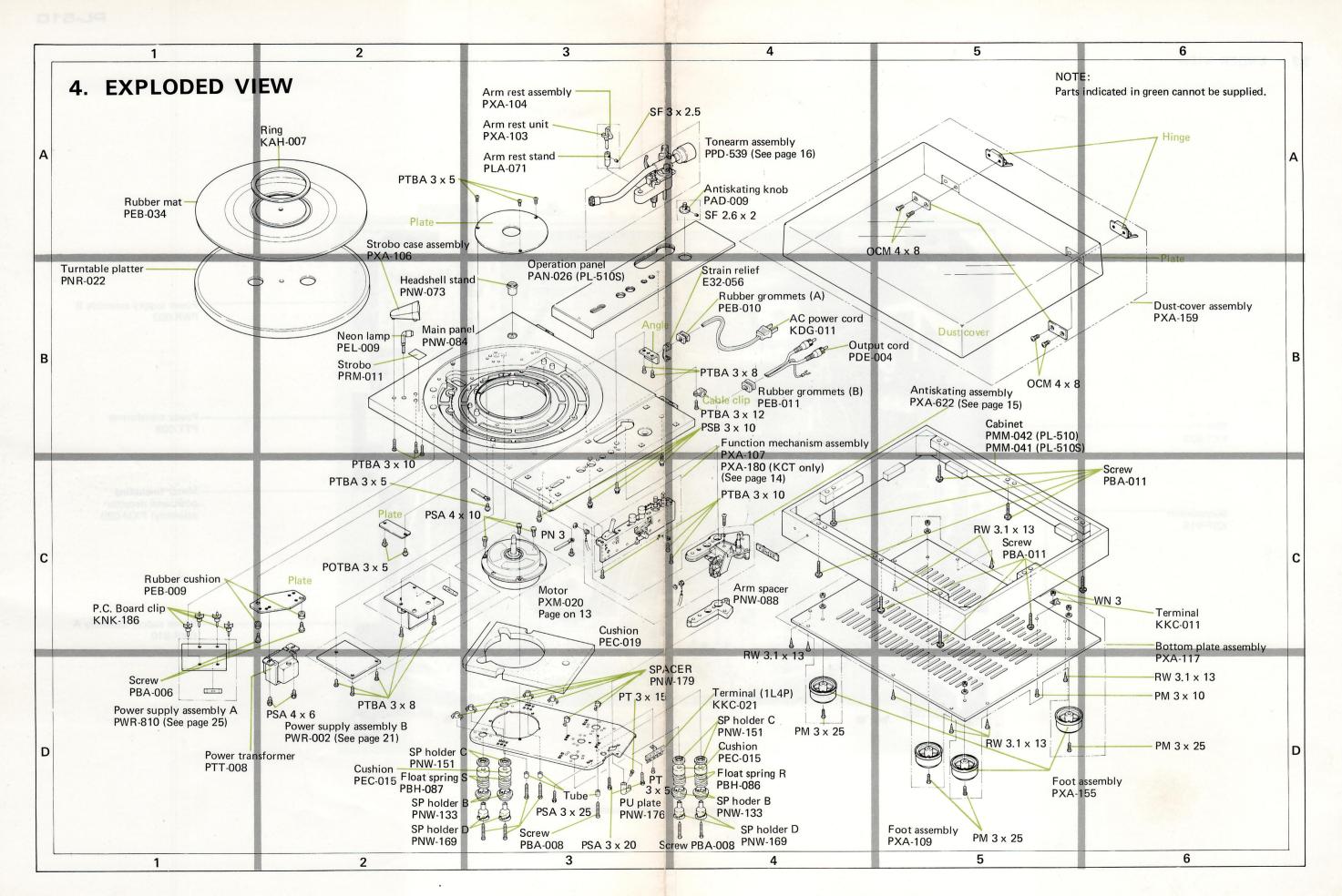
Power supply assembly B PWR-002

Power transformer PTT-008

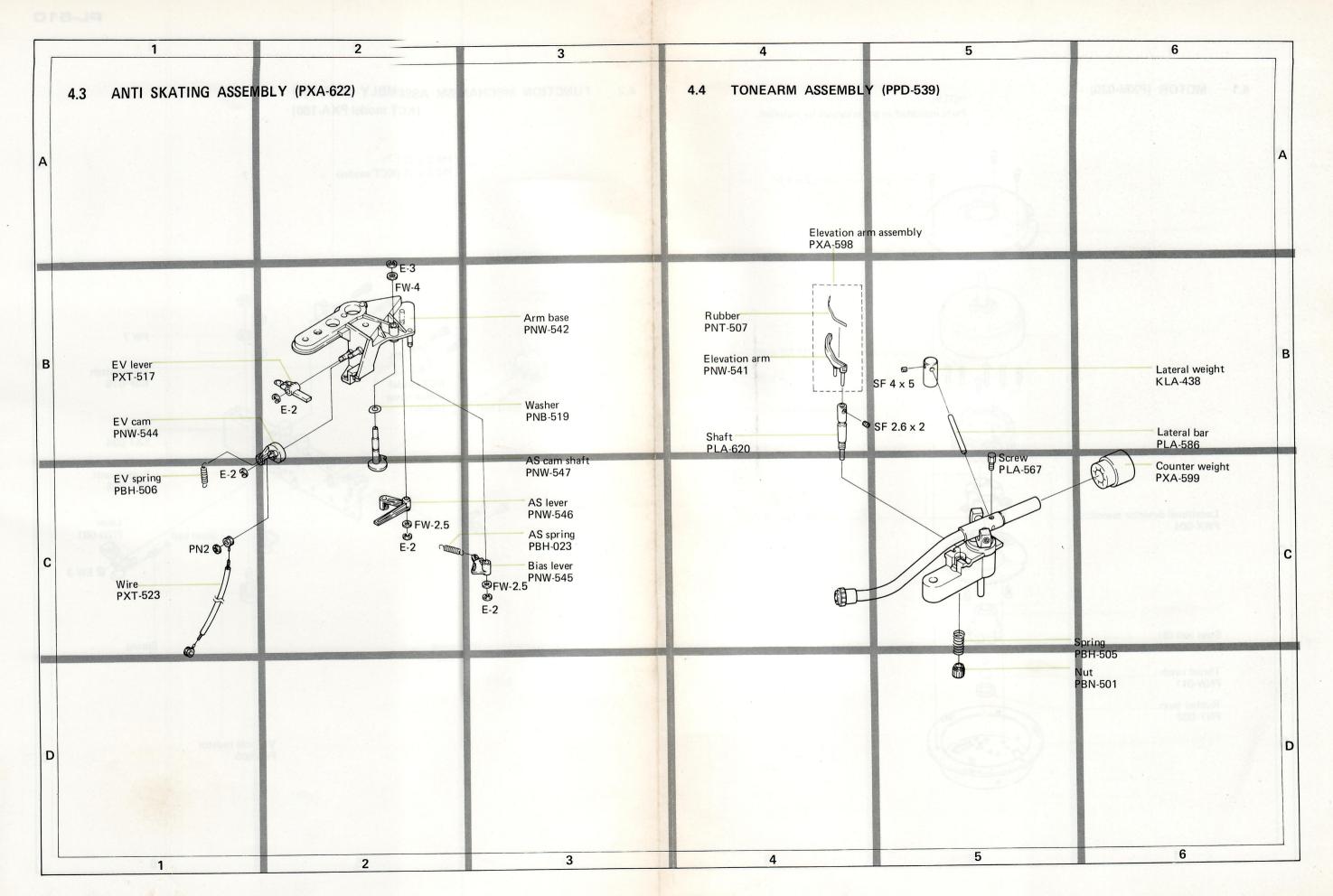
- Motor (including positional detector assembly) PXM-020

Power supply assembly A PWR-810

Driving current control assembly PWG-007



	1	2	3	4	5	6
	4.1 MOTOR (PXM-020)	NOTE:	en cannot be supplied.	4.2 FUNCTION MECHAN	VISM ASSEMBLY (PXA-107) (KCT model PXA-180)	4.3 ANTI SKATING ASSE
A			2.6 × 6 <sup>e</sup>		PM 3 x 12 PM 3 x 15 (KCT model)	N 7
	Upper cover		Bob Astri	Fuction lever PXT-035		
В	Rotor assembly		PM 2.6 × 20 PM 2.6 × 30	EW 3	KCT model	FW 7  Microswitch KSF-016
	Armature core		1	Spring PBH-028 Steel ball	within cover (Cover)	Angle PXT-034  Button unit
С	Locational detector assembly PWX-004		PM 2.6 × 6	PSA 3 x 8		PXT-036  Lever PNW-091
	Bearing assembly Steel ball (B)		PM 2.6 x 3	Wi	ire guide JW-092	Spring PBH-029
D	PEF-001  Thrust catch			PN		ariable resistor CS-005
	1	2	3	4 .	5	6



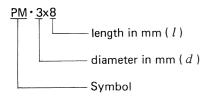
# 5. NOMENCLATURE OF SCREWS, WASHERS AND NUTS

The following symbols stand for screws, washers and nuts as shown in exploded view.

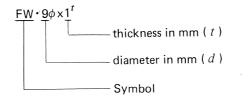
Symbol	Description	Shape
RT	Brazier head tapping screw	
PT	Pan head tapping screw	
PTT	Special screw (A)	Cimminim
РТВА	Special screw (B)	
РОТВА	Special screw (C)	
ост	Oval countersunk head tapping screw	
PM	Pan head machine screw	
СМ	Countersunk head machine screw	
ОСМ	Oval countersunk head machine screw	
ТМ	Truss head machine screw	
вМ	Binding head machine screw	
PSA	Pan head screw with spring lock washer	
PSB	Pan head screw with spring lock washer and flat washer	
PSF	Pan head screw with flat washer	

Symbol	Description	Sha	pe
EW	E type washer		
FW	Flat washer		
sw	Spring lock washer		
N	Nut	0	
WN	Washer faced nut	0	
PN	Push nut		1
FFW	Fiber flat washer	0	
SC	Slotted set screw (Cone point)	€	
SF	Slotted set screw (Flat point)	$\Theta$	
HS	Hexagon socket headless set screw	<b>©</b>	
ocw	CW Oval countersunk head wood screw		
CW	Countersunk head wood screw	<u> </u>	
RW	Round head wood screw		

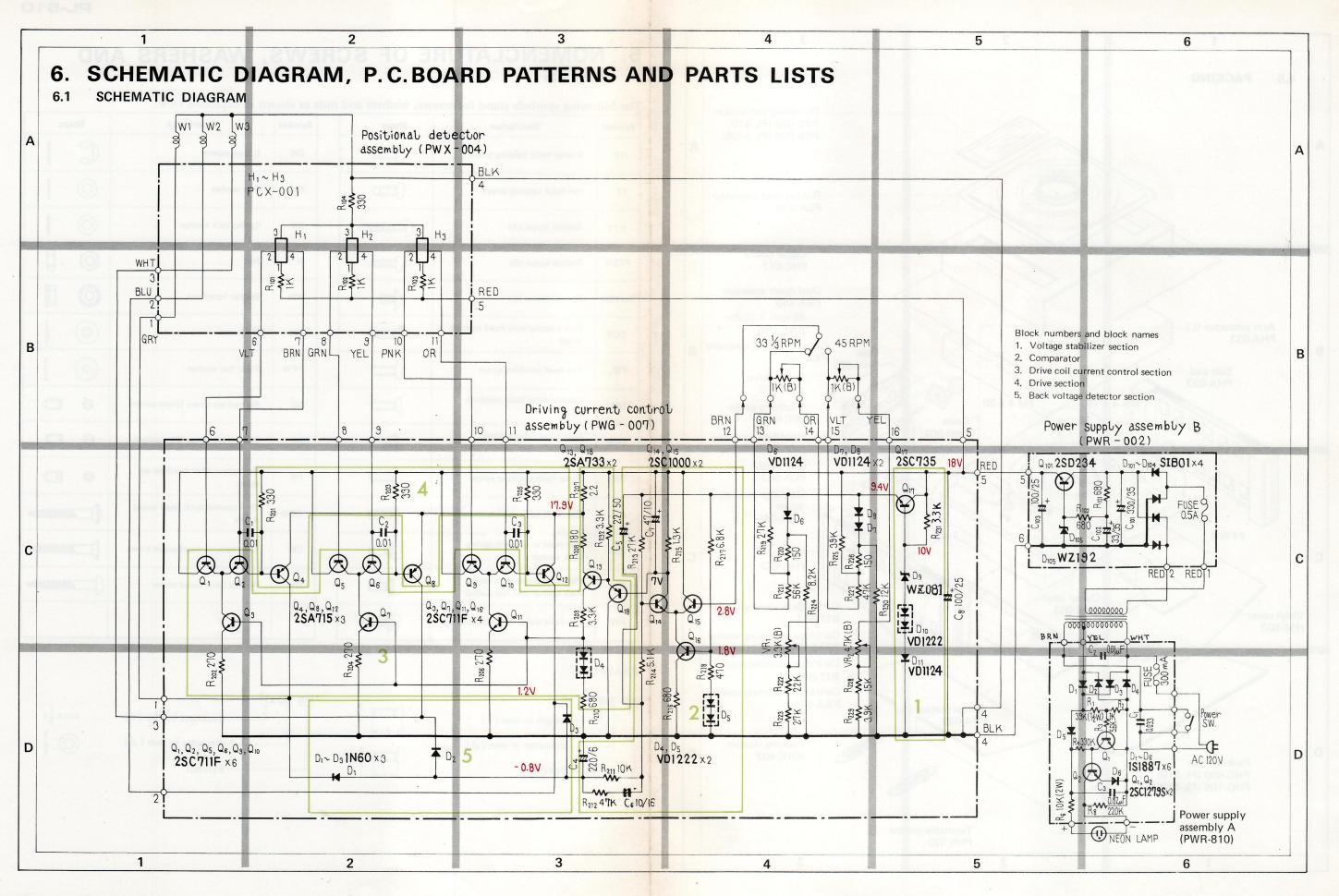
# **EXAMPLE**



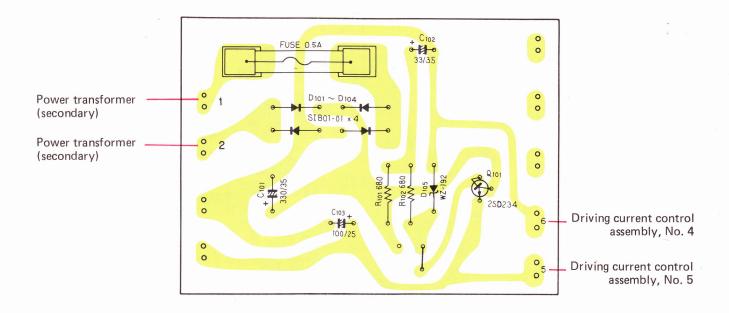








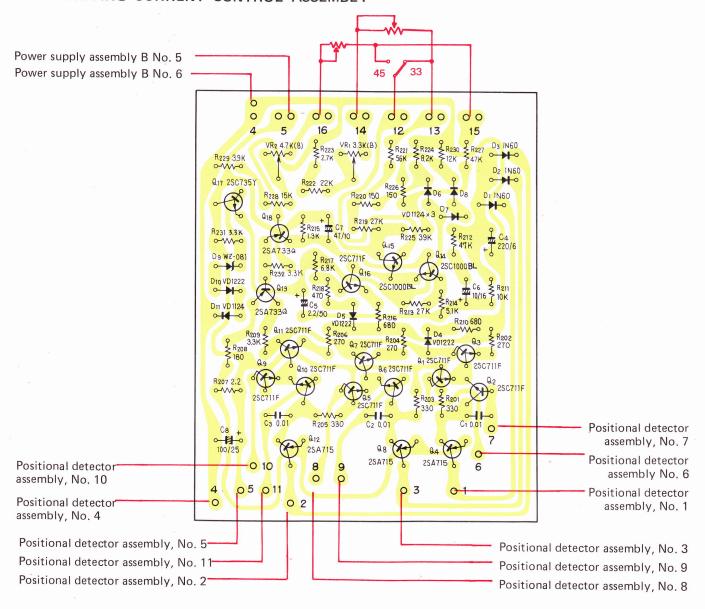
# 6.2 POWER SUPPLY ASSEMBLY B (PWR-002)



Parts List of Power Supply Assembly B

Parts List of Power Supply Assembly B					
Symbol	Description		Part No.		
C101	Electrolytic	330	50V	CEA 331P 35	
C102	Electrolytic	33	35V	CEA 330P 35	
C103	Electrolytic	100	25V	CEA 101P 25	
R101	Carbon film	680		RD%PS 681J	
R102	Carbon film	680		RD%PS 681J	
Q101	Transistor			2SD234	
D101	Diode			SIB01-01	
D102	Diode			SIB01-01	
D103	Diode			SIB01-01	
D104	Diode			SIB01-01	
D105	Zener diode			WZ-192	
FU	Fuse Fuse clip	500mA		PEK-004 K91-006	

# 6.3 DRIVING CURRENT CONTROL ASSEMBLY



# Parts List of Driving Current Control Assembly

# **CAPACITORS**

Symbol	Description			Part No.
C1 C2	Ceramic	0.01	50V	CKDYF 103Z 50
C3	Ceramic	0.01	50∨	CKDYF 103Z 50
	Ceramic	0.01	50∨	CKDYF 103Z 50
C4	Electrolytic	220	6V	CEA 221P 6
C5	Electrolytic	2.2	50V	CEA 2R2P 50
C6	Electrolytic	10	16V	CEA 100P 16
C7	Electrolytic	47	10V	CEA 470P 10
C8	Electrolytic	100	25V	CEA 101P 25

# **RESISTORS**

Symbol	Description		Part No.
R201	Carbon film	330	RD¼VS 331J
R202	Carbon film	270	RD¼VS 271J
R203	Carbon film	330	RD¼VS 331J
R204	Carbon film	270	RD¼VS 271J
R205	Carbon film	330	RD¼VS 331J
R206	Carbon film	270	RD¼VS 271J
R207	Carbon film	2.2	RD½VS 2R2J
R208	Carbon film	180	RD%VS 181J
R209	Carbon film	3.3k	RD%VS 332J
R210	Carbon film	680	RD¼VS 681J
R211	Carbon film	10k	RD%VS 103J
R212	Carbon film	47k	RD%VS 473J
R213	Carbon film	27k	RD%VS 273J
R214	Carbon film	5.1k	RD%VS 512J
R215	Carbon film	1.3k	RD¼VS 132J
R216	Carbon film	680	RD¼VS 681J
R217	Carbon film	6.8k	RD%VS 682J
R218	Carbon film	470	RD¼VS 471J
R219	Carbon film	27k	RD¼VS 273J
R220	Carbon film	150	RD¼VS 151J
R221	Carbon film	56k	RD¼VS 563J
R222	Carbon film	22k	RD%VS 223J
R223	Carbon film	2.7k	RD¼VS 272J
R224	Carbon film	8.2k	RD¼VS 822J
R225	Carbon film	39k	RD%VS 393J
R226	Carbon film	150	RD%VS 151J
R227	Carbon film	47k	RD¼VS 473J
R228	Carbon film	15k	RD¼VS 153J
R229	Carbon film	3.9k	RD¼VS 392J
R230	Carbon film	12k	RD¼VS 123J
R231	Carbon film	3.3k	RD%VS 332J
R232	Carbon film	3.3k	RD¼VS 332J
VR1	Semi-fixed	3.3k-B	PCP-001
VR2	Semi-fixed	4.7k-B	PCP-002

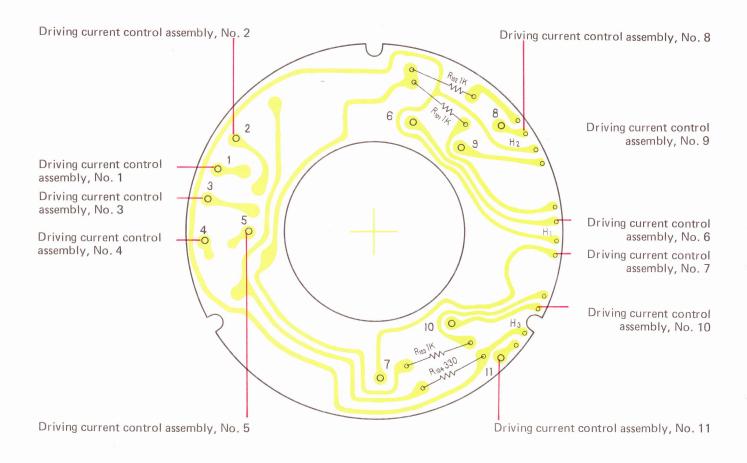
	Symbol	Description	Part No.
	Ω6	Transistor	2SC711-F
1			(2SC458-C,
1			2SC945-P1)
١	<b>Q</b> 7	Transistor	2SC711-F
1			(2SC923-E)
1	<b>Q8</b>	Transistor	2SA715-C
1			(2SA509-Y,
١			2SB564-L)
١	<b>Q</b> 9	Transistor	2SC711-F
١			(2SC458-C,
			2SC945-P1)
-	Q10	Transistor	2SC711-F
1			(2SC458-C,
1		/	2SC945-P1)
١	Q11	Transistor	2SC711-F
			(2SC923-E)
1	Q12	Transistor	2SA715-C
1			(2SA509-Y,
1			2SB564-L)
İ	Q13	Transistor	2SA733-Q
1	Q14	Transistor	2SC1000-BL
	Q15	Transistor	2SC1000-BL
	Q16	Transistor	2SC711-F
1			(2SC923-E)
1	Q17	Transistor	2SC735-Y
1	Q18	Transistor	2SA733-Q
	D1	Diode	IN60
	D2	Diode	IN60
١	D3	Diode	IN60
ı	D4	Varistor	VD1222
	D5	Varistor	VD1222
	D6	Varistor	VD1124
	D7	Varistor	VD1124 VD1124
1	D8	Varistor	VD1124
	D9	Zener diode	WZ081
	D10	Varistor	VD1222
	D11	Varistor	VD1124

# **SEMICONDUCTORS**

Symbol	Description	Part No.
Q1	Transistor	2SC711-F
		(2SC458-C,
		2SC945-P1)
Q2	Transistor	2SC711-F
		(2SC458-C,
		2SC945-P1)
Q3	Transistor	2SC711-F
		(2SC923-E)
Q4	Transistor	2SA715-C
		(2SA509-Y,
		2SB564-L) \
Q5	Transistor	2SC711-F
		(2SC458-C,
		2SC945-P1)

- 1.  $Q_1$ ,  $Q_2$ ,  $Q_5$ ,  $Q_6$ ,  $Q_9$ , and  $Q_{10}$  should, on the same circuit board, use the same kind and rank of product.
- Q<sub>3</sub>, Q<sub>7</sub>, Q<sub>11</sub>, and Q<sub>16</sub> should, on the same circuit board, use the same kind and rank of product.
   D<sub>1</sub>, D<sub>2</sub>, and D<sub>3</sub> should be 'paired' (PYY-006-0).

# 6.4 POSITIONAL DETECTOR ASSEMBLY (PWX-004)



Parts List of Positional Detector Assembly (PWX-004)

Symbol	Description	Part No.
H1	Hall-effect element	PCX-001
H2	Hall-effect element	PCX-001
НЗ	Hall-effect element	PCX-001
R101	Carbon film resistor 1k	RD%PS 102J
R102	Carbon film resistor 1k	RD%PS 102J
R103 Carbon film resistor 1k		RD%PS 102J
R104	Carbon film resistor 330	RD%PS 331J

## 6.5 POWER SUPPLY ASSEMBLY A (PWR-810) Secondary 0000000 Power transfomer 120V BRN WHT 100V 00 D1 ~D4 1S1887 × 4 0 6 0 PT PT PT Power SW (BR) (YE) (WH) switch 1 0 0 R<sub>1</sub> 39K(½w) C2 0.01µF ± C1 T 0.033μF 0,0 Q<sub>1</sub> 2SC 1279S R<sub>3</sub> 5.6 K D5 1S1887 AC 120V AC 0 R4 330K Q2 2SC1279S D6 1S1887 FUSE 25V 300mA R<sub>8</sub> 220K

₹R<sub>6</sub> 10K(2W)

(+)

OO NE OO

Cз 0.82µF

STROBE LIGHT

Parts List of Power Supply Assembly A (PWR-810)

Symbol	Desc	ription		Part No.
C1	Ceramic	0.033		KCE-009
C2	Ceramic	0.01		ACG-003
C3	Ceramic	0.82		PCL-010
R1	Carbon film	39k	1/2W	RD½P 393
R2	Carbon film	1k		RD%P 102J
R3	Carbon film	5.6k		RD¼P 562J
R4	Carbon film	330k		RD¼P 334J
R6	Carbon film	10k	2W	RD2P 102J
R8	Carbon film	220k		RD¼P 224J
D1	Diode			1S1887
D2	Diode			1S1887
D3	Diode			1S1887
D4	Diode			1S1887
D5	Diode			1S1887
D6	Diode			1S1887
Q1	Transistor			2SC1279S
Q2	Transistor			2SC1279S
FU	Fuse Fuse clip	300mA		E21-030 K91-006

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# 7. PXM-020 OUTLINE OF OPERATION

# 7.1 STRUCTURE

The PXM-020 is an external-rotor type DC motor in which Hall-effect elements are used to detect the rotor position, with electronic ON-OFF switching of the current to the motor windings. As shown in Figure 1a, the ferrite rotor is magnetized alternately N and S in 45° segments. Figure 1b shows the three Hall-effect elements under the rotor

The Hall-effect elements,  $H_1$ ,  $H_2$ , and  $H_3$ , are fitted 30° apart (120° magnetically), so that whatever the orientation of the rotor, one of them will experience a Hall potential at a particular time.

# 7.2 OPERATION OF THE MOTOR (SEE CONNECTION DIAGRAM)

When the electrical supply is connected to the motor, current flows through the three Hall-effect elements, which go into the operating condition. If we assume, at this time, that a rotor N pole is located at the  $H_1$  Hall-effect element position, then the Hall potential developed in  $H_1$  sends the base of  $Q_1$  negative (-) and that of  $Q_2$  positive

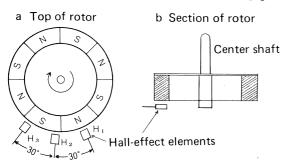


Fig. 1: Relative Locations of Rotor and Hall-Effect Elements

(+). Due to this Hall-effect potential Q<sub>2</sub> turns ON, voltage at the Q<sub>2</sub> collector drops, the potentail on the base of Q<sub>4</sub> drops, and Q<sub>4</sub> turns ON. With Q<sub>4</sub> ON, the motor drive coil W<sub>1</sub> is energized by the collector current, and the rotor begins to move. After some small movement of the rotor, the N pole approaching the Hall-effect element H<sub>2</sub> causes Q<sub>6</sub> and Q<sub>8</sub> to turn ON, and drive coil W<sub>3</sub> to be energized. With further movement of the rotor the N pole approaches H<sub>3</sub>, Q<sub>10</sub> and Q<sub>12</sub> go ON, and W<sub>2</sub> is energized. The first N pole passes H<sub>3</sub> as the next one approaches H<sub>1</sub>, putting Q<sub>2</sub> and Q<sub>4</sub> ON, and thus the rotation of the rotor is continuously sustained.

On the other hand, when a S pole approaches the Hall-effect element(s)  $H_1$  ( $H_2$ ,  $H_3$ ), the polarity of the Hall potential changes, the base(s) of  $Q_1$  ( $Q_5$ ,  $Q_9$ ) go positive (+), the base(s) of  $Q_2$  ( $Q_6$ ,  $Q_{10}$ ) go negative (—), and so  $Q_2$  ( $Q_6$ ,  $Q_{10}$ ) turn OFF. This means that  $Q_4$  ( $Q_8$ ,  $Q_{12}$ ) also turn OFF and the current ceases to flow in the drive coil(s)  $W_1$  ( $W_2$ ,  $W_3$ ).

# 7.3 SPEED CONTROL

When no current is flowing through a drive coil (that is when a S pole is approaching the Hall effect element), a voltage proportional to the speed of rotation of the rotor is induced in the drive coil (the same effect as with a generator). This voltage is rectified by the diode(s)  $D_1$  ( $D_2$ ,  $D_3$ ), and the negative potential derived is applied to the base of  $Q_{14}$ .  $Q_{14}$  and  $Q_{15}$  form a differential amplifier circuit, and the standard voltage for 33-1/3 or 45 rpm rotation is applied to the base of  $Q_{15}$ . It follows that so long as the rotor is

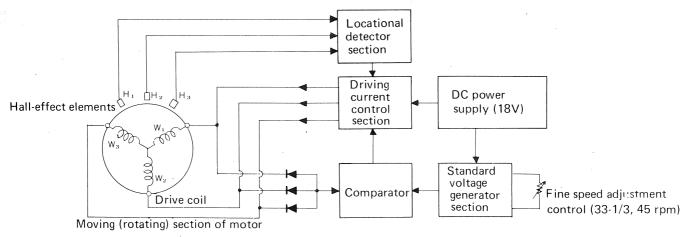


Fig. 2: Block Diagram of the PXM-020

turning at the correct speed (revs), this circuit is balanced. If for any reason the speed of ratation of the rotor exceeds the proper value, the voltage generated in each drive coil will increase. increase.

This causes the potential on the base of  $Q_{14}$  to drop, and the potential on the bases of  $Q_{18}$  and  $Q_{13}$  rises. As the potential on the base of  $Q_{13}$  rises, the collector current drops and this reduces the potential on the base(s) of  $Q_3$  ( $Q_7$ ,  $Q_{11}$ ). This results in a reduction in the current flowing through  $Q_2$  ( $Q_6$ ,  $Q_{10}$ ), and a rise in the potential on the base(s) of  $Q_4$  ( $Q_8$ ,  $Q_{12}$ ), so that the collector current(s) of  $Q_4$  ( $Q_8$ ,  $Q_{12}$ ) drop. If the collector current drops, the field strength of the drive coil also drops, the rotor speed drops, and it returns to the correct speed of rotation.

On the other hand, if the rate of rotation of the rotor drops below its proper value, the process is precisely the reverse of the above: the voltage across each drive coil drops, and the base potential of  $Q_{14}$  rises. This causes the collector current of  $Q_{13}$  to increase, and the current(s) through  $Q_1$  ( $Q_7$ ,  $Q_{11}$ ) and  $Q_2$  ( $Q_6$ ,  $Q_{10}$ ) also rise. As the collector current(s) of  $Q_2$  ( $Q_6$ ,  $Q_{10}$ ) increase, the base potential(s) on  $Q_4$  ( $Q_8$ ,  $Q_{12}$ ) drop, the collector current(s) rise, the magnetic field strength of the drive coil(s) increases, and the rotor speed increases to the correct value.

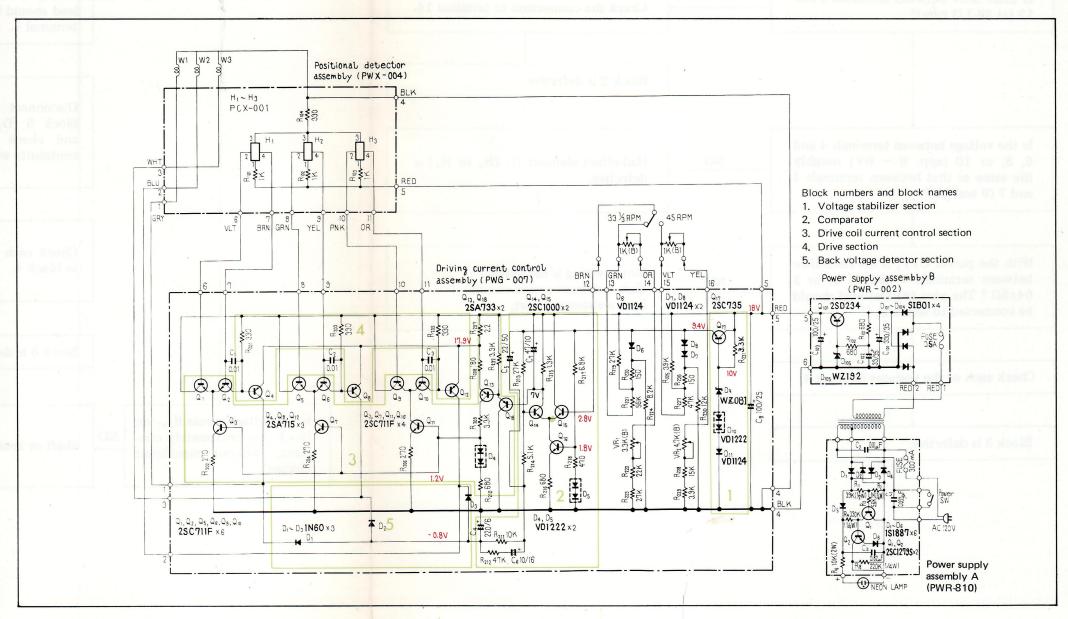
# 7.4 TEMPERATURE COMPENSATION

The section which corrects the speed of rotation of the motor as the ambient temperature changes comprises varistors ( $D_4$ ,  $D_5$ ,  $D_6$ ,  $D_7$ ,  $D_8$ ,  $D_{10}$ ,  $D_{11}$ ) to achieve temperature compensation.

- D<sub>4</sub> compensates Q<sub>3</sub>, Q<sub>7</sub>, and Q<sub>11</sub>. If D<sub>4</sub> were not provided, an increase in temperature would be accompanied by a drop in the V<sub>B-E</sub> of Q<sub>3</sub>, Q<sub>7</sub>, and Q<sub>11</sub>, and an increase in the collector currents. This would result in a drop in the base potentials of Q<sub>4</sub>, Q<sub>8</sub>, and Q<sub>12</sub>, and an increase in their collector currents with, in turn a higher current through the drive coils and a corresponding increase in the speed of revolution. The temperature coefficient of D<sub>4</sub> (VD1222) is −3.6mV/°C, which ensures that the bases of Q<sub>3</sub>, Q<sub>7</sub>, and Q<sub>11</sub> do not drop in potential, so that the motor speed will not increase.
- $D_5$  compensates  $Q_{16}$ . If  $D_5$  were not provided, an increase in temperature would cause an increase in  $Q_{16}$  collector current, and a corresponding increase in  $Q_{14}$ ,  $Q_{15}$ ,  $Q_{18}$ ,  $Q_{13}$ , with a rise in the base potential of  $Q_3$ ,  $Q_7$ , and  $Q_{11}$ , and an increase in the speed of the motor.

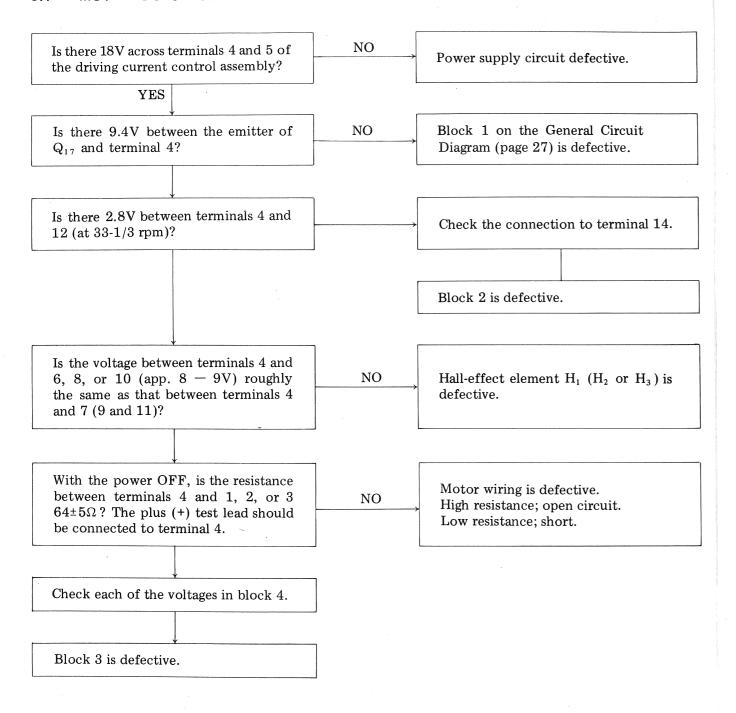
- D<sub>6</sub>, D<sub>7</sub> and D<sub>8</sub> provide the temperature compensation for rotor magnetism. Magnetic field strength drops at -0.18%/°C with an increase in temperature. For this reason, if D<sub>6</sub>, D<sub>7</sub> and D<sub>8</sub> are not provided, even at the proper rate of rotation, the voltage generated in the drive coils would drop, because the comparator would indicate that the speed has dropped, and so the motor speed would. D<sub>6</sub> (33-1/3) D<sub>7</sub> and D<sub>8</sub> (45 rpm) raise the potential at the base of Q<sub>15</sub> as the temperature rises, preserving the balance of Q<sub>14</sub> and Q<sub>15</sub>, and maintaining proper speed.
- D<sub>10</sub> and D<sub>11</sub> compensate D<sub>9</sub> and Q<sub>17</sub>. D<sub>9</sub> (WZ081) is a zener diode. The zener temperature coefficient is 0.05%/° C. If D<sub>10</sub> and D<sub>11</sub> are not provided, as the temperature rises the zener potential will rise, so that the V<sub>B</sub>-E of Q<sub>17</sub> drops, raising the emitter potential (the standard voltage) of Q<sub>17</sub>. If the standard voltage rises, the speed of the motor also rises. This is the reason for the compensation by D<sub>10</sub> and D<sub>11</sub> for the rise in D<sub>9</sub> zener potential and the drop in V<sub>B</sub>-E potential of Q<sub>17</sub>. The temperature coefficient of D<sub>11</sub> (VD1124) is −1.9mV/° C.

# **CONNECTION DIAGRAM**

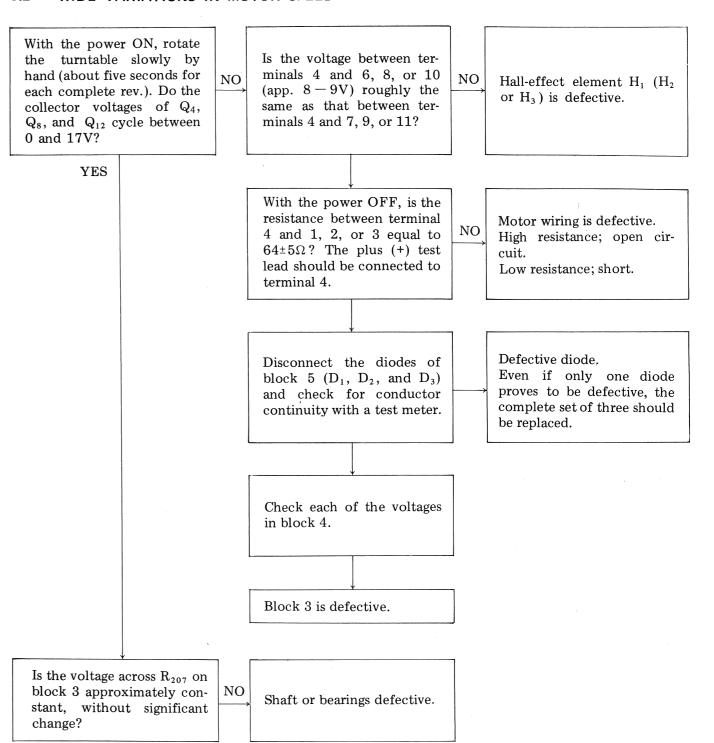


# 8. TROUBLE SHOOTING CHART

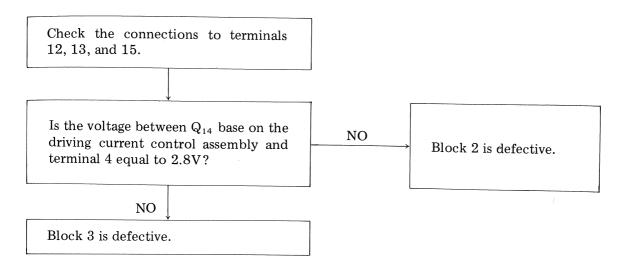
# 8.1 MOTOR DOES NOT TURN



# 8.2 WIDE VARIATIONS IN MOTOR SPEED



# 8.3 MOTOR RACES



# 9. ADJUSTMENT

# 9.1 MOTOR SPEED

When it proves impossible to adjust the fine speed controls to give the correct speeds, the motor may be adjusted as follows.

- 1. Set the fine speed adjustment controls on the stereo turntable to their mechanical centers (approx. in the middle).
- 2. Separate volume-type controls are accessible on the motor back plate for both 33-1/3 and 45 rpm adjustment. Use a small screwdriver to turn these preset controls to give synchronization as indicated by the stroboscopic speed indicator on the record player.
- 3. When even turning the controls fails to give the required adjustment, refer to Connection diagram on page 6, and change  $R_{223}$  (33-1/3 rpm) and  $R_{229}$  (45 rpm) within the range  $1.5 \mathrm{k}\Omega$  to  $5.6 \mathrm{k}\Omega$  before repeating the adjustment.

# 9.2 ARM ELEVATION

Tonearm elevation is operated by a cable release. If the release stretches due to aging or other reasons, loosen EV guide screw (Fig. 1) and adjust cable release anchor condition. Perform this adjustment with tonearm elevation in DOWN setting. As adjustment standard, EV lever unit (Fig. 2) should tightly contact straight line portion of EV cam. Be sure to confirm operation after adjusting.

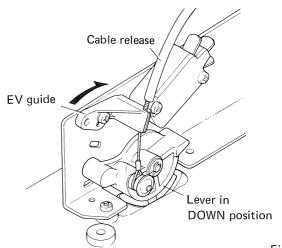


Fig. 1

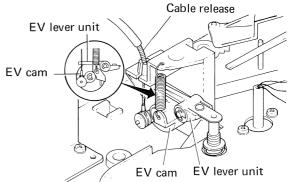


Fig. 2

# 10. PARTS LIST OF EXPLODED VIEW

Parts No.	Parts Name
KAH-007	Ring
KBA-044	Screw
KBA-045	Screw
KDG-011	AC Power cord
KEX-002	Screwdriver
REX-002	Sciewariver
KKC-011	Terminal
KKC-021	Terminal
KLA-438	Lateral weight
RNK-055	45 rpm Adaptor
KNK-403	Packing stopper
KSF-016	Micro switch
PAD-009	Antiskating knob
PAN-024	Operation panel
PBA-006	Screw
PBA-008	Screw
	331300
PBA-011	Screw
PBH-023	AS Spring
PBH-028	Spring
PBH-029	Spring
PBH-086	Float spring F
PBH-087	Float spring G
PBH-505	Spring
PBH-506	EV Spring
PBN-501	Nut
PCS-005	Variable resistor
1 00 000	Variable resistor
PEA-010	Rubber mat assembly
PEB-009	Rubber cushion
PEB-010	Rubber grommet A
PEB-011	Rubber grommet B
PEB-034	Rubber mat
PEC-012	Overhoos
PEC-012	Overhang gauge Cushion
PED-004	Output cord
PEF-001	Steel ball
PEL-009	Neon lamp
000 000 000 00	1
PHC-016	Turntable pad
PHC-017	Upper board
PHP-023	Side pad
PLA-071	Arm rest stand
PLA-563	Sub weight
PLA-567	Screw
PLA-586	Lateral bar
PLA-620	Shaft
PMM-042	Cabinet
PMS-003	Bottom plate
1 10000	Bottom plate
PNB-519	Washer
PNR-022	Turntable platter
PNT-002	Rubber bush
PNW-011	Thrust catch
PNW-073	Head shell stand

Parts No.	Parts Name
PNW-084	Main panel
PNW-088	Arm spacer
PNW-091	Lever
PNW-092	Wire guide
PNW-133	SP Holder B
PNW-151	SP Holder C
PNW-169	SP Holder D
PNW-176	PU Plate
PNW-542	Arm base
PNW-544	EV Cam
PNW-545	Bias lever
PNW-546	AS Lever
PNW-547	AS Cam shaft
PPD-539	Tonearm assembly
PRB-023	Operating instruction
	,
PRM-011	Strobo
PTT-008	Power transformer
PWG-007	Control assembly
PWR-002	Power supply assembly
PWX-003	Positional detector
PX A-103	Arm rest unit
PX A-104	Arm rest assembly
PXA-106	Strobo case assembly
PXA-107	Function mech assembly
PX A-109	Foot assembly
PX A-117	Pottom plata assembly
PXA-117	Bottom plate assembly Foot assembly
PX A-159	Dust cover assembly
PXA-598	Elevation arm assembly
PXA-599	Counterweight
	4
PXA-622	Antiskating assembly
PXM-020	Motor
RXT-034	Angle
PXT-035	Function lever
PXT-036	Button unit
PXT-517	EV Lever
PXT-518	Wire
B11-657	Screw
B23-642	Washer
B32-056	Strain relief
B71-652	Nut
H56-603	Vinyl cover
1100-000	Villyl Cover

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