42-2970

REALISTIC

Service Manual

LAB-500

QUARTZ LOCK DIRECT-DRIVE TURNTABLE

WITH FULL-AUTOMATIC SYSTEM CATALOG NUMBER:42-2970



8A8 003091 Purchased 7/21/79

CUSTOM MANUFACTURED FOR RADIO SHACK & A DIVISION OF TANDY CORPORATION

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TECHNICAL SPECIFICATIONS

Description	Condition	Nominal	Limit
Туре	2*	2-speed QUARTZ Locked DIRECT drive, full automation system	
Platter		Aluminum alloy die-cast, 12-5/8" (320 mm) outer diameter, 3.1 lbs	
Motor		(1.4 kg) 12-pole brushless DC QUARTZ-locked servo-type	
Speed	Measured with 3kHz reference signal	2-speed: 33-1/3 rpm 45 rpm	34.0 ~ 32.7 44.1 ~ 45.9
Speed Accuracy S/N	Measured at 1 kHz, 5 cm/sec	0.0005% after 1.5 second Better than 55 dB (IEC B)	
Rumble (DIN B) Wow & Flutter Tone arm Head shell & Cartridge	Measured at 3kHz	70dB Less than 0.04% (WRMS) Static balance type, tubular	0.06%(WRMS)
Overall length Effective length Overhang Adjustable force range (scale)		Plug-in type 12-3/8" (315 mm) 8-15/16" (227 mm) 9/16" (14mm) 0 to 3g/one of the scale ring (directly readable in 0.1g steps)	
Acceptable cattridge weight Effective arm mass Resonance of arm and		4.5 to 10g 19.8g 7.5Hz	
and Cartridge Tracking error		+2° 54″	
Cartridge Frequency response	,	-1° 30" Realistic/Shure Model R-9000ELWS 20 \sim 20,000 Hz	
Output voltage Channel difference		3. mV at 1kHz, 50 mm/sec 2dB at 1kHz	
Channel separation Tracking force Stylus tip Measured compliance Nominal DC resistance Nominal inductance Recommendeb termination		23 dB at 1 kHz $3/4 \sim 1-1/2$ grams 0.7×0.2 mil diamond stylus 30×10^{-6} cm/dyne 1550 ohms typical 650 mili henries 47 Kohms, 450 pF	
Stylus pullout force Cartridge weight Power source		6-25oz(170-700g) 10.7 grams 120 volts, 60 Hz AC 220/240 volts, 50 Hz for European/	
Power consumption Dimension Weight ACCESSORIES		Australian Models 8 watts 6-1/8"(H) × 18-7/8"(W) × 15-3/16"(D) 22 lbs (10 kg) Counterweight 45 RPM adapter	

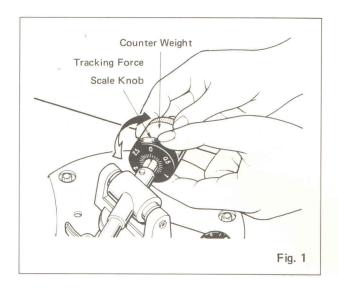
NOTE: Nominal Specs represent the design specs; all units should be able to approximate these — some will exceed and some may drop slightly below these specs. Limit Specs represent the absolute worst condition which still might be considered acceptable; in no case should a unit perform to less than within any Limit Spec.

ADJUSTMENTS

1. Tracking Force Adjustment

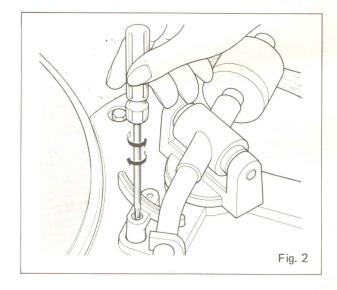
Caution: During adjustment, be careful not to let the stylus tip touch the Plate or Turntable Mat.

- After removing the Stylus Cover from the Cartridge, bring the Tone Arm to a position halfway between the Arm Rest and Plate.
- (2) Turn the Counterweight to balance the Tone Arm, and let the Tone Arm rest on the Arm Rest. (Fig. 1)
- (3) Fix the Counterweight so that it will not move. Turn just the Tracking Force Scale Knob to set "0" to the Tone Arm's index mark.
- (4) Turn the Counterweight gently counterclockwise to set the Knob's scale to the tracking force specified for the cartridge. The recommended tracking force for the cartridge supplied is 1-1/2g.



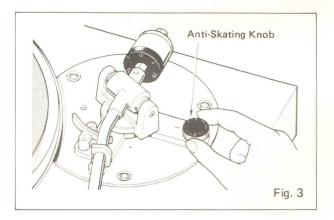
2. Stylus Tip Height Adjustment

- (1) The stylus tip height decreases as the Stylus Tip Height Adjust Screw is turned clockwise and increases when turned counterclockwise. (Fig. 2)
- (2) The optimal stylus tip height is 9 mm measured from the Turntable Mat to the Stylus Tip (when CUE is in UP position).



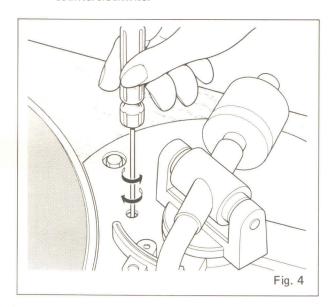
3. Adjustment of Antiskate Mechanism

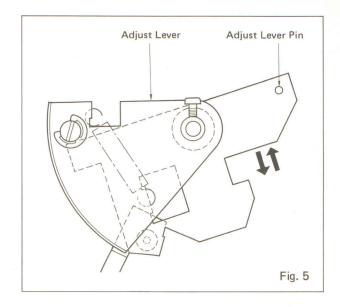
In tone arms having an offset angle, a force is generated during record playing that causes the stylus tip to be pulled toward the record center, resulting in improper tracking and/or jumping of stylus. The antiskate mechanism applies a force that corresponds to the tracking force. When the tracking force is 1-1/2g, the scale of the antiskate knob should also be set to 1-1/2. (Fig. 3)



4. LEAD-IN Adjustment

- If at LEAD-IN, the stylus tip descends outside the lead-in groove, correct this by turning the LEAD-IN Adjust Screw clockwise. (See Figs. 4 & 5.)
- (2) If at LEAD-IN, the stylus tip descends to a position inside the proper LEAD-IN position, correct by turning the Lead-In Adjust Screw counterclockwise.

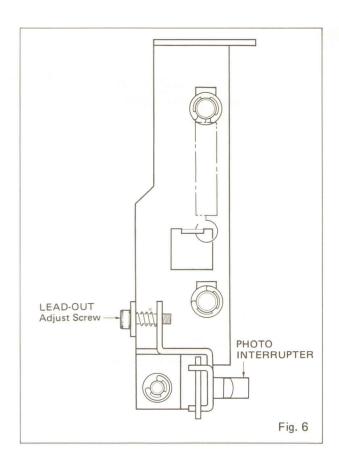




5. LEAD-OUT Adjustment

If the Tone Arm does not lift off when the stylus tracks in the "Lead-Out" groove, or has lifted off before the lead-out groove, adjust as follows:

 Turn Lead-Out Adjust Screw to "Lead-Out" sooner; turn counterclockwise to lead-out later. (Fig. 6)

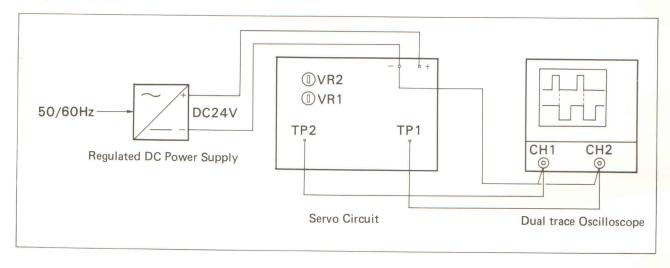


6. Phase Adjustment of Servo Circuit

IMPORTANT: For adjusting, a dual-trace oscilloscope is required. If you don't have one, do NOT adjust the VR's but replace entire Servo PCB assy.

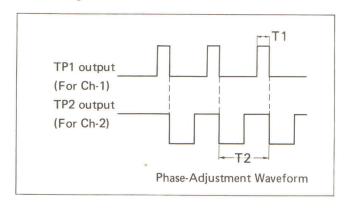
- (1) Test instruments required
 - 1) Dual trace Oscilloscope
 - 24V DC Power Supply
 When adjusting only the servo circuit board assembly, a regulated DC power supply is needed.

(2) Connection



(3) Adjustment

 Set Motor speed to 45 rpm and apply power. Then, by turning VR1, synchronize the negative-edge phase as shown in the drawing.



T1...... $0.8 \sim 1.2 ms$ T2..... 20ms at 33-1/3 rpm

14.814ms at 45 rpm

 Next, set speed to 33-1/2 rpm and adjust VR2 in the same manner.

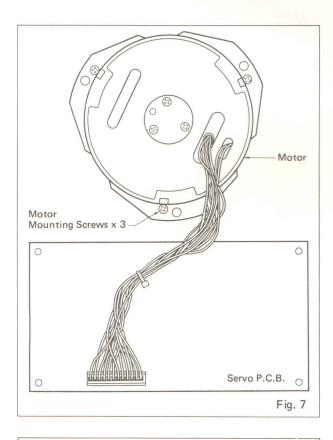
CAUTION: (1) Always perform 45 rpm adjustment first.

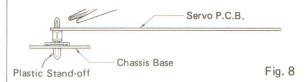
(2) The adjustment must be very precise.

DISASSEMBLY INSTRUCTIONS

1. Removal of Motor

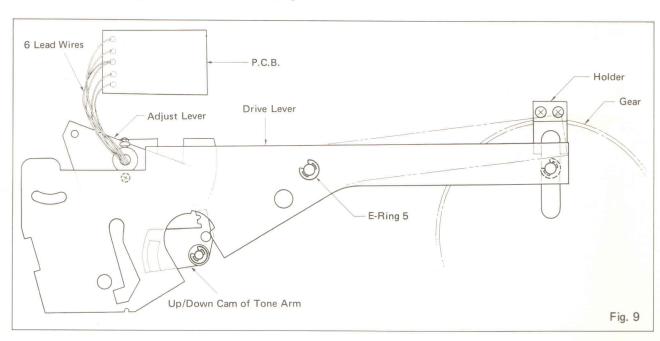
- (1) To Remove Rear Cover.
 - Turn the set upside down and remove the rear cover screws (ten 3.1 \times 20 screws and two M3 \times 8 screws). Take off Rear Cover.
- (2) Remove the three motor screws (M3 \times 8). (Fig. 7)
- (3) If only the Motor is to be removed, disconnect plug from the Servo Circuit Board.
- (4) To remove the Servo Circuit Board together with the Motor, pinch the end of the plastic standoffs with pliers (Fig. 8) and lift off the Servo Circuit Board.



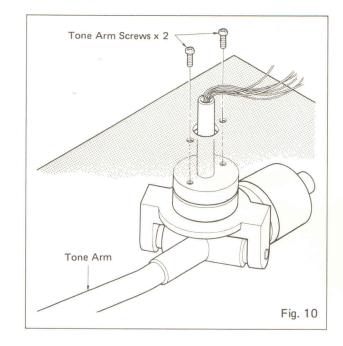


2. Removal of Tone Arm

- (1) Remove Rear Cover.
- (2) Turn the Center Shaft of the Start/Stop Lever, until the pin on the forward end of the Drive Lever reaches a position off the Holder. (Fig. 9)



- (3) Remove Drive Lever.
- (4) Unsolder the output leads of the Tone Arm.
- (5) Remove the Up/Down Cam of the Tone Arm (E-Ring).
- (6) Remove the Arm Lever (Adjust Lever).
- (7) Remove two screws (M3 x 5) from the Tone Arm and lift off the Tone Arm. (Fig. 10)



3. Removal of Arm Lifter

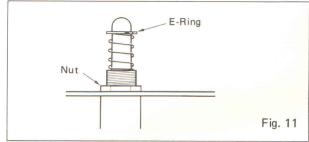
- (1) Take off Rear Cover.
- (2) Remove the nut shown in Fig. 11.
 Remove the Shaft Assy of the Arm Lifter.

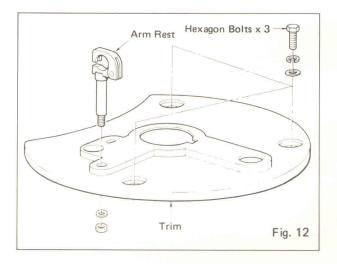


After the Arm Lifter has been removed as described above, remove three hexagon bolts (M3 x 12).

The Trim can now be removed along with the Arm Rest.

Note: Since the Trim is glued in place, it can not be removed just by removing the hexagon bolts.

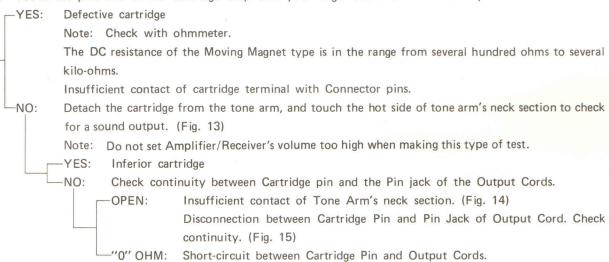




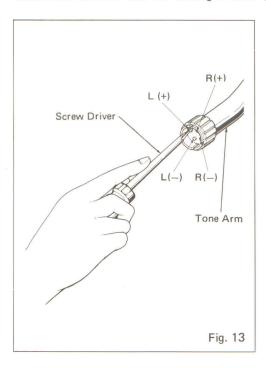
TROUBLESHOOTING

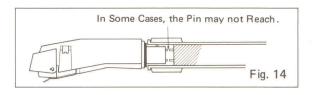
I. No Sound is Heard.

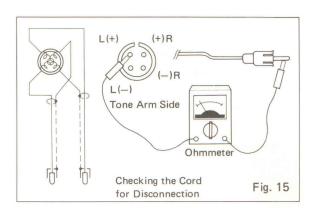
1. Touch the plus side of the Cartridge Chip with your finger and check whether any sound is heard.



2. Check and confirm that the muting circuits (Microswitches S102 and 104) are operating normally.







II. Distorted Sound

[Possible Causes]

- (a) Inadequate tracking force
- (b) Dust on stylus tip
- (c) Worn stylus tip
- (d) Defective cartridge
- (e) Slanting of head shell. Loosening of neck section of head shell.
- (f) Others

Is the tracking force adequate? Check tracking force and stylus tip. If too light, treble will be distorted. If very light, sound may be intermittent. Are both channels distorted? Is distortion present when tracking the inner-most grooves of the record? YES: - Dust on stylus tip. Distortion is present over the NO: Worn stylus tip. entire record. - Defective cartridge. -YES: Distortion on inner-most grooves -- Recordings which run into extremely only. small inside diameter grooves will distort (this is normal and is the fault of the record). NO: Distortion only on one channel. -Is Turntable leveled and balanced horizontally? Wrong fitting of Head Shell. Is the Arm's bearing operation jerky? -NORMAL: Too strong Antiskating force. Insufficient Antiskating force. Defective Cartridge. Worn stylus. Wrong fitting of Head Shell. Jerky bearing operation ABNORMAL: will cause sound to be weak or distorted. Head Shell is slanted. Turntable is not positioned horizontally.

III. Intermittent Sound

[Possible Causes]

- (a) Interruption of sound when someone walks by the Turntable is caused by a too-light tracking force, or by vibrations that cause the stylus to jump.
- (b) Intermittent Cartridge Coil.
- (c) Intermittent wiring somewhere between Cartridge and Preamplifier's PHONO Terminal Pin Jack, or intermittent short-circuit in that area.
- (d) Insufficient contact, or defective soldering of pin jacks.

When in the PLAY mode, is sound interrupted when someone walks by the Turntable? Sound interruption happens without any relation to someone walking by the Turntable. Are sounds interrupted when the Output Cord (Pin Cord) is moved? YES: Intermittent Output Cord. Defective soldering, or insufficient contact of pin jack. NO: Not related to Output Cord. Is sound interrupted even after the Cartridge has been replaced? -Intermittent Cartridge Coil. Is tracking force too light? YES: When tracking force is too light, the stylus will jump, or sound will be interrupted when someone walks by. Turntable base platform (where mounted) is too soft. When someone passes by, the NO: vibrations cause the stylus to jump and sound to be interrupted.

IV. Up and Down travel of the Tone Arm is Too Fast or Too Slow.

[Possible Cause]

- (a) Leaking oil from elevation mechanism.
- (b) Inadequate tracking force.
- (c) Too weak elevation spring.
- (d) Defective arm lifter mechanism

Operate Arm Lifter to check whether the up and down operations are too fast, or too slow.

- Going-down is too slow:

Too light tracking force, or too weak elevation spring.

Both are too slow:

Leaking oil from elevation mechanism.

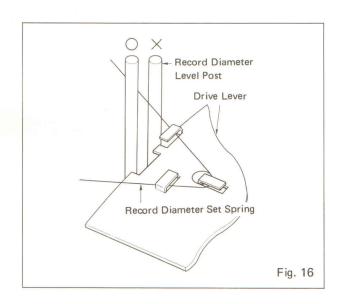
Going-up is too slow:

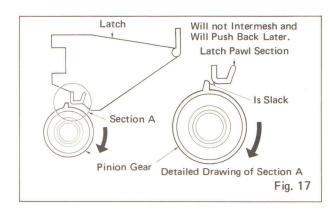
Too heavy tracking force, or too strong elevation spring.

V. Lead-In and Lead-Out Failure

(1) Even after the Tone Arm has descended, the Stylus Tip will not move toward the inner grooves.

When the post of the Record Diameter Lever is disengaged from the Record Diameter Set Spring, the Adjust Lever Pin will stop moving, being prevented by the Record Diameter Lever; this in turn, prevents the Tone Arm from moving. (Fig. 16)





- (2) Even when the Start/Stop Lever is pulled, the Tone Arm will not "Lead-In".
 - If either the Latch or Pawl of the Pinion Gear has worn down (corners no longer sharp), the Latch and Pinion Gear's Pawl will not intermesh. Thus, "Lead-In" and "Return" will not be activated. (Fig. 17)
- (3) The descending position of the Stylus Tip at Lead-In is too far inward, or outward.
 - Adjust, referring to "LEAD-IN Adjustment" instructions.

(4) At Lead-In, the Tone Arm does not move toward the record.
Remove Rear Cover and check to see whether the Lead-In Pawl on the Drive Lever is positioned normally.

-NO: Correct the Pawl's position as shown in Fig. 18.

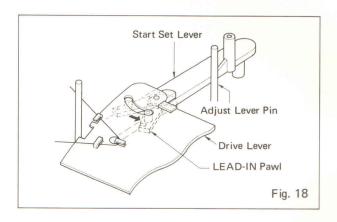
YES:

Push Start/Stop Lever and see if it causes the Pinion Gear and Latch to intermesh.

NO: Defective Latch or Pinion Gear. Replace it.

YES: Is the pin on the Drive Lever located inside the groove of the Main Gear?

NO: The Drive Lever will not operate if its pin is not in the Main Gear's groove (Cam).



(5) Tone Arm does not return when record has finished playing.

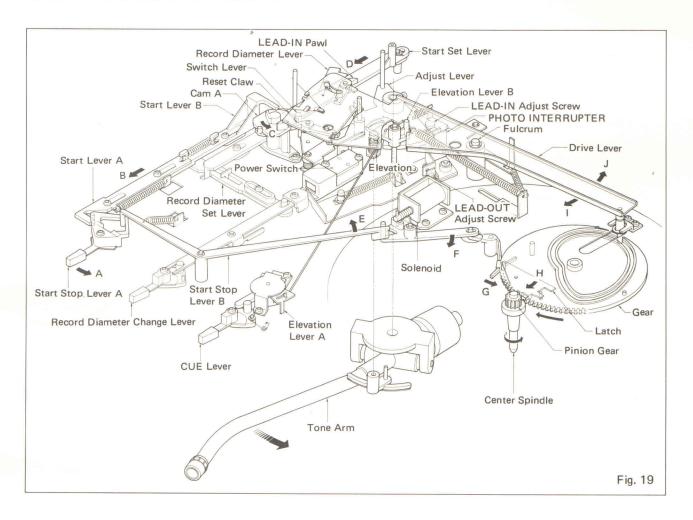
* Adjust, according to "LEAD-OUT Adjustment" instructions.

Is it normal after adjusting the Lead-Out Adjust Screw?

YES: Inadequate adjustment.
NO: Examine circuit, Check

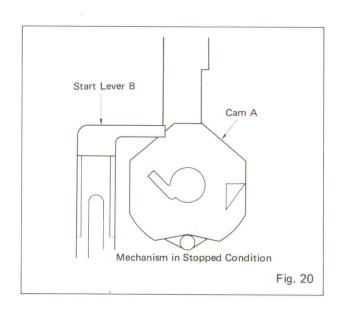
Examine circuit. Check voltage of Photo Interrupter IC.

MECHANISM OPERATING PRINCIPLE



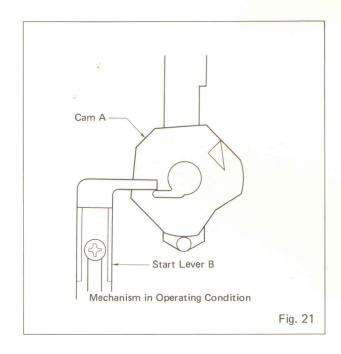
Start-Up of DD Motor and Lead-In of Tone Arm (Refer to Fig. 19)

- (1) When Start/Stop Lever is pushed in the direction of arrow A, Start Levers A and B will move in the direction of arrow B.
- (2) The projecting portion of Cam A is pulled by the forward end of Start Lever B, turning Cam A in the direction of arrow C (moving from the position of Fig. 19 to Fig. 20). The projecting portion of Cam A will become horizontal as a result of this motion.
- (3) At the same time, the Start/Set Lever moves in the direction of arrow D, and maintains the condition shown in Fig. 21.
- (4) Meanwhile, the rotation of Cam A causes the Switch Lever to move along Cam A's surface, switching on the power switch and starting the motor.
- (5) On the other hand, the Start/Stop Lever B will be pushed in the direction of arrow E, so that



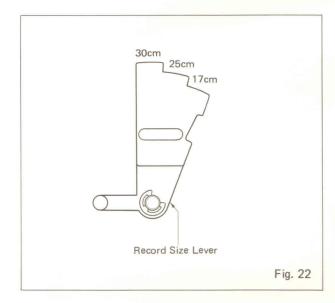
each lever will move as indicated by arrows F and G and push the Latch attached to the Gear toward the center (arrow H).

- (6) As a result, the Latch and Pinion Gear will intermesh, turning the Main Gear.
- (7) The rear side of the Main Gear is grooved, forming a cam. The Pin on the forward end of the Drive Lever is in this groove. When the Main Gear turns, the Cam causes the Drive Lever to make see-saw movements centering around the fulcrum (arrows I and J).
- (8) The Drive Lever will move in the direction of arrow I first, causing the Lead-In Pawl on the Drive Lever to hit the post of the Start Lever and become horizontal.
- (9) Next, as the Drive Lever moves in the direction of arrow J, the Lead-In Pawl will engage Adjust Lever's Post and cause the Tone Arm to move in the direction of the record's inside diameter and the Reset Pawl will restore Cam A to its original condition (RESET).



2. Record Diameter Detection

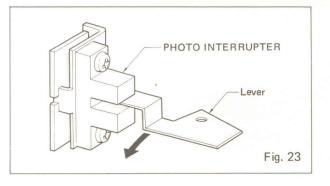
Through record diameter detection, the amount of the Tone Arm's horizontal movement is controlled by the Record Diameter Lever (Fig. 22).



3. Detection of Lead-Out Position

As this Turntable is the position-detecting type (unlike turntables of the speed detecting type) the Tone Arm will be absolutely free of any load during disc playing. Therefore, tone quality is not degraded.

(1) As the Tone Arm moves toward the center and record playing is finished, the lever attached to the Adjust Lever will shield off the Photo Coupler beams (Fig. 23), turning off the Photo



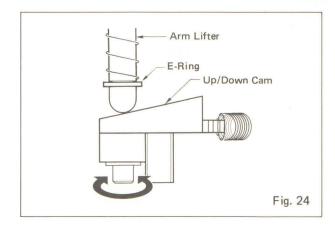
Transistor that is attached to PS-4001 (Photo Interrupter). This causes IC-101 1/4 6 to become LOW level (referred to as "L") and to invert. As its output will become HIGH level (referred to as "H"), the output of IC-101 2/4 3 will become "L", whereas that of IC-101 3/4 11 will become "H".

This causes Q104 to turn on. Q103 will also turn on and cause a voltage to be applied to Solenoid S0-101, actuating it.

- (2) When the Solenoid is actuated, the levers linked with the Solenoid will be pulled in the direction of arrow F shown in Fig. 19. The rest of the operation is the same as that described in Step 1-(4).
- (3) When the Main Gear turns, the Drive Lever will again make see-saw movements, pushing back the post of the Adjust Lever and making the Tone Arm return to the Arm Rest.

4. Up/Down Movements of Tone Arm

- (1) The Up and Down movements of the Arm Lifter is operated by the sloped section of the Lifter Lever, as the Lifter Lever is turned by the see-saw movements of the Drive Lever. (Fig. 24)
- (2) In manual operation, the Up and Down movements of the Arm Lifter are as follows: The operation of the Up/Down Lever activates the Elevation Lever and causes the Lifter Lever to turn.



DESCRIPTION OF SERVO CIRCUIT

This circuit provides constant speed control over the Type-936 motor, by using signals obtained from the frequency generator incorporated in the motor. It utilizes dual feedback control, speed and phase. Inside the motor, the rotor is constructed with 90 magnet poles arranged around the circumference. When the rotor rotates, a sine wave is produced at the frequency generator terminals. The frequency produced is 50 Hz for 33-1/3 rpm and 67.5 Hz for 45 rpm. These signals (we'll call them FG signals) are fed to pins 2 and 3 of IC-1. Pins 1, 2 and 3 of IC-1 together with R4, C3 etc. compose an integrating amplifier, which amplifies the FG signals. These amplified signals are coupled via C-4 to pin 6 of IC-1. Pins 5, 6 and 7 of IC-1 together with R7, etc. compose a waveform shaping circuit, which converts the FG signals into rectangular waves. The rectangular-wave signals are fed to pin 4 of IC-2. IC-2 includes a frequency-to-voltage conversion circuit for speed control, a frequency divider for phase control, a phase comparator, etc.

First, let's take a look at the section associated with speed control. The rectangular-wave FG signals that have been fed to pin 4 are, in turn, fed to pin 7 after being converted into DC voltages that correspond to the frequencies by the frequency-to-voltage conversion circuit. This output will be decreasing when FG signal frequency gets higher, and increasing when the FG frequency signal gets lower. VR1, VR2 together with C5, etc. compose a time-constant circuit that is attached to the frequency-to-voltage conversion circuit. In the time constant circuit, switchover of time constants (frequencies) is made by the 33-1/3-45 rpm changeover switch, X13 and R10. Being connected to terminal 12 of IC-2, the 33-1/3-45 rpm changeover switch also carries out changeover of the frequency divisor in phase control.

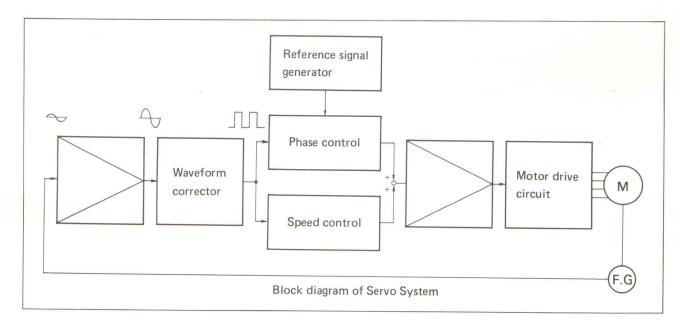
Next, let us study the section associated with phase control. A 9.504 MHz oscillator is provided, which is composed of the crystal oscillator (X'tal) connected to pins 2 and 3, and C12 and C13. This oscillator signal is divided by the frequency divider (190,080 for 33-1/3 rpm and 140,800 for 45 rpm) into FG signal frequencies (50 Hz for 33-1/3 rpm, 67.5 Hz for 45 rpm). The rectangular-wave FG signals that are fed to pin 4 are compared with this reference frequency. The DC voltage that corresponds to the phase difference is output from pin 11. This output will decrease with an increase in phase and increase with a delay in phase.

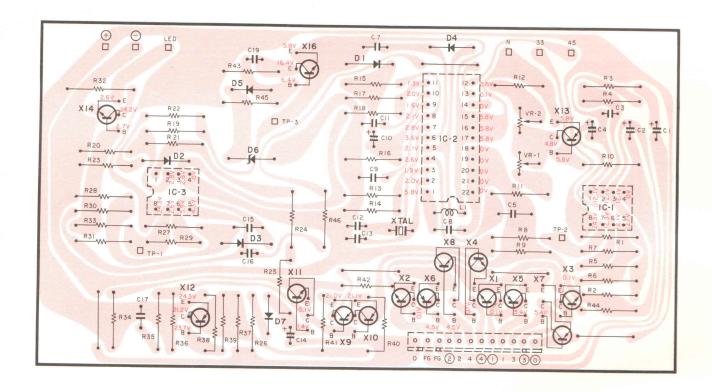
In other words, both the speed control output and the phase control output have the same polarity (output drops with an increase in the motor's speed, and increases with decrease of motor speed). Both output signals are added by way of R13 and R18 and are fed to pin 3 of IC-3. Pins 1, 2 and 3 of IC-3 together with R19, R20 and R21 form a linear amplifier, which amplifies the control signals fed out from IC-2, and then adds them into the first stage (X11) of the motor drive circuit. The motor drive circuit (which uses X11 for its first stage) is connected to the motor's drive coil via connector terminals 4, 7, 8 and 11. The motor stator contains 48 coils wound on 24 slots and two Hall Effect elements. The inside wall of the rotor magnet has 12 poles and when it rotates, the changing magnetic polarity affects the Hall Elements to supply information for the electronics circuit to change phase and magnitude of current through each coil as necessary for sustaining the rotation. (Thus, the Hall Effect devices become the commutator for the Motor.) The rotating action force has 4 phases of 12 poles. This 4-phase drive coil generates a turning moment, current-driven by X1, X2, X3 and X4. Connector terminals 5, 6, 9 and 10 feed X5, X6, X7 and X8 the output signals from the Hall elements incorporated in the Motor. These signals, the phases of which are 90° apart, are used to cause X5, X6, X7 and X8 to perform switching operations according to the rotary direction of the motor. This, in turn, will cause the drive transistors, X1, X2, X3 and X4 to carry out successive switching operations, and these provide signals for the drive coil. Transistors X9, X10, etc. serve the function of varying the current that is supplied to transistors X5, X6 and X7 according to the control signals that are fed to the base of X11. Stable Motor speed is assured by this drive circuit, whose function consists of detecting the motor coil's drive current (by means of R44, the emitter resistor common to X1, X2, X3 and X4) and of effecting negative feedback of the detected current to the emitter of X11.

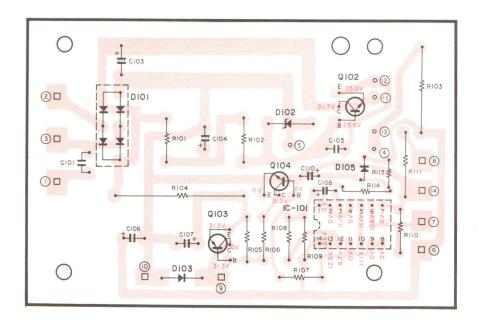
The following gives a brief description of the operations of the servo system:

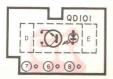
Let's assume, for example, that a load torque has been applied that will cause a drop in the Motor's speed. This will cause the FG signal frequency to drop, and the level of the control output signal from IC-2 to rise. These output signals of increased levels are first

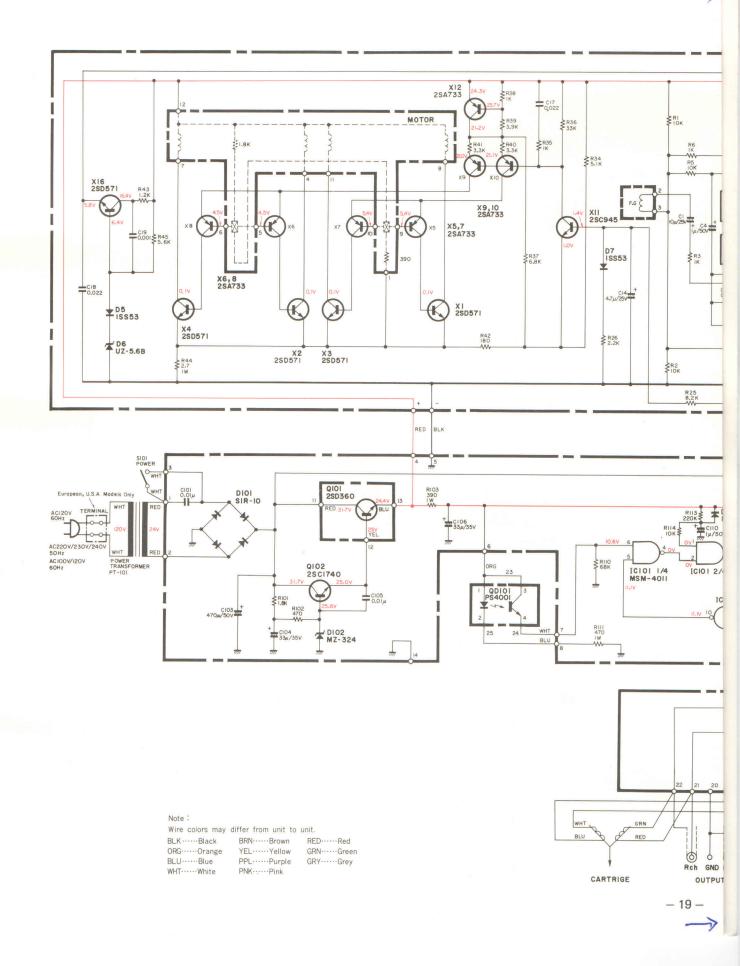
amplified by IC-3 and then applied to the base of the first stage (X11) of the drive circuit. This will cause the current that flows through the drive coil to increase and the speed of the motor to increase as well. As a result, the motor's speed will be maintained constant.



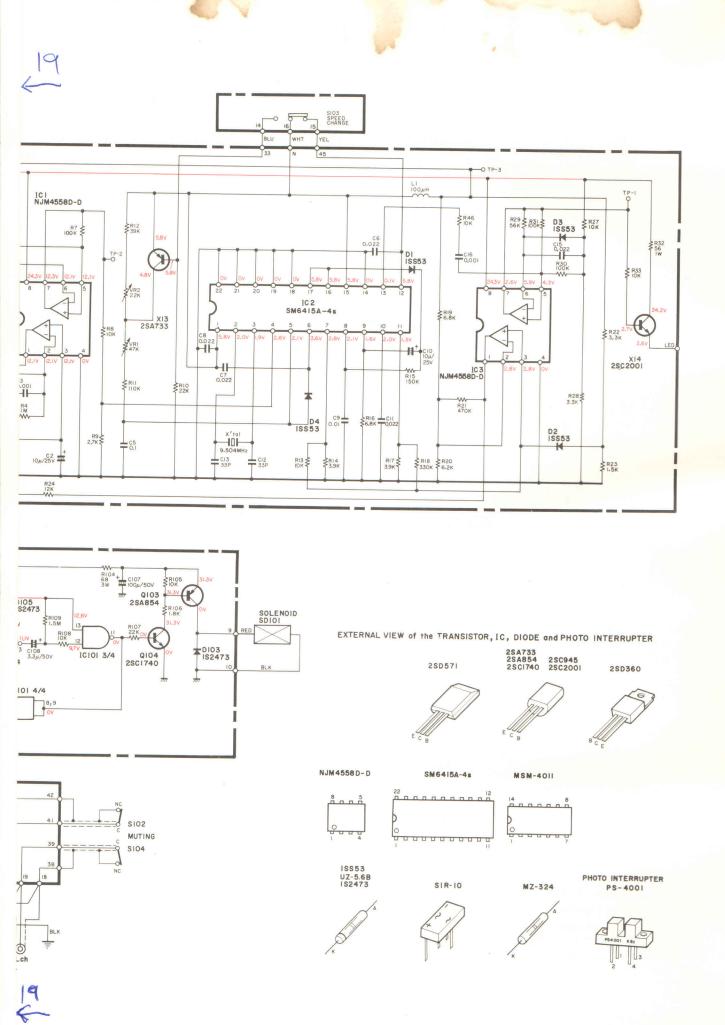


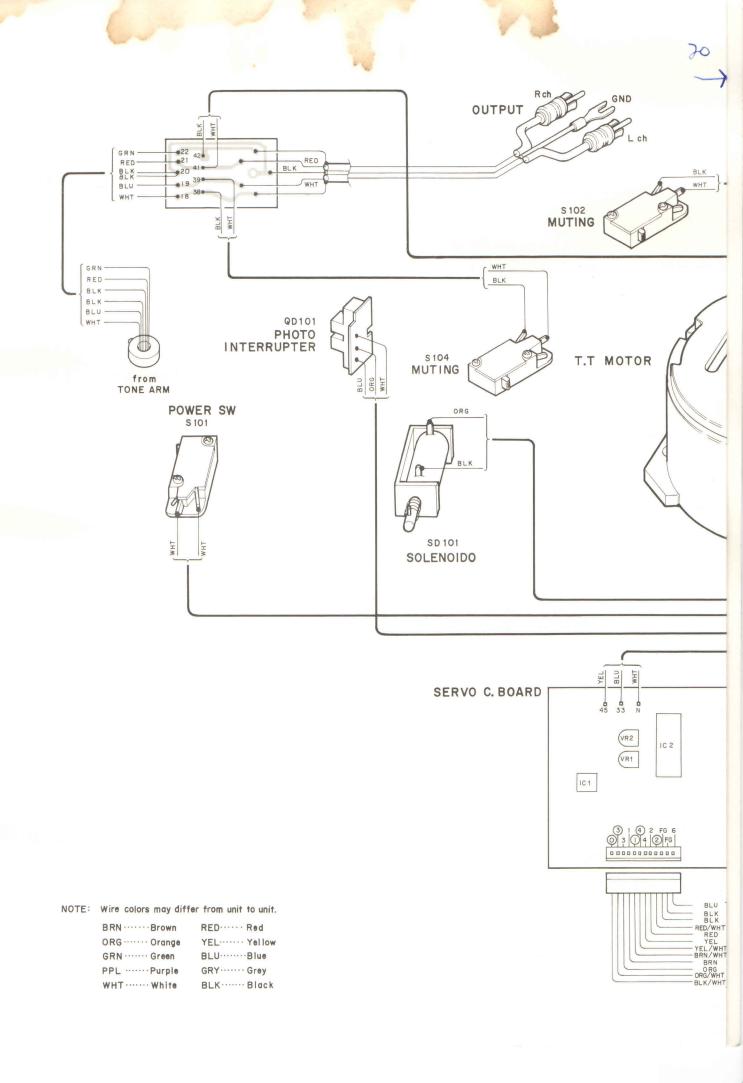


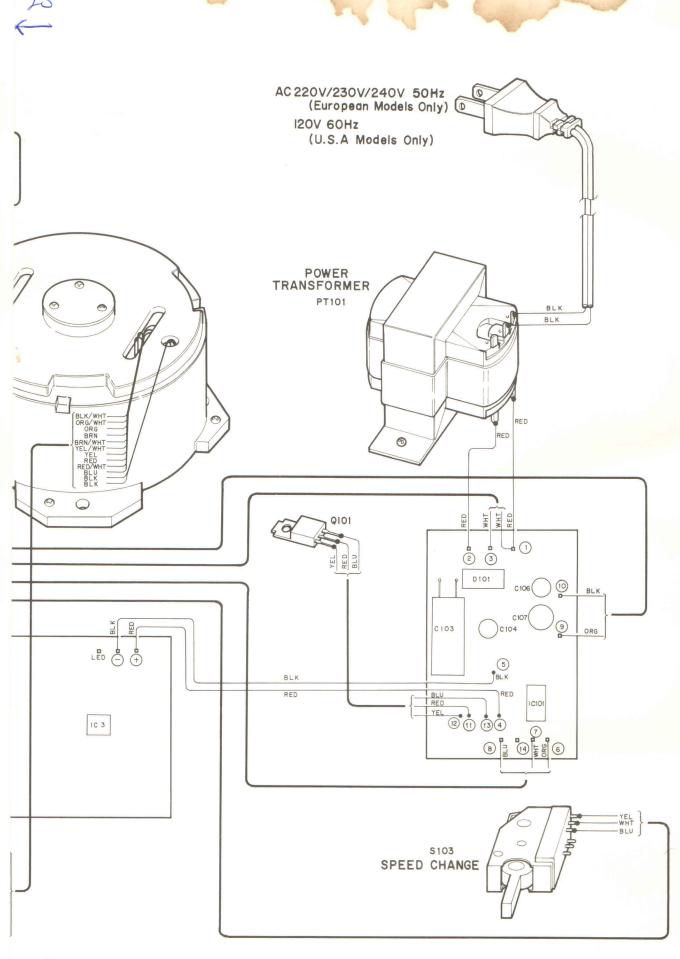


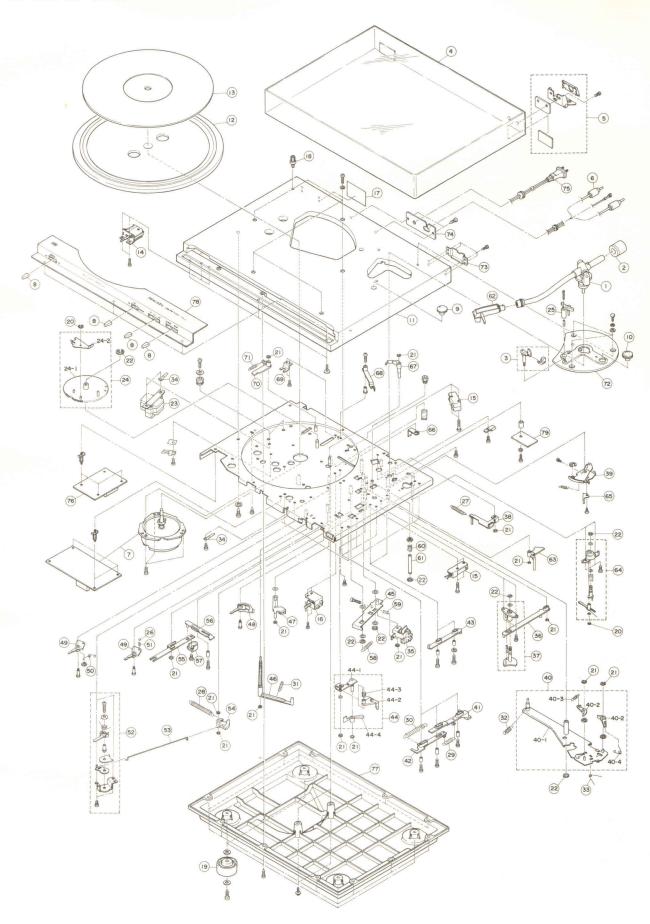


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PARTS LIST

Ref. No.	Descriptio	n	RS. No.	Mfr. No.
C1	Capacitor	10μF 25V		
C2	Capacitor	10μF 25V		
C3	Capacitor	0.001 µF		
C4	Capacitor	1μF 50V		
C5	Capacitor	O.1μF		
C6	Capacitor	0.022μF		
C7	Capacitor	0.022 <i>µ</i> F		
C8	Capacitor	0.022 <i>µ</i> F		
C9	Capacitor	0.01μF		
C10	Capacitor	10μF 25V		
C11	Capacitor	0.022μF		
C12	Capacitor	33pF		
C13	Capacitor	33pF		
C14	Capacitor	4.7μF 25V		
C15	Capacitor	0.022μF		
C16	Capacitor	0.001μF		
C17	Capacitor	0.022μF		
C18	Capacitor	0.022μF		
C19	Capacitor	0.001μF		
C101	Capacitor-ceramic	0.01μF 50V		U140S005H2
C103	Capacitor-electrolytic	470μF 50V		U182S021H7
C104	Capacitor-electrolytic	33μF 50V		U182S021H6
C105	Capacitor-ceramic	0.01μF 50V		U140S005H2
C106	Capacitor-electrolytic	33μ F $35V$		U182S021H6
C107	Capacitor-electrolytic	100μF 50V		U182S021H7
C108	Capacitor-electrolytic	$3.3\mu F$ 50V		U182S031H4
C110	Capacitor-electroytic	1μ50V		U182S033H4
D1	Diode	1SS53	DX-0322	M07314320
D2	Diode	1SS53	DX-0322	M07314320
D3	Diode	1SS53	DX-0322	M07314320
D4	Diode	1SS53	DX-0322	M07314320
D5	Diode	1SS53	DX-0322	M07314320
D6	Diode	UZ-5.6B	DX-1053	M07314321
D7	Diode	1SS53	DX-0322	M07314320
D101	Diode	SIR10	DX-1168	M07151320
D102	Diode	MZ324	DX-1169	M07288320
D103	Diode	1S2473	DX-0299	M07060320

Ref. No.	Descrip	tion	RS. No.	Mfr. No.
D105	Diode	1S2473	DX-0249	M07060320
IC1	IC	NJM4558DD	MX-3449	M07314343
IC2	IC	SM6415-4S	MX-3724	M07314344
IC3	IC	NJM4558DD	MX-3449	M07314343
IC101	IC	MSM4011	MX-3725	M07297343
L1	Coil	100μΗ		
Q101	Transistor	2SD360		M05079311
Q102	Transistor	2SC1740		M05104313
Q103	Transistor	2SA854		M07137308
Q104	Transistor	2SC1740		M05104313
R1	Resistor-carbon	10Kohm		
R2	Resistor-carbon	10Kohm		
R3	Resistor-carbon	1Kohm		
R4	Resistor-carbon	1Mohm		
R5	Resistor-carbon	10Kohm		
R6	Resistor-carbon	1Kohm		
R7	Resistor-carbon	100Kohm		
R8	Resistor-carbon	10Kohm		
R9	Resistor-carbon	2.7Kohm		
R10	Resistor-carbon	22Kohm		
R11	Resistor-carbon	110Kohm		
R12	Resistor-carbon	39Kohm		
R13	Resistor-carbon	10Kohm		
R14	Resistor-carbon	3.9Kohm		
R15	Resistor-carbon	150Kohm		
R16	Resistor-carbon	6.8Kohm		
R17	Resistor-carbon	3.9Kohm		
R18	Resistor-carbon	330Kohm		
R19	Resistor-carbon	6.8Kohm		
R20	Resistor-carbon	6.2Kohm		
R21	Resistor-carbon	470Kohm		
R22	Resistor-carbon	3.3Kohm		
R23	Resistor-carbon	1.5Kohm		
R24	Resistor-carbon	12Kohm		
R25	Resistor-carbon	8.2Kohm		
R26	Resistor-carbon	2.2Kohm		
R27	Resistor-carbon	10Kohm		

Ref. No.	Descrip	tion	RS. No.	Mfr. No.
R28	Resistor-carbon	3.3Kohm		
R29	Resistor-carbon	56Kohm		
R30	Resistor-carbon	100Kohm		
R31	Resistor-carbon	100Kohm		
R32	Resistor-metal	56ohm 1W		
R33	Resistor-carbon	10Kohm		
R34	Resistor-carbon	5.1Kohm		
R35	Resistor-carbon	1Kohm		
R36	Resistor-carbon	33Kohm		
R37	Resistor-carbon	6.8Kohm		
R38	Resistor-carbon	1Kohm		
R39	Resistor-carbon	3.9Kohm		
R40	Resistor-carbon	3.3Kohm		
R41	Resistor-carbon	3.3Kohm		
R42	Resistor-carbon	180ohm		
R43	Resistor-carbon	1.2Kohm		
R44	Resistor-metal	2.7ohm 1W		
R45	Resistor-carbon	5.6Kohm		
R46	Resistor-carbon	10Kohm		
R101	Resistor-carbon	1.8Kohm1/4WJ		U103S014H2
R102	Resistor-carbon	470ohm 1/4W J		U103S014H1
R103	Resistor- metal	390ohm 1W J		U105S005H2
R104	Resistor-metal	68ohm 3W J		U105S002H0
R105	Resistor-carbon	10Kohm 1/4W J		U103S014H3
R106	Resistor-carbon	1.8Kohm &/4W		U103S014H2
R107	Resistor-carbon	22Kohm 1/4W		U103S014H3
R108	Resistor-carbon	10Kohm 1/4W J		U103S014H3
R109	Resistor-carbon	1.5Mohm 1/4W		U103S014H5
R110	Resistor-carbon	68Kohm 1/4W		U103S014H4
R111	Resistor-metal	470ohm 1W J		U105S005H2
R113	Resistor-carbon	220Kohm 1/4W		U103S014H3
R114	Resistor-carbon	10Kohm 1/4W		U103S014H3
VR1	VR-semifixed	47Kohm		
VR2	VR-semifixed	22Kohm		
X1	Transistor	2SD571		M07228303
X2	Transistor	2SD571		M07228303
X3	Transistor	2SD571		M07228303

Ref. No.	Des	cription	RS. No.	Mfr. No.
X4	Transistor	2SD571		M07228303
X5	Transistor	2SA733		M05071301
X6	Transistor	2SA733		M05071311
X7	Transistor	2SA733		M05071311
X8	Transistor	2SA733		M05071311
X9	Transistor	2SA733		M05071311
X10	Transistor	2SA733		M05071311
X11	Transistor	2SC945		M07229304
X12	Transistor	2SA733		M05071311
X13	Transistor	2SA733		M05071311
X14	Transistor	2SC2001		M07314303
X16	Transistor	2SD571		M07228303
X'tal	Crystal	9.5040	MX-2633	M07314310

Ref. No.	Description	RS. No.	Mfr. No.
1	Tonearm	RC-6382	M07314610
2	Counter Weight	RC-8052	M07243649
3	Arm rest assembly	RD-5393	M07150618
4	Dust Cover	Y-1006	M07314690
5	Hinge	RD-5538	M07243125
6	Patch cord	W-2243	M07314445
7	Motor (Servo PCB)	K-4452	M07314637
8	Knob (Play)	K-3176	M07314650
9	Knob (Repeat)	K-3177	M07244650
10	Knob (Anti-skating)	K-3178	M07295651
11	Cabinet assembly	Y-1507	M07314100
12	Plate	RC-4140	M07314601
13	Turn table mat	RC-4141	M07314757
14	Level switch	S-5057	M07244660
15	Micro switch	S-6058	M07243430
16	Solenoid	S-9098	M07314390
17	Name plate	RD-5539	M07314605
18	Pin for 45 adapter	RC-7104	M04142716
19	Leg	F-1135	M07296695
20	E-Ring 2	HE-0004	M07314741
21	E-Ring 3	HE-0008	M07296741

Ref. No.	Description	RS. No.	Mfr. No.
22	E-Ring 4	HE-0010	M07296743
23	Power transformer (USA models only)	TA-0691	M07314549
23	Power transformer (European models only)		M07319549
24	Gear assembly		U530C008G02
24-1	Gear	RD-5537	M07314645
24-2	Latch	RD-5540	M07314646
25	Arm lifter	RC-6381	M07243619
26	Steel board	RD-5541	M07314627
27	Spring	RD-5542	M07314670
28	Spring	RD-5543	M07314671
29	Spring	RD-5544	M07314672
30	Spring	RD-5545	M07314673
31	Spring	RD-5546	M07314674
32	Spring	RD-5547	M07314675
33	Spring	RD-5548	M07314676
34	Clamper		540S005H01
35	PHOTO INTERRUPTER	RD-5550	M07314309
	45 rpm adapter	RC-7099	M07191603
36	45 rpm adapter lever		U525D621H03
37	Cam A assembly		U536D053G0
38	Lever		U525D677G01
39	Adjust lever		U525D639G03
40	Drive lever		U525C020G01
40-1	Lever		U525C019G01
40-2	Lead in claw		U525D620H02
10-2	Reset claw		U525D620H0
40-3	Spring		U570D738H02
10-4	Spring		U570D733H01
1 1	Start lever		U525D622H01
12	Start lever B		U525D623H01
13	Record size set lever B		U525D618H01
14	Switch lever		U525D658G01
14-1	Lever assembly		U525D636G01
14-2	Lever		U525D615H02
14-3	Spring		U570D750H01
14-4	Lever		U525D616H03
1 5	Lever		U525D678G01

Ref. No.	Description	RS. No.	Mfr. No.
46	Start/Stop lever B		U525D614H02
47	Lever		U525D676G01
48	Start/Stop lever A		U525D682G02
49	Record size set lever		U525D681G02
49	CUE lever		U525D681G0
50	Spring		U570D734H01
51	Spring		U570D737H01
52	Elevation lever		U525D640G01
53	Link		U526D177G02
54	Elevation lever		U525D612H02
55	Record size set lever		U525D680G01
56	Record size set lever		U525D619H01
57	Holder		U541D069H01
58	Spring		U570D788H01
59	Spring		U670D787H01
60	Spring		U570D763H02
61	Elevation shaft		U531D265H01
62	Cartridge assembly	R9000ELWS	
63	Record size set lever		U525D617H03
64	Anti-skating lever		U945C003G01
65	Lever		525D670H02
66	Holder		546D121H02
67	Lever		525D696G01
68	Muting lever		525D695G02
69	Holder Z		549D106H01
70	Lever		525D611H02
71	Spring		570D746H04
72	Ornament		703B026H02
73	Holder U		547Y005H01
74	Holder F		544D081H01
75	Power cord (USA models only)		242C777H02
75	Power cord (European models only)		242C800H02
76	PS-PCB		241C520G02
77	Board bottom		700C019G03
78	Panel assembly		712C136G01
79	Muting-PCB		241C508H32

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