

# Service Manual

## Multi Compact Disc Player SL-PD627

**COMPACT**  
**disc**  
DIGITAL AUDIO

**DIGITAL**

**MASH**<sup>\*</sup>  
multi-stage noise shaping

**Colour**

(K)... Black Type

**Area**

Suffix for Model No.	Area	Colour
(P)	U.S.A.	(K)
(PC)	Canada.	



- ※
- Technics (or Panasonic) developed the world's first MASH type DAC and ADC. MASH technology was invented by NTT (LSI Labs).
  - MASH is a trademark of NTT.

**NEW MECHANISM SERIES (RAE0201-1)**

**SPECIFICATIONS**

■ **Audio**

No. of channels	2 (left and right, stereo)
Frequency response	2~20,000 Hz, ±1 dB
Output voltage	2 V (at 0 dB)
Dynamic range	92 dB
S/N ratio	100 dB
Total harmonic distortion	0.009% (1 kHz, 0 dB)
Wow and flutter	Below measurable limit
DA converter	MASH (1 bit)
Output impedance	Approx. 1 kΩ
Load impedance	More than 10 kΩ

■ **Pickup**

**Wavelength** 780 nm

■ **General**

<b>Power consumption</b>	13 W
<b>Power supply</b>	AC 120 V, 60 Hz
<b>Dimensions (W×H×D)</b>	430×130×401 mm (16 <sup>15</sup> / <sub>16</sub> "×5 <sup>1</sup> / <sub>8</sub> "×15 <sup>25</sup> / <sub>32</sub> "
<b>Weight</b>	5.0 kg (11.0 lb.)

**Note:**

Specifications are subject to change without notice. Weight and dimensions are approximate.

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**Technics**

## ■ PRECAUTION OF LASER DIODE

**CAUTION:** This unit utilizes a class 1 laser. Invisible laser radiation is emitted from the optical pickup lens when the unit is turned on:

1. Do not look directly into the pickup lens.
2. Do not use optical instruments to look at the pickup lens.
3. Do not adjust the preset variable resistor on the optical pickup.
4. Do not disassemble the optical pickup unit.
5. If the optical pickup is replaced, use the manufacturer's specified replacement pickup only.
6. Use of control or adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure.

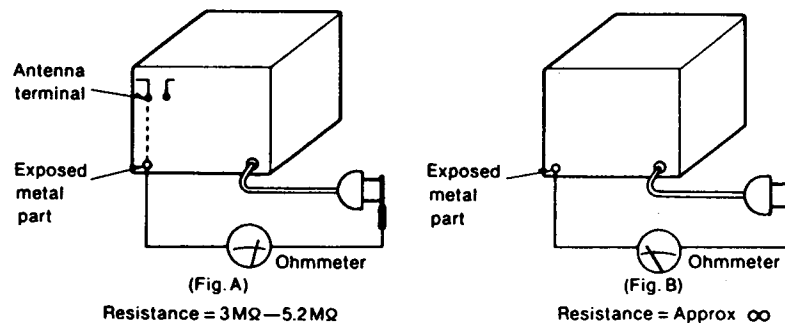
## ■ SAFETY PRECAUTION (This "safety precaution" is applied only in U.S.A.)

1. Before servicing, unplug the power cord to prevent an electric shock.
2. When replacing parts, use only manufacturer's recommended components for safety.
3. Check the condition of the power cord. Replace if wear or damage is evident.
4. After servicing, be sure to restore the lead dress, insulation barriers, insulation papers, shields, etc.
5. Before returning the serviced equipment to the customer, be sure to make the following insulation resistance test to prevent the customer from being exposed to a shock hazard.

### • INSULATION RESISTANCE TEST

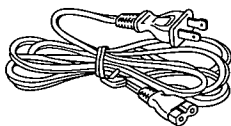
1. Unplug the power cord and short the two prongs of the plug with a jumper wire.
2. Turn on the power switch.
3. Measure the resistance value with ohmmeter between the jumpered AC plug and each exposed metal cabinet part, such as screwheads antenna, control shafts, handle brackets, etc. Equipment with antenna terminals should read between  $3M\Omega$  and  $5.2M\Omega$  to all exposed parts. (Fig. A) Equipment without antenna terminals should read approximately infinity to all exposed parts. (Fig. B)

**Note:** Some exposed parts may be isolated from the chassis by design. These will read infinity.

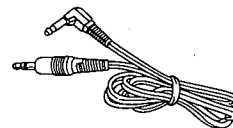


4. If the measurement is outside the specified limits, there is a possibility of a shock hazard. The equipment should be repaired and rechecked before it is returned to the customer.

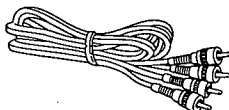
## ■ ACCESSORIES



AC power supply cord ..... 1 pc.  
 [(SJA172-1)..... (P)]  
 [SJA172 ..... (PC)]

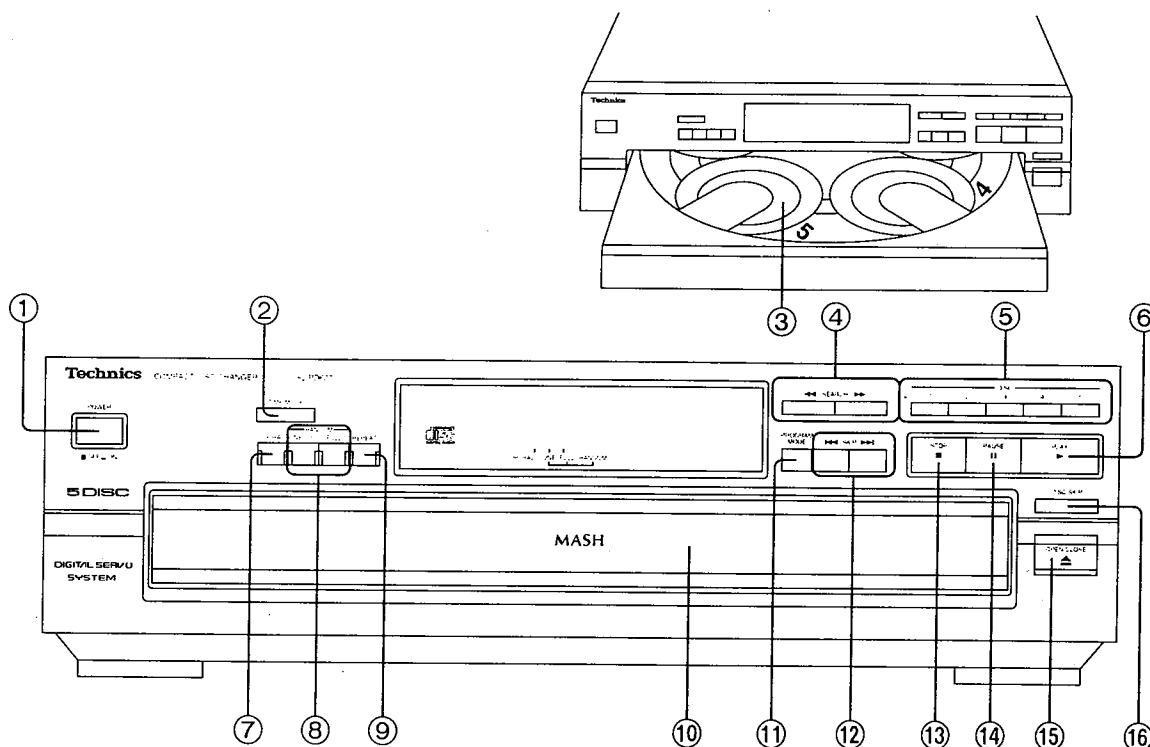


Remote control cable  
 (SJP2257T) ..... 1 pc.



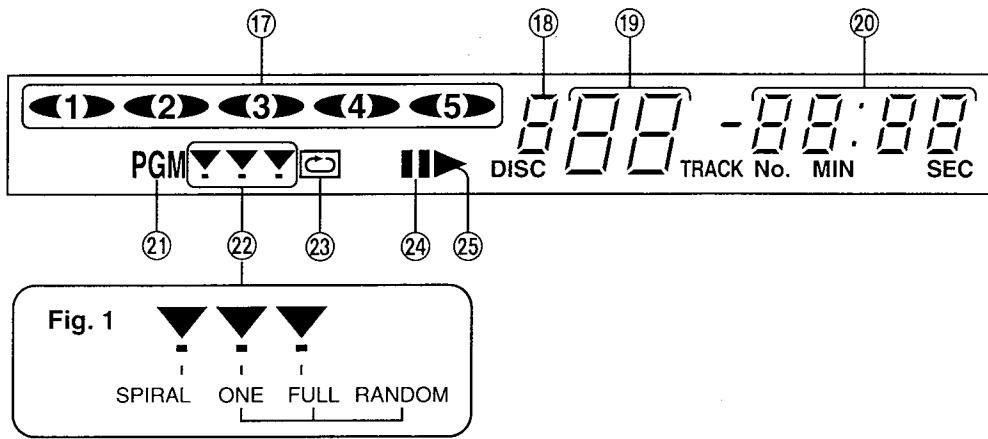
Stereo connection cable  
 (SJP2249-3) ..... 1 pc.

## LOCATION OF CONTROLS AND COMPONENTS



### Control section

- ① **Power switch (POWER)**  
Press (■) to switch the power on.  
Press again (■) to switch the power off.
- ② **Time mode button (TIME MODE)**  
Use to select the desired time mode. Each time you press the button, the display information will change as follows.
  1. Track number and its elapsed play time of the current track.
  2. Track number and remaining time of the current track.
  3. Total track numbers and playing time of the current disc.
  4. Total elapsed play time of the current disc.
- ③ **Disc trays (1-5)**  
You can load up to five discs, one disc per one tray.
- ④ **Search buttons (◀◀ SEARCH ▶▶)**  
Press to move forward and backward through the tracks on the disc.
- ⑤ **Disc buttons (DISC 1-5)**  
Use to select the desired disc.
- ⑥ **Play button (▶ PLAY)**
- ⑦ **Spiral button (SPIRAL)**  
Press to play the first tracks on all the loaded discs in sequence, followed by the second tracks on all the discs, and so on.
- ⑧ **Random buttons (RANDOM)**
  - **One disc random button (ONE DISC)**  
Press to activate one disc random play. The changer will choose a disc and play all the tracks in random sequence, and choose next disc, and so on.
  - **Full random button (FULL)**  
Press to activate full random play. The changer will select the sequence to be played from all of the loaded discs, in an exclusively random manner.
- ⑨ **Repeat button (REPEAT)**  
Press to activate the repeat function.
- ⑩ **Loading drawer**  
You can load and unload discs when this drawer is open.
- ⑪ **Program mode button (PROGRAM MODE)**  
Use to select either the sequential play or program play mode. The mode changes each time you press the button. The sequential play mode is automatically selected when the power is switched on.
- ⑫ **Skip buttons (I◀◀ SKIP ▶▶I)**  
Use to skip to the beginning of the track.
- ⑬ **Stop button (■ STOP)**
- ⑭ **Pause button (|| PAUSE)**
- ⑮ **Loading drawer open/close button (▲ OPEN/CLOSE)**
- ⑯ **Disc skip button (DISC SKIP)**  
Use to rotate the disc tray.



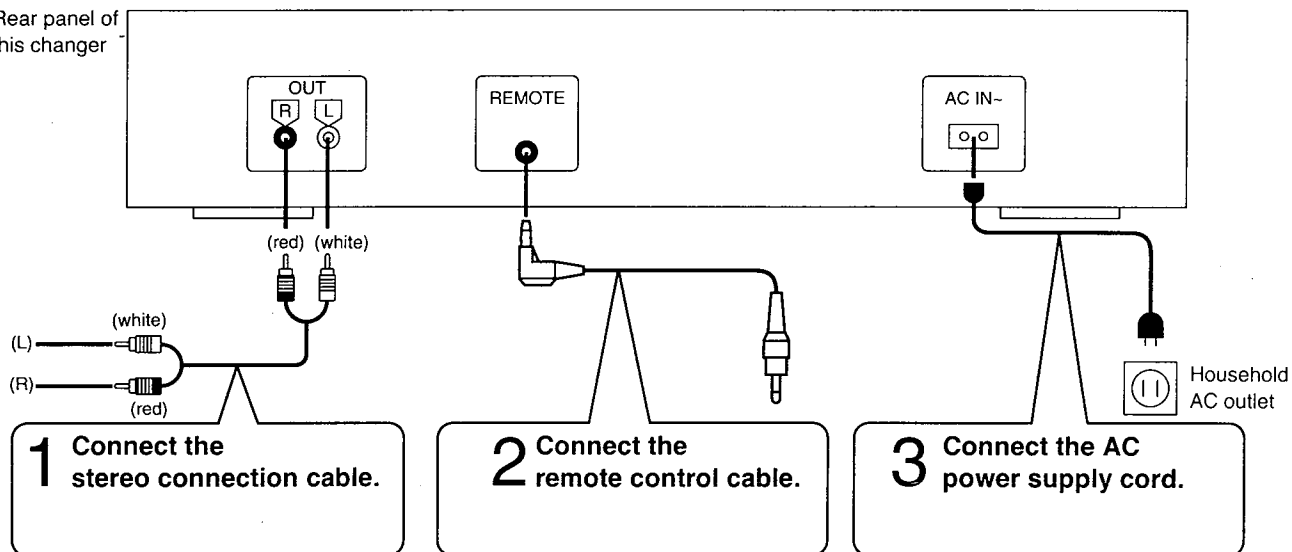
## Display section

- ①⑦ **Disc indicators ( <1> ~ <5> )**  
The indicator corresponding to the playing disc flashes. In the program play mode, programmed disc indicators will illuminate.
- ①⑧ **Disc number display**  
Shows the number (1-5) of the current disc.
- ①⑨ **Track number display**  
Shows the number (up to 99) of the current track.
- ①⑩ **Time/program sequence display**  
Shows the elapsed playing time of the track in play. Also shows the program sequence in the program play mode.
- ②① **Program play indicator (PGM)**  
Lights in the program play mode.
- ②② **Play mode indicators ( ▼▼▼ ) (Fig. 1)**  
Each indicator points to the following play modes:  
SPIRAL: Spiral play  
ONE: One disc random play  
FULL: Full random play
- ②③ **Repeat indicator ( ◁▷ )**  
Lights when the repeat function is activated.
- ②④ **Pause indicator ( || )**  
Lights in the pause mode.
- ②⑤ **Play indicator ( ▶ )**  
Lights in the play mode.

## CONNECTIONS

Before connecting the changer to your audio system, be sure that the power of the changer and all other system components are turned off.

Rear panel of this changer



- 1 Connect the stereo connection cable (included) to CD or AUX terminals of the amplifier or the receiver.
- 2 To operate with the remote control, connect the remote control cable (included) to the REMOTE CONTROL OUT terminal of Technics component.
- 3 Connect the power supply cord (included) to the household AC outlet (AC 120 V, 60 Hz) or to AC OUTLET of Technics component.

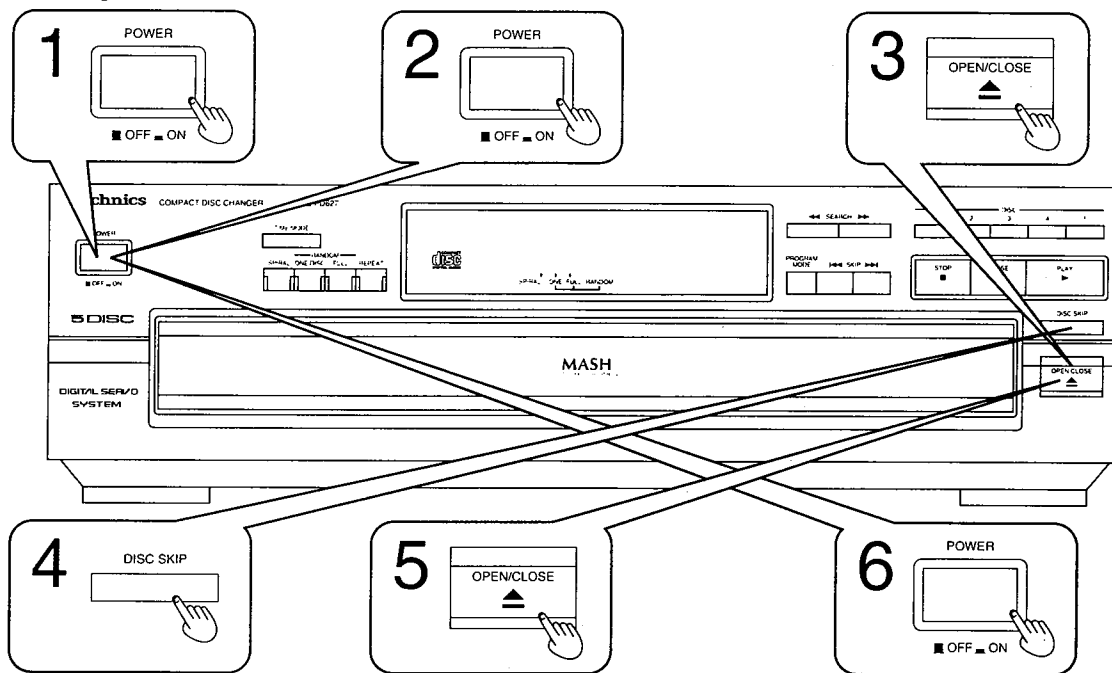
The operations such as play, stop, skip etc. can be operated by remote control included with Technics receiver or the component system. For details, refer to the operating instructions of the receiver or the system to be used.

## BEFORE MOVING

### CAUTION:

Before moving this changer to another location, be sure that no discs were left in the changer and that the changer was not switched off while in the play mode.

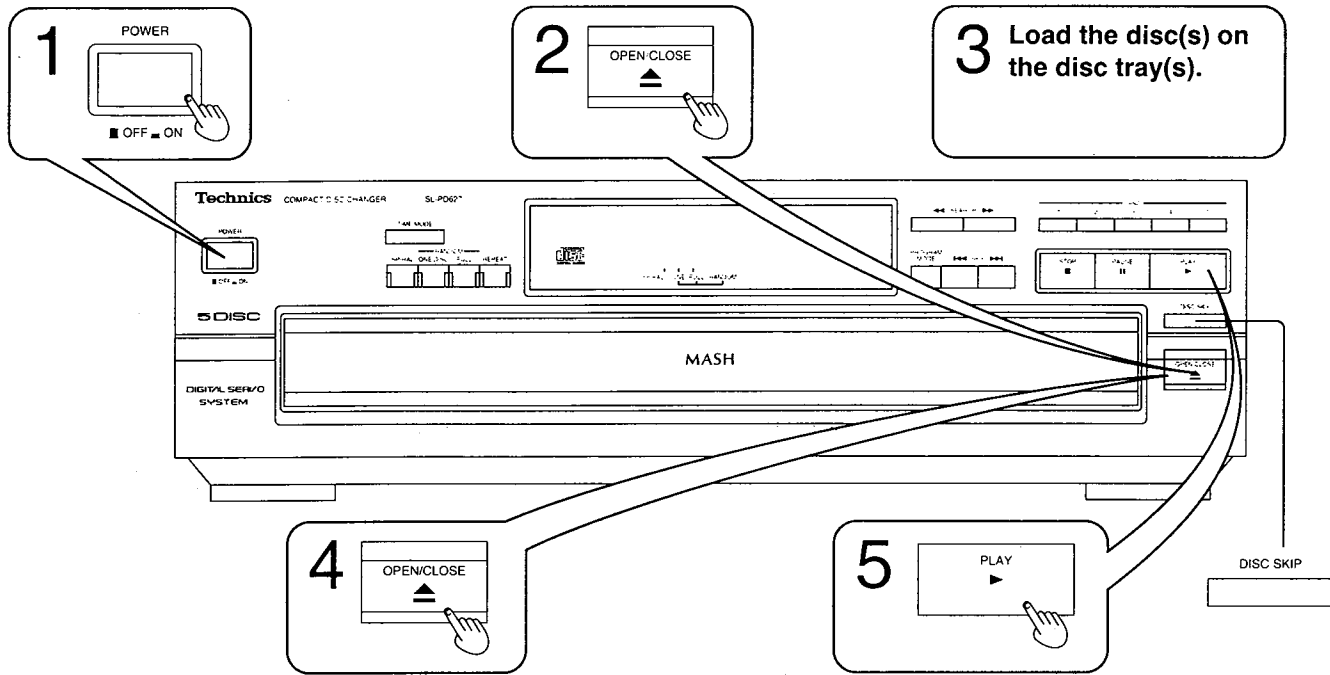
Failure to do so will expose the compact discs and the changer to the risk of severe damage.



- 1 Press POWER to switch off the power.
- 2 Press POWER to switch on the power.
- 3 Press OPEN/CLOSE to open the loading drawer.
- 4 Press DISC SKIP to rotate the disc trays and remove the discs from all disc trays.
- 5 Press OPEN/CLOSE to close the loading drawer.
- 6 Press POWER to switch off the power.

If you have pressed a wrong button by mistake, return to step 1.

# ■ BASIC OPERATING PROCEDURE



- 1 Press **POWER** to switch on the power.
- 2 Press **OPEN/CLOSE** to open the loading drawer.
- 3 Load the disc(s) on the disc tray(s).  
Do not load 3" (8 cm) and 5" (12 cm) discs on the same disc tray.  
  
The number (1-5) on the disc tray indicates the disc number.

- 4 Press **OPEN/CLOSE** again to close the loading drawer.

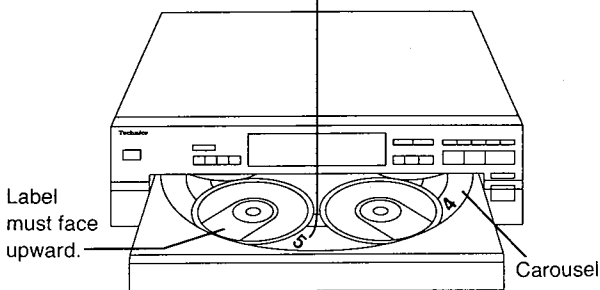
You can skip this step by pressing **PLAY**.  
The loading drawer will be closed automatically then play will start.

Do not attempt to close the drawer by hand. Be sure to press **OPEN/CLOSE**.

- 5 Press **PLAY**.

**CAUTION:**

Do not move this changer with a compact disc inside the unit. If a disc comes off the disc tray, it might be scratched or the changer might become incapable of playing. Refer to page 21 before moving the unit.



After loading discs on the two disc trays at the front position, press **DISC SKIP** to move the carousel. A different two disc trays will be at the front position.

**Note:**

Do not touch the carousel nor the loading drawer while it is moving.  
Do not turn the tray forcibly by hand because it may fail to operate normally.

## ■ HANDLING PRECAUTIONS FOR OPTICAL PICKUP

The laser diode in the optical pickup may break down due to potential difference caused by static electricity of clothes or human body.

So, be careful of electrostatic breakdown during repair of the optical pickup.

### • Handling of optical pickup

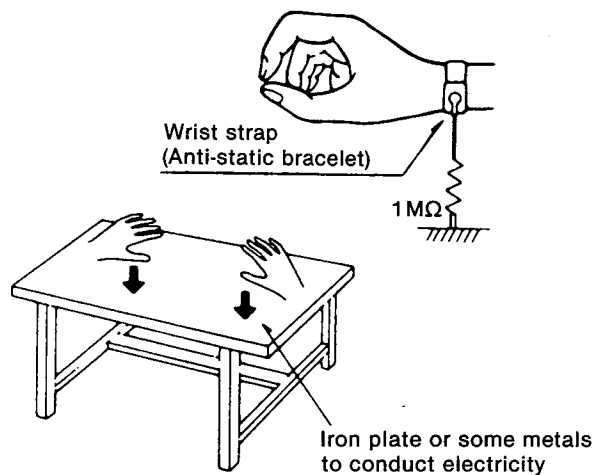
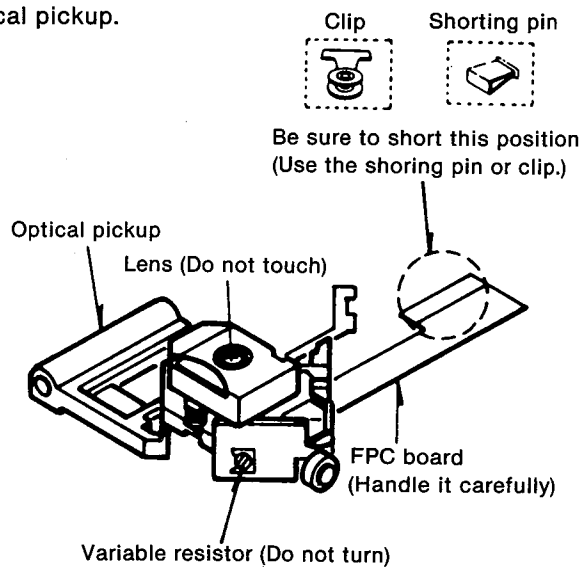
1. Do not subject the optical pickup to static electricity as it is extremely sensitive to electrical shock.
2. To prevent the breakdown of the laser diode, an antistatic shorting pin is inserted into the flexible board (FPC board).  
When removing or connecting the short pin, finish the job in as short time as possible.
3. Take care not to apply excessive stress to the flexible board (FPC board).
4. Do not turn the variable resistor (laser power adjustment). It has already been adjusted.

### • Grounding for electrostatic breakdown prevention

1. Human body grounding  
Use the anti-static wrist strap to discharge the static electricity from your body.
2. Work table grounding  
Put a conductive material (sheet) or steel sheet on the area where the optical pickup is placed, and ground the sheet.

#### Caution:

The static electricity of your clothes will not be grounded through the wrist strap. So, take care not to let your clothes touch the optical pickup.



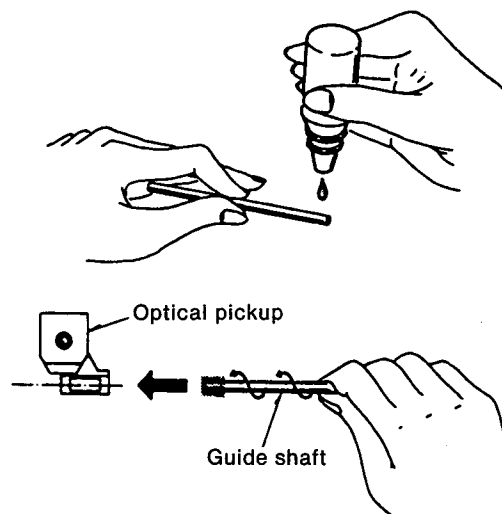
## ■ INSTRUCTIONS FOR TRAVERSE OIL (Part No. SZZ0L31)

The container contains 6g (approx. 3ml) of oil.

One application (one shaft) uses 0.05ml of oil.

### How to Use

- (1) Remove the guide shaft in the traverse deck from the optical pickup and clean off any dust from the guide shaft.
- (2) Apply one drop of the SZZ0L31 to the tip of the guide shaft.
- (3) Hold the guide shaft so that its oiled end touches the optical pickup and insert it into the bearing while rotating it slowly.
- (4) After securing the guide shaft, move the optical pickup by hand several times to the left and right to distribute the oil on the guide shaft.



# DISASSEMBLY INSTRUCTIONS

**Warning:** This product uses a laser diode. Refer to caution statements on page 2.

**Ref. No. 1**  
**Removal of the cabinet**

**Procedure 1**

1. Remove the 6 screws (①~⑥).  
2. Remove the cabinet in the direction of arrow.

**Ref. No. 2**  
**Removal of the front panel ass'y**

**Procedure 1→2**

**Note on installation**  
Connect the FPC board with the blue line upward.

1. Pull out the FPC board.

**Ref. No. 3**  
**Removal of the tray ass'y**

**Procedure 1→2→3**

**Note:** Be sure the close position to remove the tray ass'y.

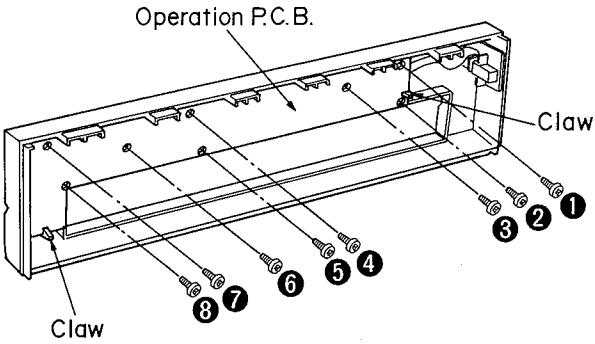
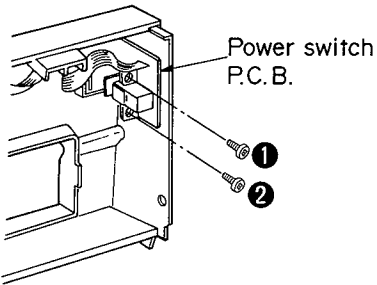
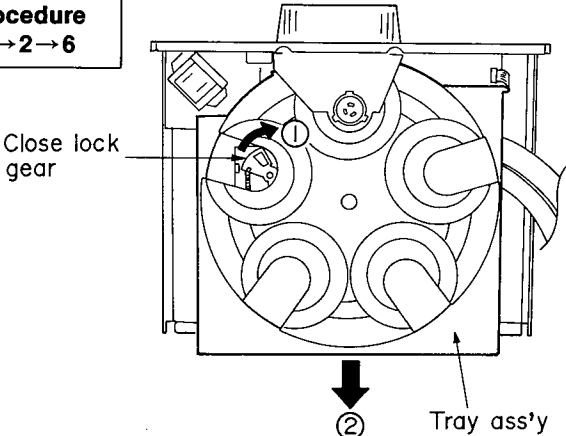
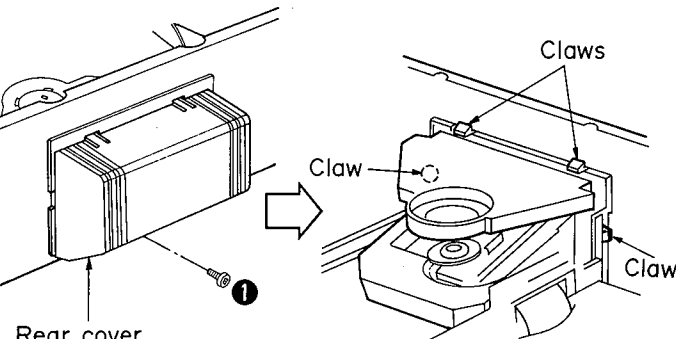
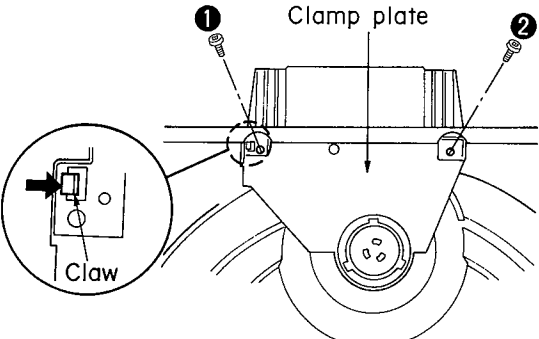
1. Keep the close lock gear pressed in the direction of arrow ① and move the tray ass'y in the direction of arrow ②.  
2. Fit the claw of the tray ass'y in the claw of the tray base guide (L).

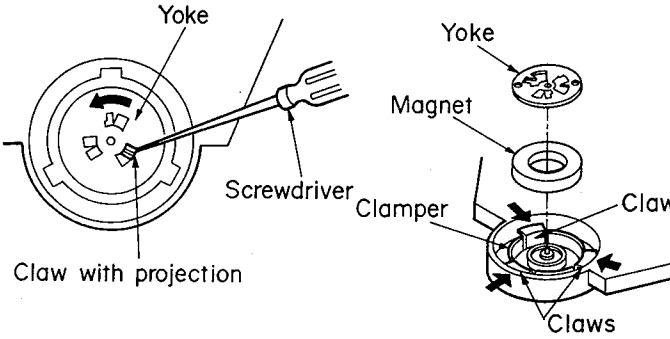
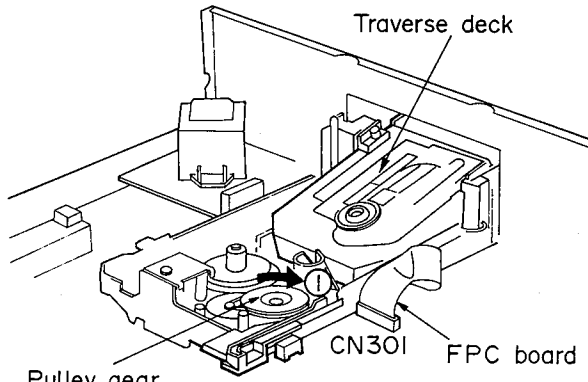
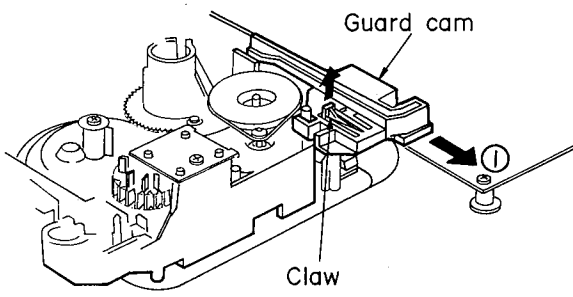
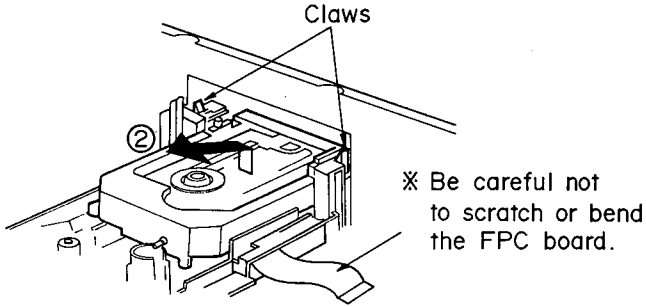
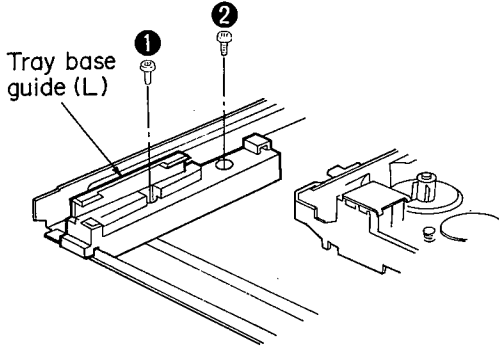
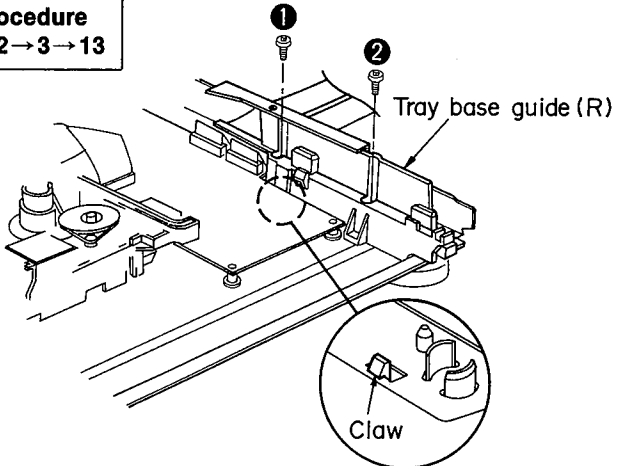
2. Remove the 3 screws (①~③).  
3. Pull the front panel ass'y in both directions of arrow ① to unlock it from the projection of the chassis ass'y.  
4. Remove the front panel ass'y in the direction of arrow ②.

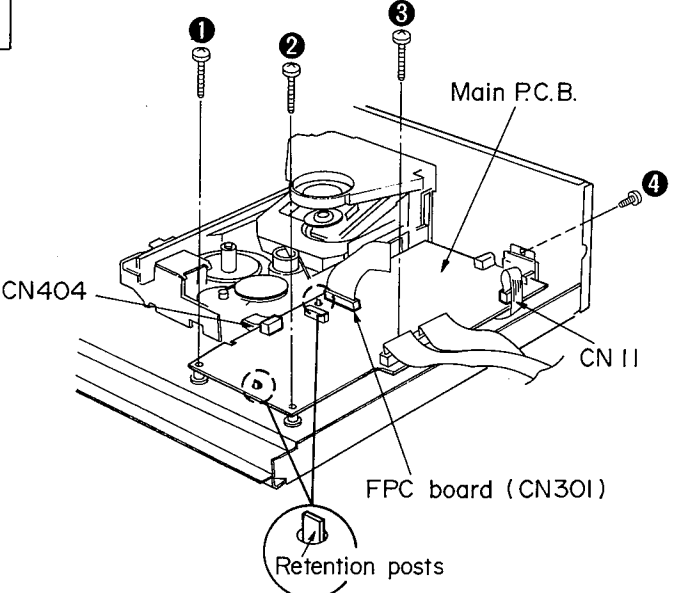
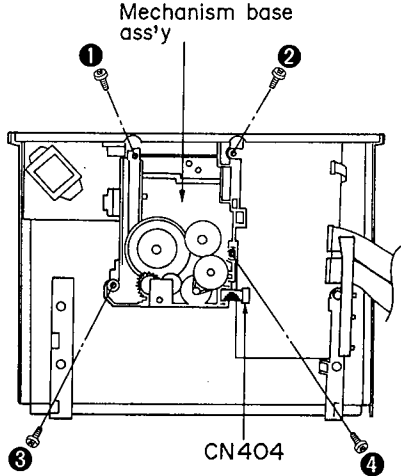
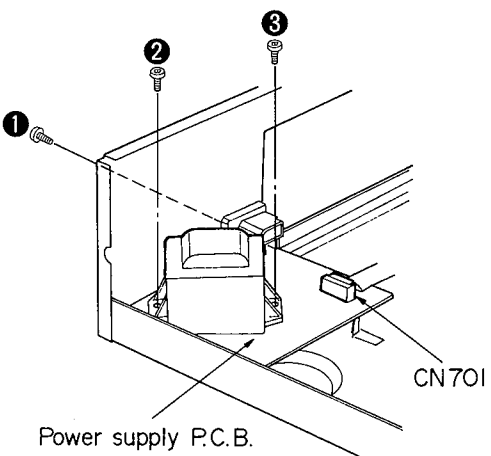
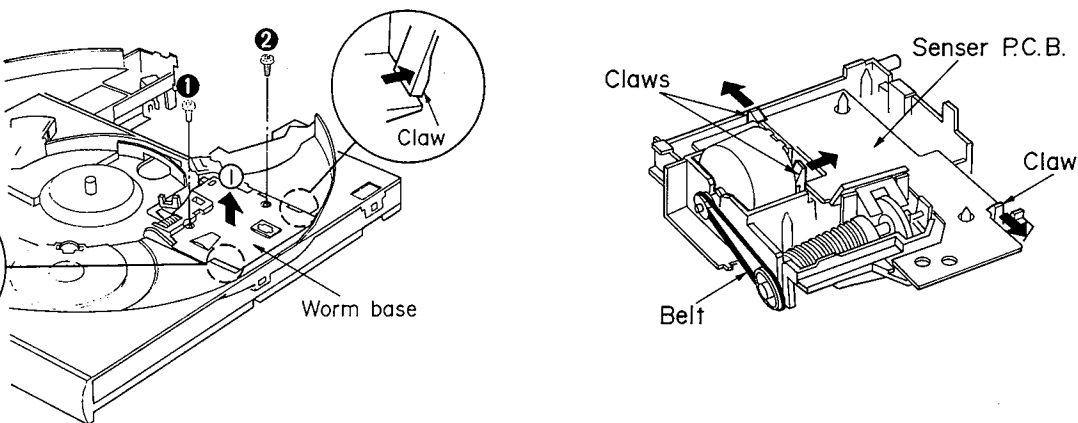
3. Remove the tray ass'y in the direction of arrow ③ by pressing the claw of the tray ass'y with a screw driver or another suitable object.

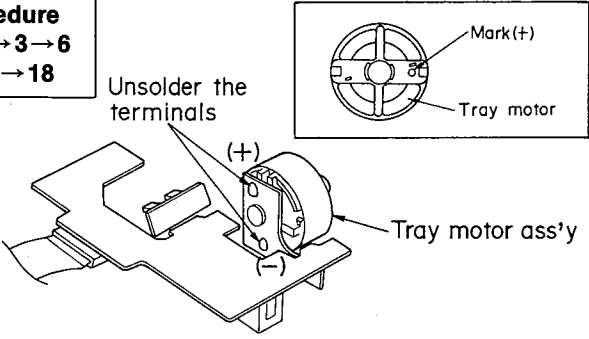
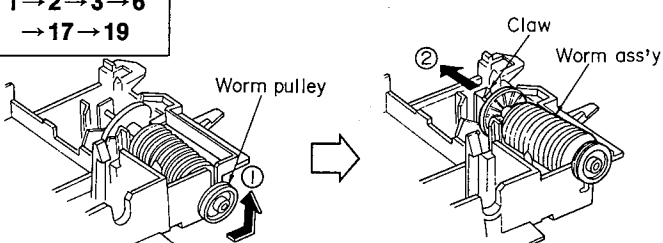
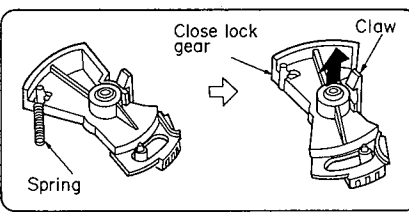
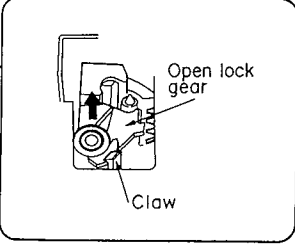
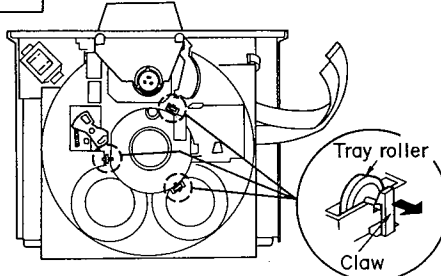
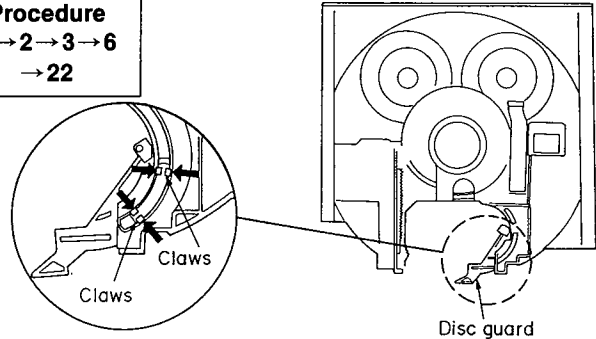
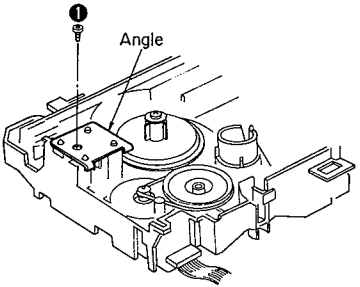
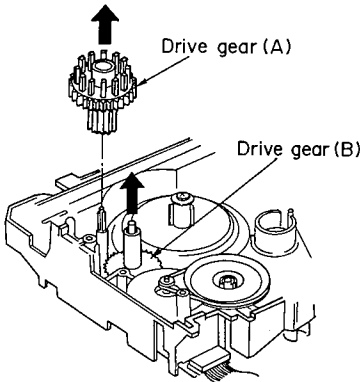
4. Raise the left side of the tray ass'y in the direction of arrow ④ and remove the claw on the right side.  
5. Pull out the FPC board



<p><b>Ref. No.</b> 4</p>	<p><b>Removal of the operation P.C.B.</b></p>	<p><b>Ref. No.</b> 5</p>	<p><b>Removal of the power switch P.C.B.</b></p>
<p><b>Procedure</b> 1→2→4</p>		<p><b>Procedure</b> 1→2→5</p>	
 <ol style="list-style-type: none"> <li>1. Remove the 8 screws (①~⑧).</li> <li>2. Release the 2 claws.</li> </ol>		 <ul style="list-style-type: none"> <li>• Remove the 2 screws (①, ②).</li> </ul>	
<p><b>Ref. No.</b> 6</p>	<p><b>Removal of the rotary tray</b></p>	 <ol style="list-style-type: none"> <li>1. Keep the close lock gear pressed in the direction of arrow ① and move the tray ass'y in the direction of arrow ②.</li> <li>2. Remove the 1 screw (①).</li> <li>3. Remove the spring and washer.</li> <li>4. Remove the rotary tray in the direction of arrow ③.</li> </ol>	
<p><b>Procedure</b> 1→2→6</p>			
<p><b>Ref. No.</b> 7</p>	<p><b>Removal of the rear cover</b></p>	<p><b>Ref. No.</b> 8</p>	<p><b>Removal of the clamp plate</b></p>
<p><b>Procedure</b> 1→7</p>		<p><b>Procedure</b> 1→8</p>	
 <ol style="list-style-type: none"> <li>1. Remove the 1 screw (①).</li> <li>2. Release the 4 claws.</li> </ol>		 <ol style="list-style-type: none"> <li>1. Remove the 2 screws (①, ②).</li> <li>2. Release the 1 claw.</li> </ol>	

<p><b>Ref. No.</b> 9</p>	<p><b>Removal of the clamber ass'y (yoke, magnet and clamber)</b></p>	<p><b>Ref. No.</b> 10</p>	<p><b>Removal of the traverse deck</b></p>
<p><b>Procedure</b> 1→8→9</p>		<p><b>Procedure</b> 1→2→3→7 →8→10</p>	
 <p>Yoke Screwdriver Claw with projection Magnet Clamber Claw Claws</p> <ol style="list-style-type: none"> <li>1. While lifting the claw with a screwdriver, rotate yoke in the direction of arrow and remove the yoke and magnet.</li> <li>2. Release the 3 claws of the clamber.</li> </ol>		 <p>Traverse deck Pulley gear CN301 FPC board</p> <ol style="list-style-type: none"> <li>1. Rotate the pulley gear in the direction of arrow ① until the traverse deck comes up.</li> <li>2. Pull out the FPC board (CN301).</li> </ol>	
<p><b>Ref. No.</b> 11</p>	<p><b>Removal of the guard cam</b></p>	<ol style="list-style-type: none"> <li>3. Release the 2 claws.</li> <li>4. Remove the traverse deck in the direction of arrow ②.</li> </ol>	
<p><b>Procedure</b> 1→2→3→11</p>			
 <p>Guard cam Claw</p> <ol style="list-style-type: none"> <li>1. Release the 1 claw and then remove the guard cam in the direction of arrow ①.</li> </ol>		 <p>Claws</p> <p>※ Be careful not to scratch or bend the FPC board.</p>	
<p><b>Ref. No.</b> 12</p>	<p><b>Removal of the tray base guide (L)</b></p>	<p><b>Ref. No.</b> 13</p>	<p><b>Removal of the tray base guide (R)</b></p>
<p><b>Procedure</b> 1→2→3→12</p>		<p><b>Procedure</b> 1→2→3→13</p>	
 <p>Tray base guide (L)</p> <p>• Remove the 2 screws (①, ②).</p>		 <p>Tray base guide (R)</p> <p>Claw</p> <ol style="list-style-type: none"> <li>1. Remove the 2 screws (①, ②). [Bottom side]</li> <li>2. Release the 1 claw.</li> </ol>	

<b>Ref. No.</b> 14	<b>Removal of the main P.C.B.</b>			
<b>Procedure</b> 1→2→3→11 →13→14	<ol style="list-style-type: none"> <li>1. Remove the 4 screws (①~④),</li> <li>2. Lift the main P.C.B. off the retention posts on the chassis.</li> <li>3. Remove the 2 flat cable (CN11, CN404).</li> <li>4. Pull out the FPC board (CN301).</li> <li>5. Remove the main P.C.B. in the direction of arrow.</li> </ol>			
<b>Ref. No.</b> 15	<b>Removal of the mechanism base ass'y</b>	<b>Ref. No.</b> 16	<b>Removal of the power supply P.C.B.</b>	
<b>Procedure</b> 1→2→3→7 →8→10→11 →15			<b>Procedure</b> 1→2→3→7 →8→10→11 →15→16	
<b>Ref. No.</b> 17		<b>Removal of the worm base and senser P.C.B.</b>		
<b>Procedure</b> 1→2→3→6 →17				
<ol style="list-style-type: none"> <li>1. Remove the 2 screws (①, ②).</li> <li>2. Release the 2 claws and then remove the worm base in the direction of arrow ①.</li> </ol>		<ol style="list-style-type: none"> <li>3. Remove the belt.</li> <li>4. Release the 3 claws.</li> </ol>		

<p><b>Ref. No.</b> 18</p>	<p><b>Removal of the tray motor ass'y</b></p>	<p><b>Ref. No.</b> 19</p>	<p><b>Removal of the worm ass'y</b></p>
<p><b>Procedure</b> 1→2→3→6 →17→18</p>	<p>Unsolder the terminals</p>  <p>• Unsolder the terminals of the tray motor ass'y</p>		<p><b>Procedure</b> 1→2→3→6 →17→19</p>  <p>1. Raise the pulley in the direction of arrow ①. 2. Remove the worm ass'y by pressing the claw in the direction of arrow ②.</p>
<p><b>Ref. No.</b> 20</p>	<p><b>Removal of the close lock gear and open lock gear</b></p>		
<p><b>Procedure</b> 1→2→6→20</p>	 <p>1. Remove the spring. 2. Release the claw and then remove the close lock gear in the direction of arrow.</p>		 <p>■ Open lock gear • Release the claw and then remove the open lock gear in the direction of arrow.</p>
<p><b>Ref. No.</b> 21</p>	<p><b>Removal of the tray roller</b></p>		<p><b>Ref. No.</b> 22</p>
<p><b>Procedure</b> 1→2→6→21</p>	 <p>• Release the claw in the direction of arrow.</p>		<p><b>Procedure</b> 1→2→3→6 →22</p>  <p>• Release the 2 pairs of claws in the direction of arrow.</p>
<p><b>Ref. No.</b> 23</p>	<p><b>Removal of the drive gear (A) and drive gear (B)</b></p>		
<p><b>Procedure</b> 1→2→3→23</p>	 <p>1. Remove the 1 screw (①). 2. Remove the angle.</p>		 <p>3. Remove the drive gear (A) and drive gear (B).</p>

**Ref. No. 24**  
**Removal of the pulley gear**

**Procedure**  
1→2→3→24

Claws  
Pulley gear  
Belt

1. Remove the belt.
2. Release the 2 claws and then remove the pulley gear in the direction of arrow.

**Ref. No. 26**  
**Removal of the loading motor P.C.B.**

**Procedure**  
1→2→3→7  
→8→10→11  
→15→26

Belt

1. Remove the belt.

Claw

2. Remove the 3 screws (1~3).
3. Release the 1 claw.

Loading motor P.C.B.  
Loading motor  
Unsold the terminals

Mark(+)  
Loading motor (1)

4. Unsolder the terminals of the loading motor.

**Ref. No. 25**  
**Removal of the drive cam, elevation cam and reduction gear**

**Procedure**  
1→2→3→23  
→24→25

1. Remove the 3 screws (1~3).

Drive cam  
Elevation cam  
Reduction gear

2. Remove the drive cam, elevation cam and reduction gear.

**Ref. No. 27**  
**Removal of the servo P.C.B.**

**Procedure**  
1→2→3→7  
→8→10→27

1. Remove the 3 screws (1~3).
2. Unsolder the 2 terminals of spindle motor.
3. Remove the FPC board from the optical pickup.

Servo P.C.B.  
Connector (CN101)  
FPC board  
Unsolder the terminals

**Caution:** To prevent the breakdown of the laser diode, antistatic shorting pin is inserted into the FPC board.

FPC board  
Shorting pin

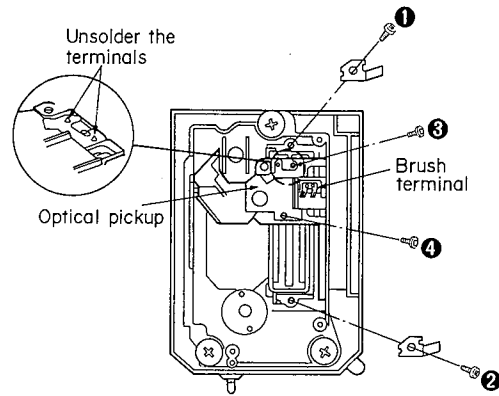
**Ref. No. 28**  
**Removal of the optical pickup**

**Procedure**  
 1→2→3→7  
 →8→10→27  
 →28

**Refer to the handling precautions for optical pickup and instructions for traverse oil (See page 7).**

1. Remove the 2 screws (1, 2).
2. Unsolder the 2 terminals and the 2 screws (3, 4).

**Caution:** Take care not to touch the brush terminal.



**Ref. No. 29**  
**Removal of the spindle motor**

**Procedure**  
 1→2→3→7  
 →8→10→27  
 →29

1. Loosen the screw (1) by using a 1.27mm allen wrench and remove the turntable.
2. Remove the 2 screws (2, 3).

**Caution:**

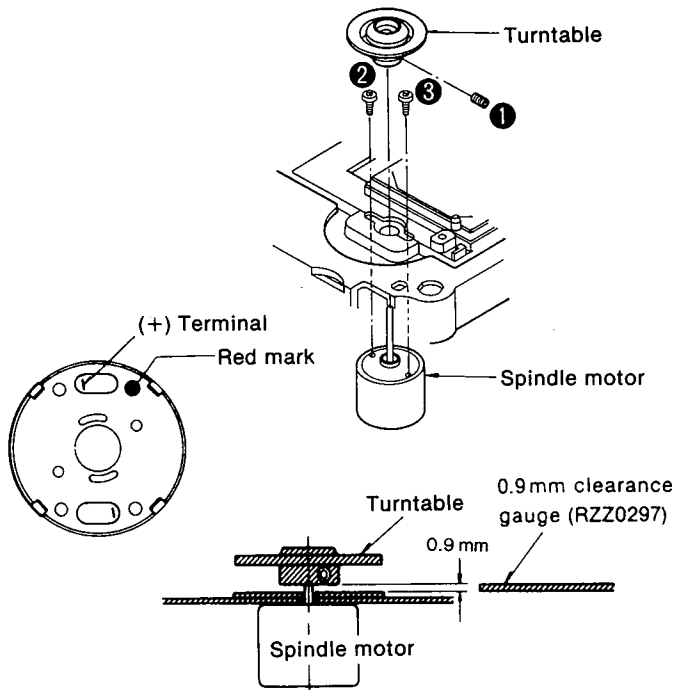
1. Turntable height adjustment is necessary any time the turntable or spindle motor is replaced.
2. The (+) terminal of the spindle motor is indicated by the red mark.

**Adjustment of turntable height**

1. Insert a 0.9mm clearance gauge (RZZ0297) between the turntable and loading base as shown in the figure.
2. Tighten the turntable set-screw by using a 1.27mm allen wrench.

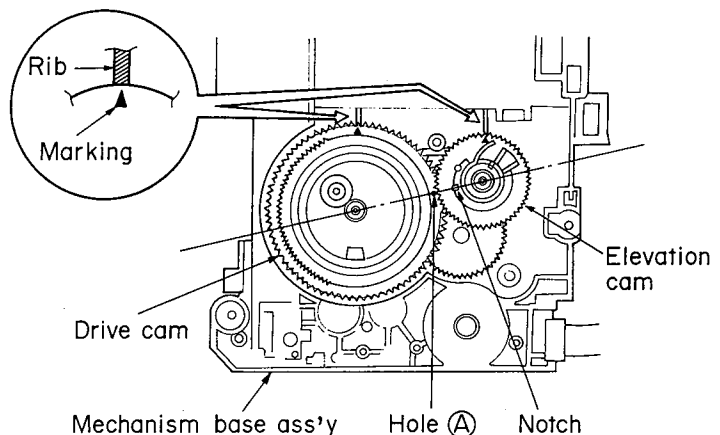
**Caution:**

Refer to turntable height adjustment (See page 25).



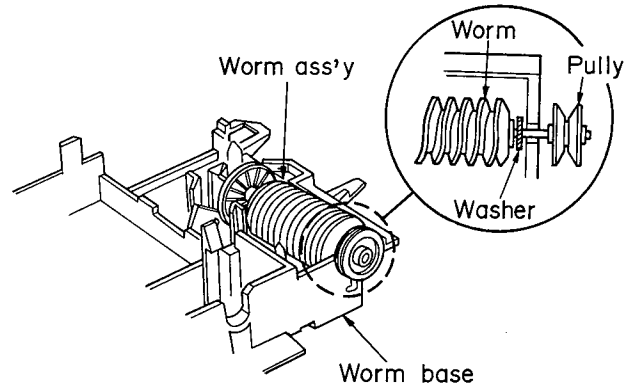
**• Installation of the elevation cam and drive cam**

1. Align the drive cam, the marking (▲) on the elevation cam, and the rib on the mechanism base ass'y.
2. Check that hole (A) on the drive cam and the notch on the elevation cam are aligned in a straight line.



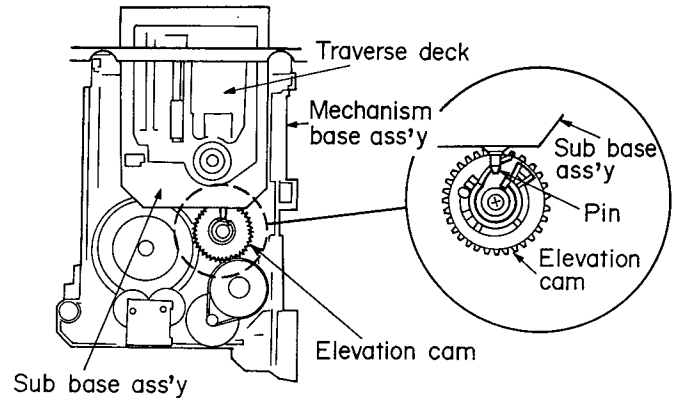
### • Installation of the worm ass'y

When installing the worm ass'y onto the worm base, move the washer located between the worm and pulley next to the worm.



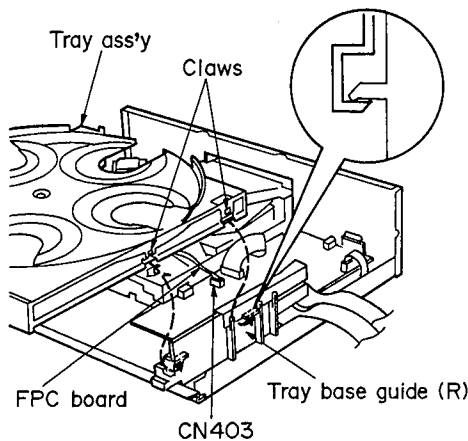
### • Installation of the traverse deck

1. Position the elevation cam as shown in the figure on the right.
2. When the traverse deck is mounted on the mechanism base ass'y, check that the pin of the sub base ass'y is positioned at the slanted part of the rib on the elevation cam.

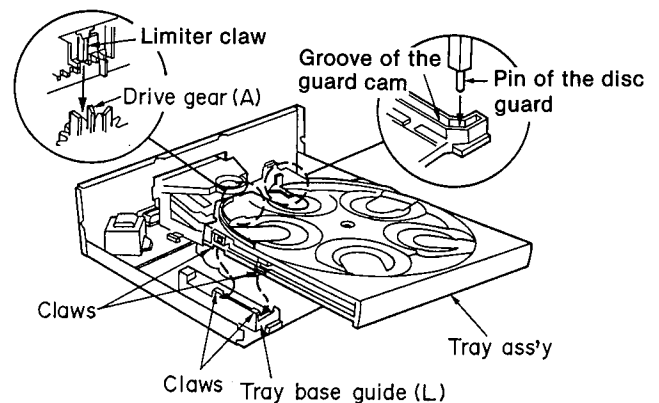


### • Installation of the tray ass'y

1. Attach the FPC board to the connector (CN403).
2. Fit the claws on the right side of the tray ass'y underneath the claws on the tray base guide (R).
3. Fit pin of the disc guard into groove of the guard cam.

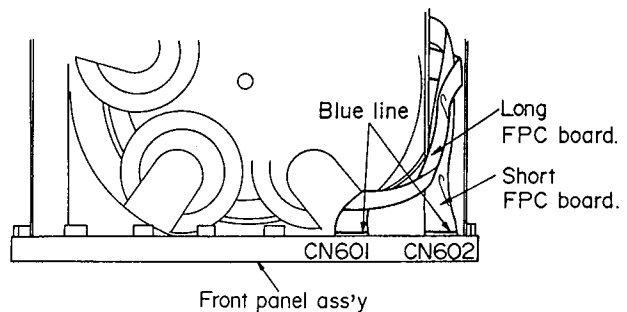


4. Fit the limiter claw on the tray ass'y between the teeth of the drive gear (A).
5. Align the claws on the left side of the tray ass'y with the claws on the tray base guide (L) and push the tray ass'y until the claws catch.
6. After installing the tray ass'y, check that it moves smoothly.



### • Notes on the installation of the FPC board for the front panel ass'y

1. With its blue line facing up, fully insert the FPC board until the foil is no longer exposed.
2. Insert the short FPC board first and then insert the long FPC board over it.



## HOW TO CHECK THE MAIN AND SERVO P.C.B.

### • Check the main P.C.B.

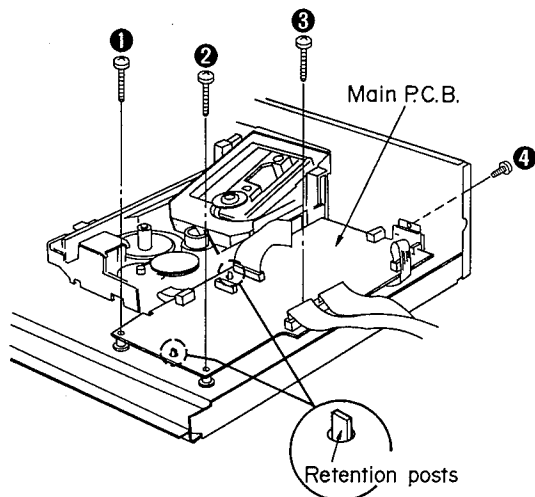


Fig. 1

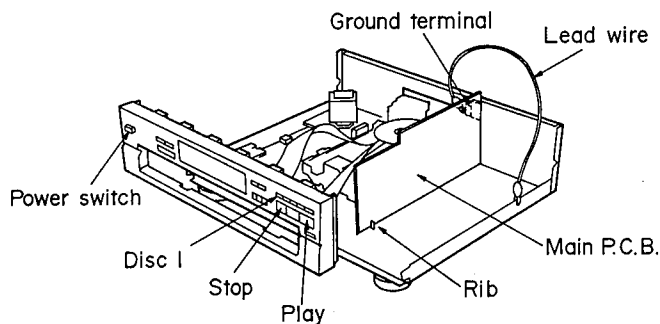


Fig. 3

### • Check the servo P.C.B.

When checking the servo P.C.B., place the traverse deck sideways.

There are two ways (A) & (B) of securing the traverse deck as shown below.

#### (A) Securing the traverse deck to the chassis ass'y.

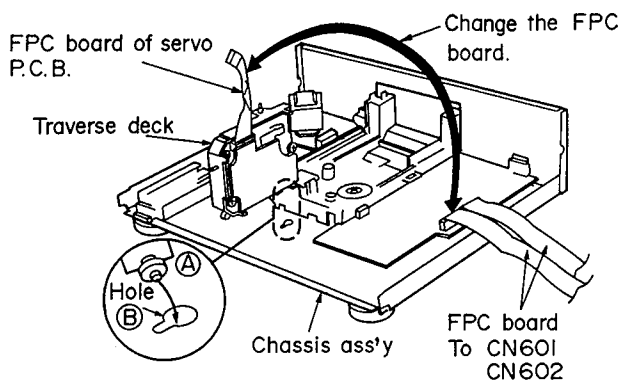


Fig. 4

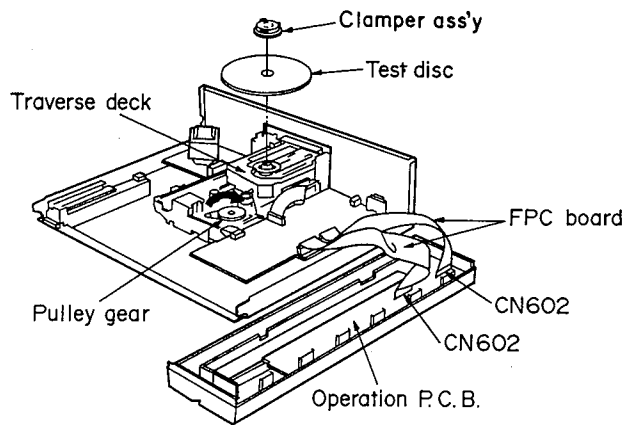


Fig. 2

1. Rotate the pulley gear in the direction of arrow until traverse deck comes up.
2. Place the test disc and secure it by using the clamper ass'y.
3. Connect the 2 FPC board (CN601, CN602) as shown in Fig. 2.
4. Remove the 4 screws (①~④) as shown in Fig. 1.
5. Lift the main P.C.B. off the retention post on the chassis.
6. Set up the main P.C.B.
7. Connect the main P.C.B. ground terminal (line out terminal) to the chassis ass'y with a lead wire.

#### How to play the disc

8. Set the unit in the test mode as follows: (hold the **play**, **stop** and **disc 1** keys (3 keys) on and set the power switch to ON.)
9. Press the **play** key and play the test disc.
10. When checking the soldered surface of the main P.C.B., do as shown in Fig. 3.

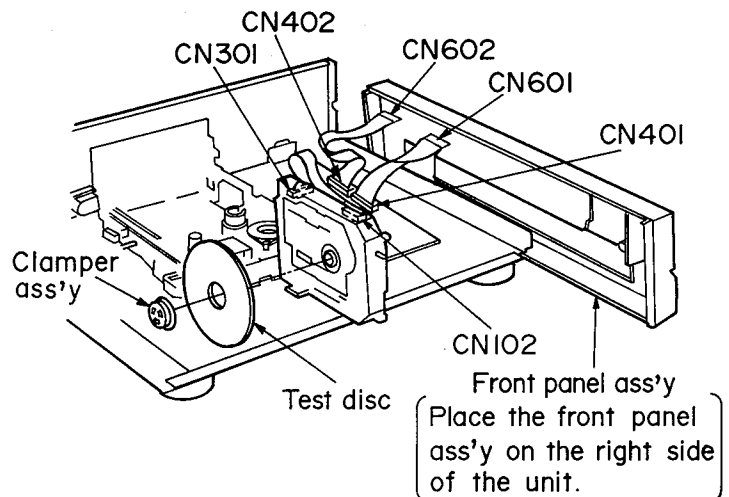


Fig. 5



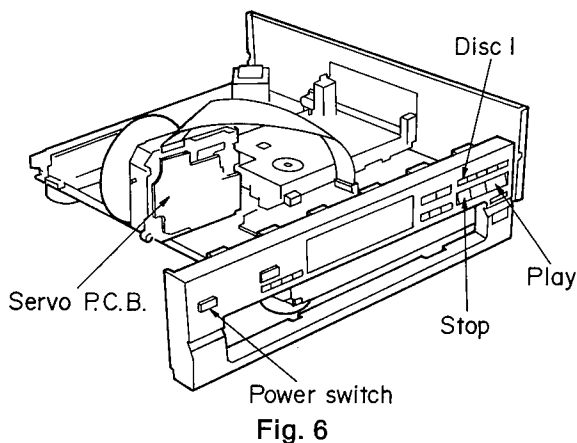


Fig. 6

1. Connect the FPC boards as shown in Fig. 5.

Between CN401 and CN601  
 Between CN402 and CN602  
 Between CN102 and CN301

Replace the FPC board for the servo P.C.B. (between CN102 and CN301) with the FPC board on the main P.C.B. (between CN401 and CN601 or between CN402 and CN602). (Reference the arrows in Fig. 4.)

#### (B) Securing the traverse deck to the mechanism base ass'y.

(The traverse deck cannot be secured unless the rear panel has been removed.)

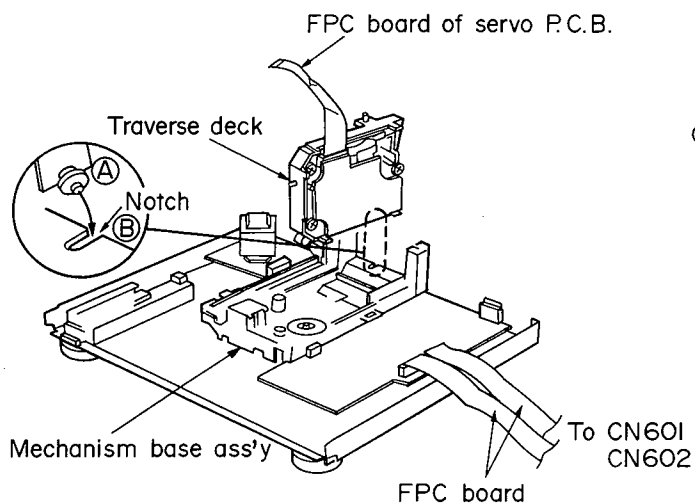


Fig. 7

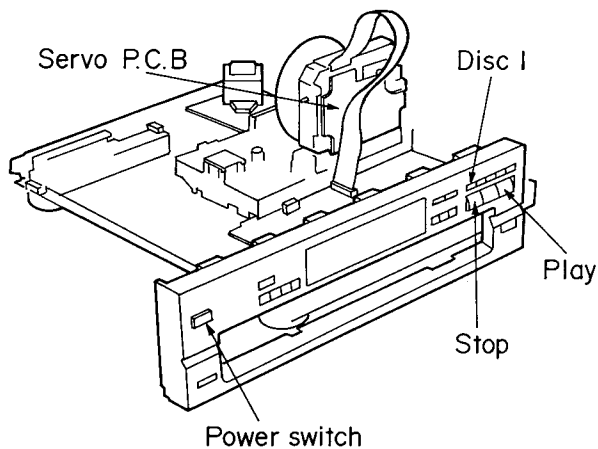


Fig. 9

#### Notes:

- The FPC board cannot be connected because it is too short when the traverse deck is secured sideways. Replace it with the long FPC board.
  - After completing the check, restore the replaced FPC boards to their original positions.
2. Insert part (A) of the traverse deck into hole (B) of the chassis ass'y as shown in Fig. 4.

#### How to play the disc

3. Set the unit in the test mode as follows: (hold the **play**, **stop** and **disc 1** keys (3 keys) on and set the power switch to ON.)
4. Press the **play** key and play the test disc.
5. When checking the soldered surface of the servo P.C.B., do as shown in Fig. 6.

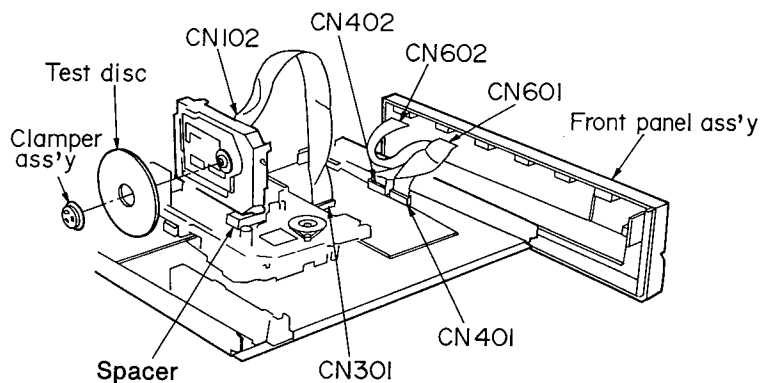


Fig. 8

1. Connect the FPC boards in the same manner as described in (A) above.
2. Insert part (A) of the traverse deck into notch (B) of the mechanism base ass'y as shown in Fig. 7.
3. Install the spacer so that the traverse deck is horizontal as shown in Fig. 8.

#### How to play the disc

4. Set the unit in the test mode as follows: (hold the **play**, **stop** and **disc 1** keys (3 keys) on and set the power switch to ON.)
5. Press the **play** key and play the test disc.
6. When checking the soldered surface of the servo P.C.B., do as shown in Fig. 9.

## ■ OPERATING THE UNIT WITHOUT THE FRONT PANEL ASS'Y (OPERATING P.C.B. AND KEYS)

The main operations of the unit can be performed by shorting jumper wires on the main P.C.B. even if the FPC board from the control panel is not connected to the main P.C.B.

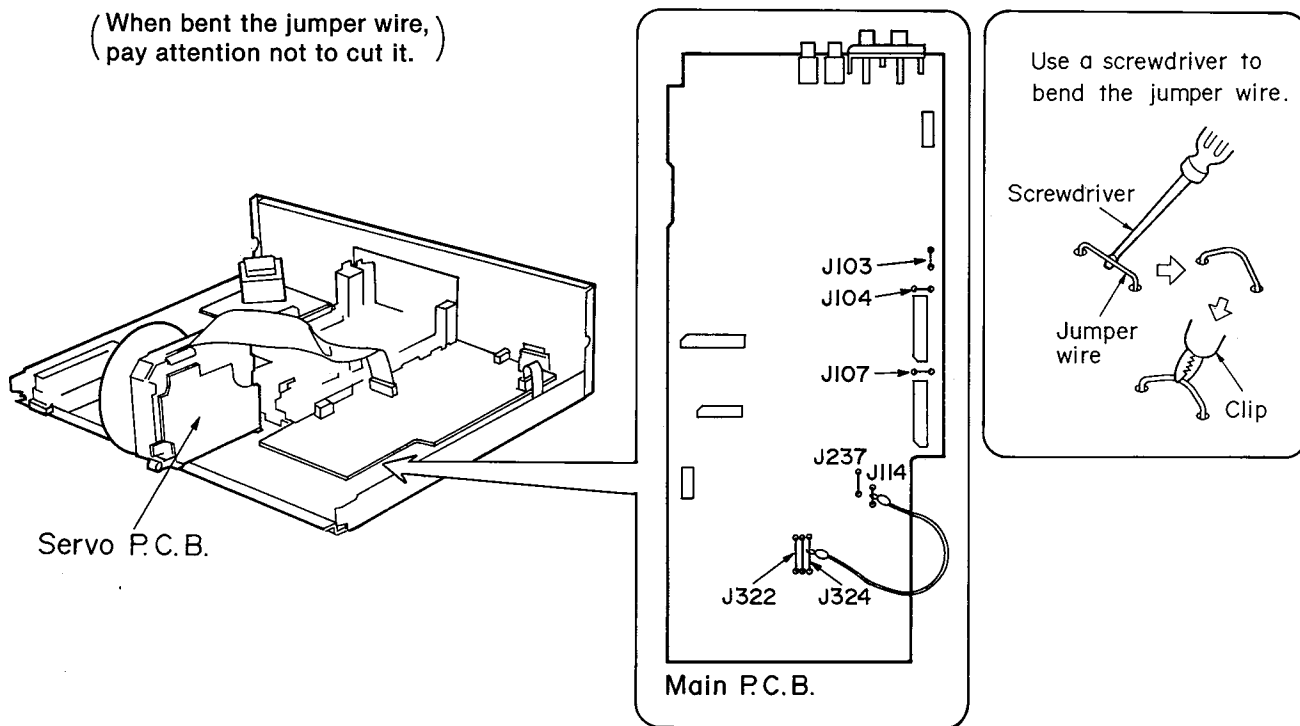


Fig. 1

1. Short the jumpers on the main P.C.B.
  - a. J324-J114 (equivalent to pressing the PLAY key)
  - b. J322-J114 (equivalent to pressing the STOP key)
  - c. J324-J237 (equivalent to pressing the DISC 1 key)
2. Shorting J103 to J104 turns the power ON.
3. After turning on the power, open the 3 shorted jumpers (a to c) in 1.
4. Momentarily short the jumpers shown below as needed. (Fig. 1)
  - To PLAY, short J324 to J114 (equivalent to pressing the PLAY key)
  - To FWD, short J322 to J107 (equivalent to pressing the ►► SKIP key)
  - To REW, short J324 to J107 (equivalent to pressing the ◀◀ SKIP key)
  - To STOP, short J322 to J114 (equivalent to pressing the STOP key)
5. The operations for the 4 modes above can be performed.

## ■ DISPLAY FUNCTION OF AUTOMATICALLY-ADJUSTED RESULTS (SELF-CHECK FUNCTION)

The unit contains a function which displays the result of the automatically adjustment of the servo circuits (tracking, focus servo, etc.) as an error code on the FL display.

The error code display serves as a repair guide showing the automatically adjustment circuit is at fault. The procedures for displaying the error codes are given below.

### • Procedures to display the error code

#### (1) Procedure to display the error code before disassembly (finished unit)

1. When the [POWER] key is pressed while holding down the [STOP (■)], [PAUSE (⏸)] and [PLAY (▶)] keys simultaneously, the FL display illuminates, release the power turns on.
2. When the FL display illuminates, release the [STOP (■)], [PAUSE (⏸)] and [PLAY (▶)] keys.
3. Press the [OPEN/CLOSE (▲)] key to open the disc tray and load the test disc (SZZP1054C).
4. Press the [PLAY (▶)] key to start the play operation.
5. After the time display appears, press the [TIME MODE] key twice to display the error code. (e.g. E-0)
6. The error code display can be used as a repair guide showing which servo circuit is at fault. (See Error Code Based Troubleshooting.)



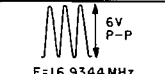
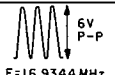


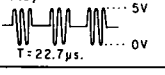

#### (2) Procedure to display the error code when disassembled

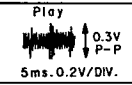


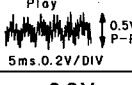
1. Prepare the unit as described in "How to Check the Servo P.C.B." on page 16.
2. Press the [POWER] key while holding down the [STOP (■)], [PLAY (▶)] and [DISC 1] keys simultaneously.
3. When the FL display illuminates, release the [STOP (■)], [PLAY (▶)] and [DISC 1] keys.
4. Load the test disc (SZZP1054C) on the turntable and secure it with the clamber ass'y.
5. Perform steps 4 and 5 in section (1) above.

### • Error code based troubleshooting

※ The unit is satisfactory if the error code is E-0 of E-2.

※ Before testing, check that the test disc is free of scratches and dirt and optical pickup is clean.

FL error code display	Symptom	Probable cause	Signal to check		Normal the values of voltage and waveform	
			Signal name	Location	PLAY	STOP
E-1	Incomplete focus, tracking or offset adjustment	1. Data transfer with IC401 2. IC102 setup condition	MDATA	IC102 ⑦ pin		0V
			MCLK	IC102 ⑧ pin		4.9V
			MLD	IC102 ⑨ pin		
			SENSE	IC102 ⑩ pin	0V	4.9V
			/RST	IC102 ⑪ pin	4.6V	4.6V
			XI	IC102 ⑫ pin		
E-3 E-5 E-7 E-9 E-B E-D E-F	Disc cannot be played reliably.	1. Scratched or dirty disc 2. Focus and tracking servo circuits 3. Spindle drive circuit 4. Optical pickup	FE	IC102 ⑬ pin		2.5V
			TE	IC102 ⑭ pin		2.5V
			FOD	IC102 ⑮ pin		2.5V
			TRD	IC102 ⑯ pin		
			KICK	IC102 ⑰ pin	2.5V	2.5V
			VR1	IC102 ⑱ pin	3.9V	3.9V
			VR2	IC102 ⑲ pin	0.9V	0.9V
			/FLOCK	IC102 ⑳ pin	0V	4.9V
			/RF DET	IC102 ㉑ pin	0V	4.7V
			RF	TJ101		2.5V
			STAT	IC301 ㉒ pin	4.9V	0V

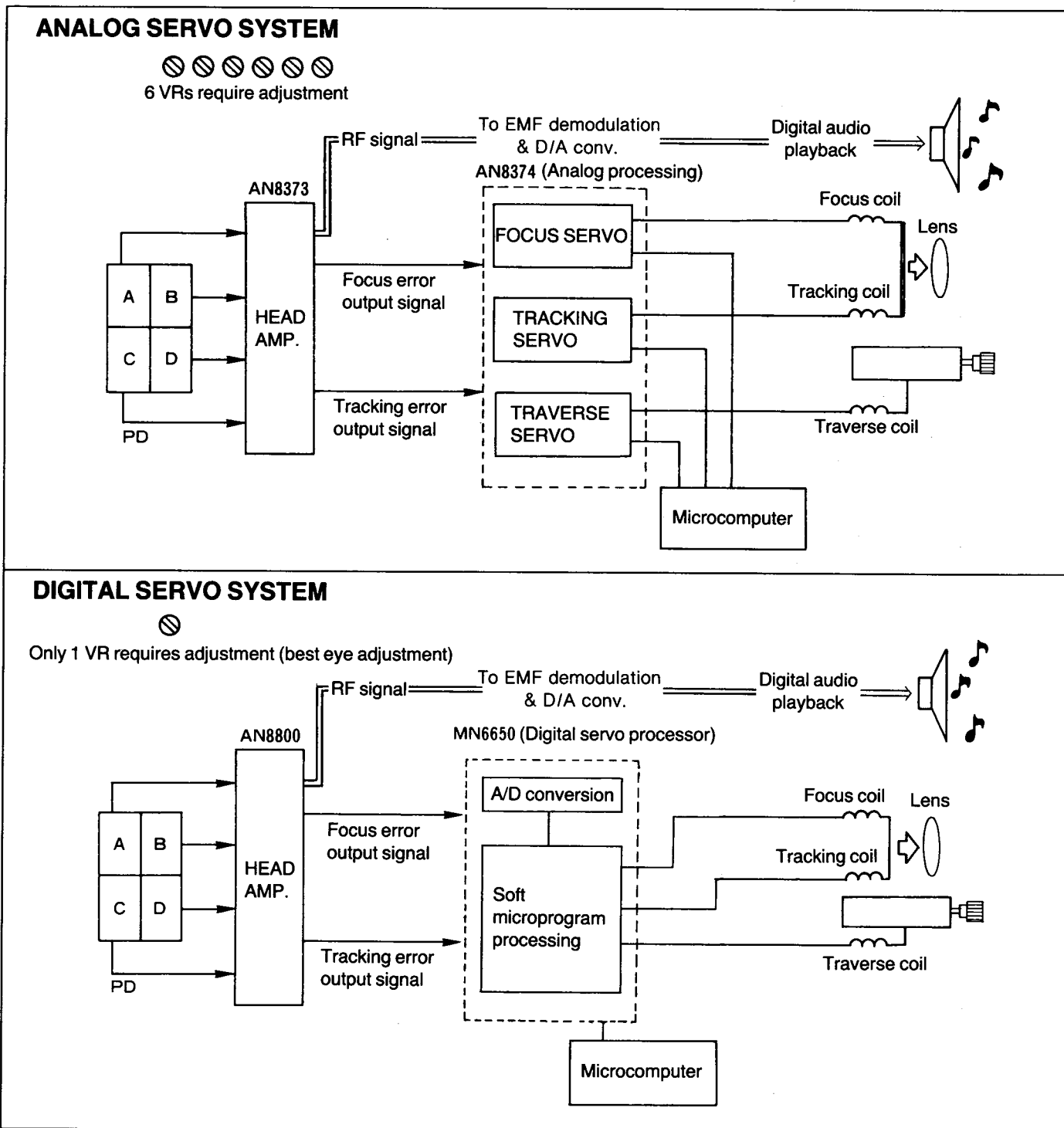
FL error code display	Symptom	Probable cause	Signal to check		Normal the values of voltage and waveform	
			Signal name	Location	PLAY	STOP
E-4 E-6	Incomplete focus gain adjustment	1. Scratched or dirty disc 2. Focus servo circuit 3. Optical pickup	FE	IC102 ⑩ pin		2.5V
			VR1	IC102 ⑫ pin	3.9V	3.9V
			VR2	IC102 ⑪ pin	0.9V	0.9V
			OFT	IC102 ⑤ pin	0V	4.7V
			/TLOCK	IC102 ⑳ pin	0V	4.9V
E-8 E-A ※ See note	Incomplete tracking gain adjustment	1. Scratched or dirty disc 2. Tracking servo circuit 3. Optical pickup	TE	IC102 ⑨ pin		2.5V
			VR1	IC102 ⑫ pin	3.9V	3.9V
			VR2	IC102 ⑪ pin	0.9V	0.9V
			OFT	IC102 ⑤ pin	0V	4.7V
			/TLOCK	IC102 ⑳ pin	0V	4.9V
E-C E-E	See error codes E-4, E-6, E-8 and E-A	See error codes E-4, E-6, E-8 and E-A	FE	IC102 ⑩ pin		2.5V
			TE	IC102 ⑨ pin		2.5V
			VR1	IC102 ⑫ pin	3.9V	3.9V
			VR2	IC102 ⑪ pin	0.9V	0.9V
			OFT	IC102 ⑤ pin	0V	4.7V
			/TLOCK	IC102 ⑳ pin	0V	4.9V

※ Note: For a unit showing error code E-8 or E-A, check the error code several times. If error code E-0 or E-2 appears, the unit can be assumed to be satisfactory.

## DIGITAL SERVO SYSTEM

The newly-developed digital servo system is adopted in the servo circuit of the unit's CD player instead of the ordinary analog servo system.

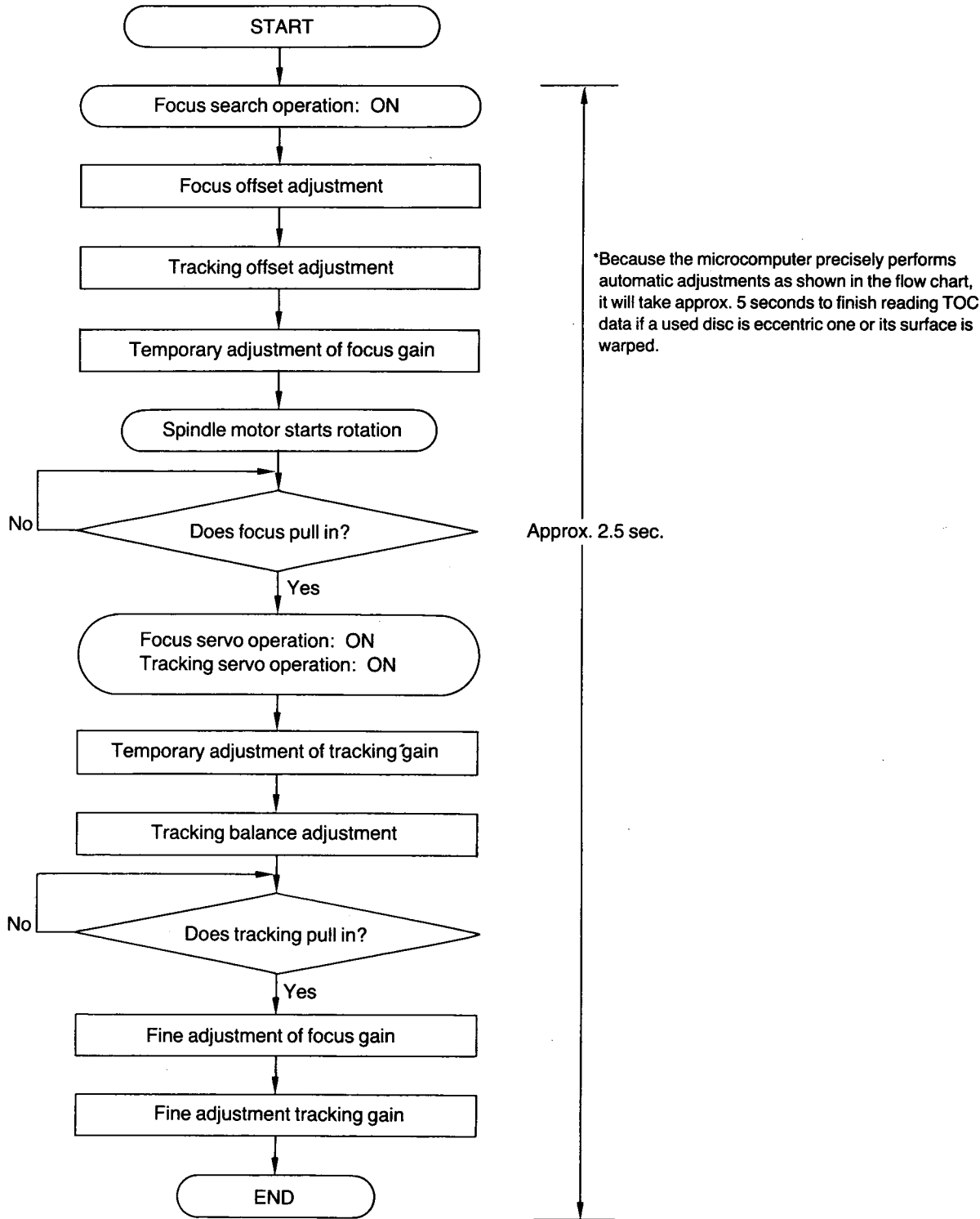
- The diagrams shown below represent differences between the analog servo and digital servo systems. The HEAD AMP. output signals (i.e., focus error and tracking error output signals) are analog. These analog signals are converted to the 8-bit digital signals through the MN6650. The MN6650 performs the following adjustments automatically; focus offset, tracking offset, focus gain, tracking gain, and tracking balance adjustments. The outputs from the MN6650 such as the focus coil driving signal, tracking coil driving signal, and traverse motor driving signal are converted to analog signals again and sent to the coils and motor to perform proper servo control for a disc.

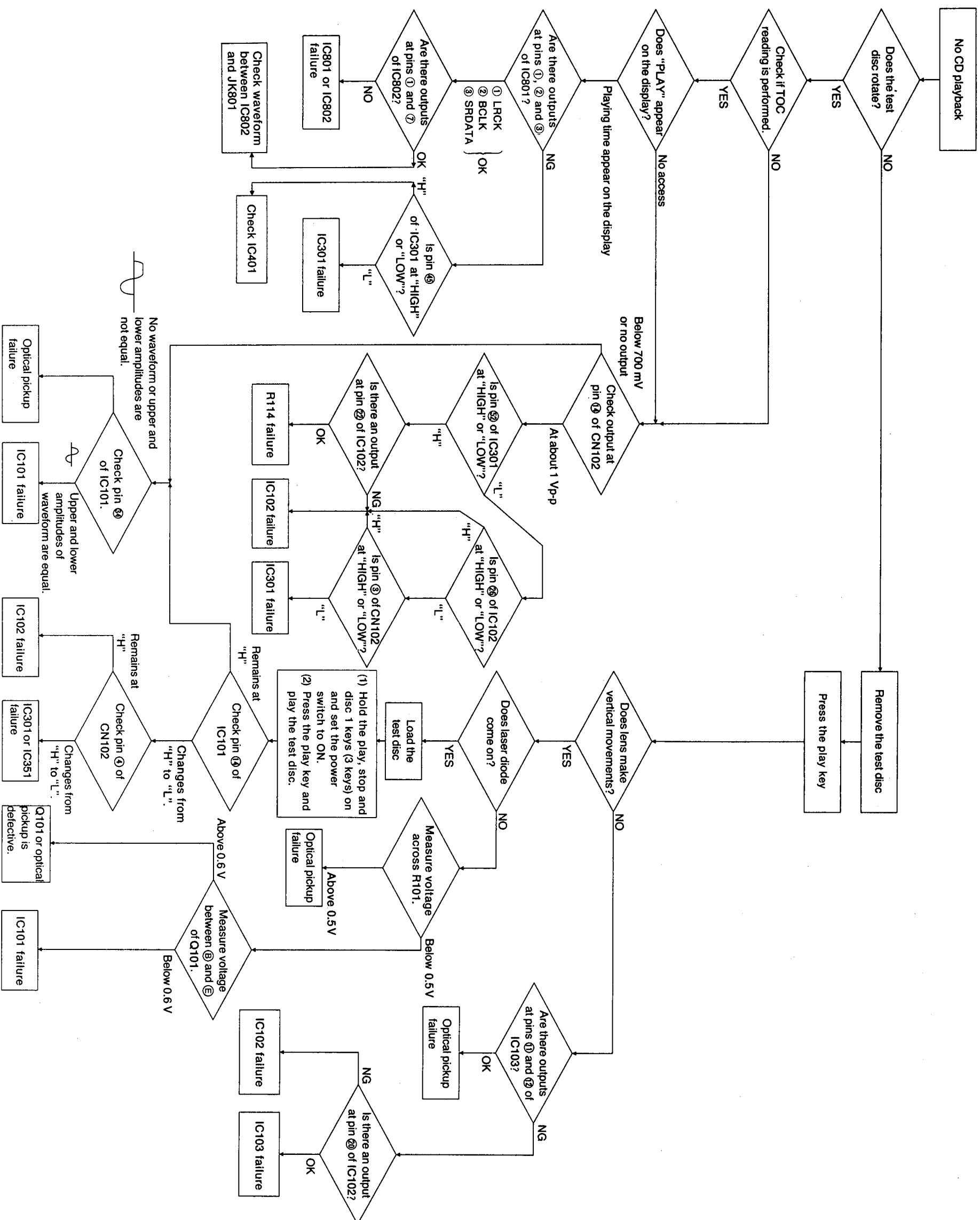


2. The servo processor IC MN6650 of the newly-developed digital servo circuit automatically performs the following adjustments which were originally adjusted manually in the conventional analog servo circuit:  
 (1) Focus offset, (2) Tracking offset, (3) Focus gain, (4) Tracking gain, and (5) Tracking balance. Therefore, you do not have to perform the above-mentioned electrical adjustments. The unit optimizes the servo for each loaded disc. [You must perform the best eye (PD balance) adjustment manually.]

The following flow chart shows the sequence of automatic adjustments.

•Flow chart on automatic adjustment sequence





## MEASUREMENTS AND ADJUSTMENTS

SL-PD627

SL-PD627

**Warning:** This product uses a laser diode. Refer to caution statements on page 2.

**Caution:** During adjustment, never connect CH-2 probe's GND to any place for it may short V-Ref. line.  
(Connect CH-1 probe's GND to specified TP, described in each section.)

### Measuring Instruments and Special Tools

- \* Test discs
  1. Playability test disc (SZZP1054C)
  2. Uneven test disc (SZZP1056C)
- \* Musical program disc (ordinary)
- \* Dual-beam oscilloscope with bandwidth of 30MHz or better (with EXT. trigger and 1:1 probe).
- \* Allen wrench (M2.0) (SZZP1101C)
- \* Allen wrench (M1.27)
- \* 0.9mm clearance gauge (RZZ0297)
- \* Filter
- \* Lock paint (RZZ0L01)

### PREPARATION

1. Remove the cabinet and front panel ass'y (refer to "disassembly instructions" Ref. No. 1, 2).
2. Set the power switch to ON and press the open/close key to close the loading drawer.
3. Press the play key and when the traverse deck reaches it's height position, set the power switch to OFF.
4. Remove the tray ass'y (refer to "disassembly instructions" Ref. No. 3).
5. Remove the clamp plate, yoke, magnet and clammer (refer to "disassembly instructions" Ref. No. 8, 9).
6. Place the test disc and secure it by using clammer ass'y. (Refer to Fig. 1)
7. Set the unit in the test mode as follows:  
(hold the **play**, **stop** and **disc-1** keys (3 keys) on and set the power switch to ON.)
8. Press the **play** key and play the test disc.
9. Follow the adjustment procedure.

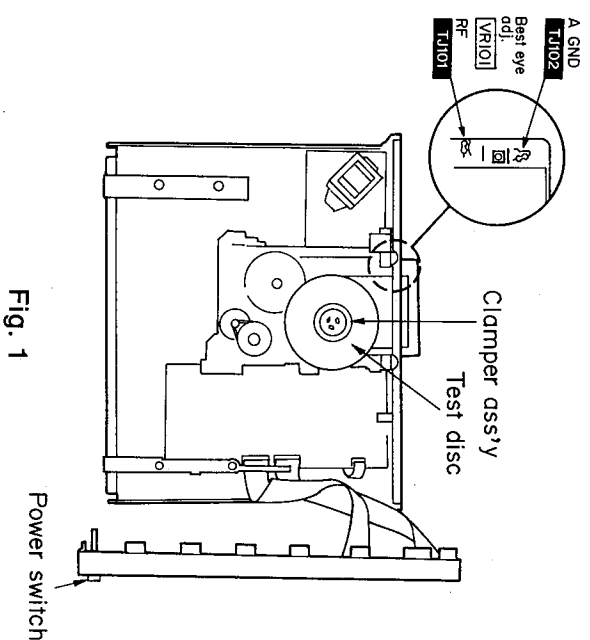


Fig. 1

### Adjusting Procedure

\* If you have replaced the optical pickup, spindle motor, or turntable, do the following adjustment:

#### (1) TURNABLE HEIGHT ADJUSTMENT

1. Insert the 0.9mm clearance gauge (RZZ0297) between the turntable and the loading base. (Refer to Fig. 2).
2. Tighten the turntable retention screw with the 1.27mm allen wrench.

3. Connect the oscilloscope's CH. 1 probe across **TP1** (+) and **TP2** (-) terminal via a filter (Refer to Fig. 3).

**Note:** For the connection of oscilloscope's CH. 1 probe to servo P.C.B. on foil side, refer to fig. 2.

**Oscilloscope setting:** VOLT ..... 500mV  
SWEEP ..... 5ms.

Input coupling..... DC

Adjust oscilloscope's DC zero balance.

5. Switch the play power ON, and play the test disc (SZZP1054C).
6. Measure the voltage amplitude of the signal on the oscilloscope.

7. Adjust the height until the voltage is  $0 \pm 1.0V$ .  
If the voltage exceeds  $+1.0V$ , lower turntable.  
If the voltage is below  $-1.0V$ , elevate the turn table.

**Note:** Measure the voltage as 0V as possible.

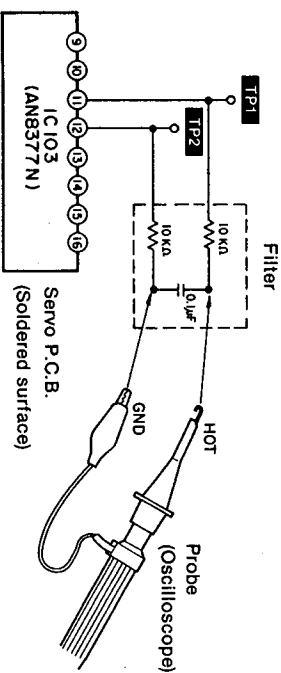
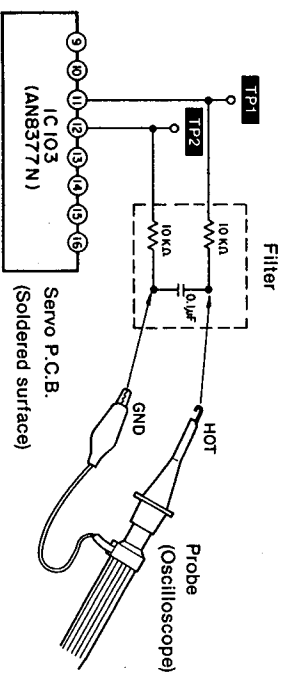


Fig. 2

Fig. 3



### (2) MECHANICAL ADJUSTMENT

1. Connect the oscilloscope's CH. 1 probe across **TP101** (+) and **TP102** (GND) on the servo P.C.B. (Refer to Fig. 4 on page 19)  
**Oscilloscope setting:** VOLT ..... 100mV  
SWEEP ..... 0.5μs.  
Input coupling..... AC
2. Switch the player power ON, and play track 7 on the test disc (SZZP1056C).  
(Playing any other track will prevent the HEX screws from being accessed.)
3. Leave the player in play mode and place it as shown Fig. 3 on page 19.
4. Alternately adjust the two HEX screws with the 2.0mm allen wrench (SZZP1101C) until the vertical fluctuation of RF signal is minimized and the eye pattern is most stretched. (Refer to Fig. 4)
5. After completing the adjustment, lock the HEX screws with lock paint (RZZ0L01).

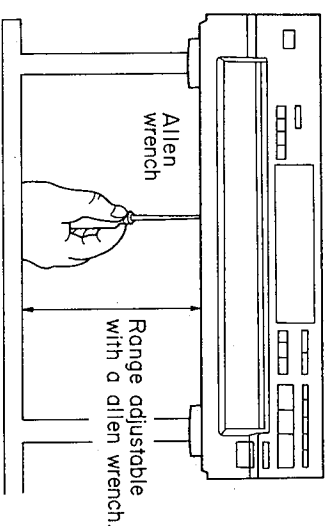
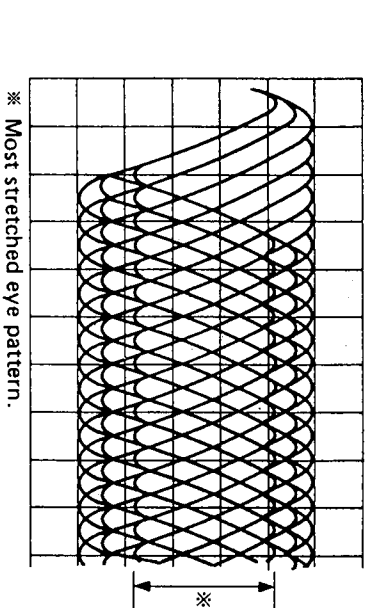
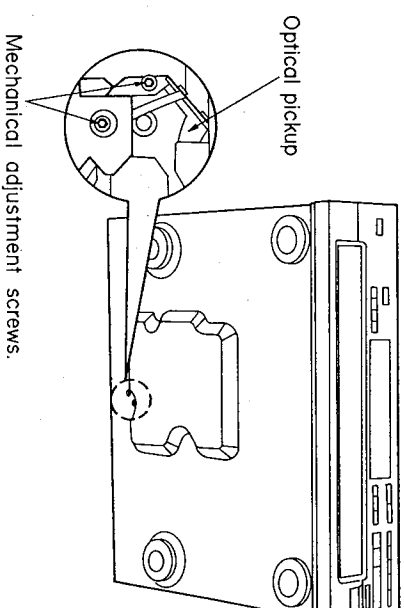


Fig. 4

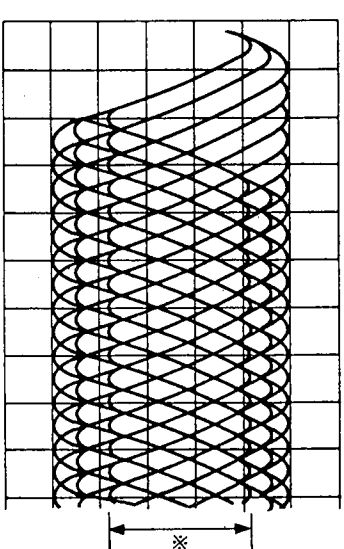


\* Most stretched eye pattern.



### (3) BEST EYE (PD BALANCE) ADJUSTMENT

1. Connect the oscilloscope's CH. 1 probe across **TP101** (+) and **TP102** (GND) on the servo P.C.B. (Refer to Fig. 4 on page 19)  
**Oscilloscope setting:** VOLT ..... 100mV  
SWEEP ..... 0.5μs.  
Input coupling..... AC
2. Switch the player power ON, and play the 1KHz (track 1) on the test disc (SZZP1054C).
3. Adjust **VR101** until the vertical fluctuation of RF signal is minimized and the eye pattern is most stretched. (Refer to Fig. 5)



\* Most stretched eye pattern.

Fig. 5

### (4) CHECK OF PLAY OPERATION AFTER ADJUSTMENT

#### \* Checking Skip Search

1. Play an ordinary musical program disc.
2. Press the skip button to check for normal skip search operation (in both the forward and reverse directions).

#### \* Checking Manual Search

1. Play an ordinary musical program disc.
2. Press the manual search button to check for smooth manual search operations at either low or high speed (in both the forward and reverse directions).

#### \* Checking Playability

1. Play the 0.7mm black dot and the 0.7mm wedge on the playability test disc (SZZP1054C) and verify that no sound skip or noise occurs.
2. Play the middle tracks of the uneven test disc (SZZP1056C) and verify that no sound skip or noise occurs.



## ■ TERMINAL FUNCTION OF IC'S

### • IC101 (AN8800SCE2): Servo amp

Pin No.	Mark	I/O Division	Function
1	LDG	I	APC loop gain select
2	LDP	I	APC monitor PD polarity select (Not used, open)
3	LD	O	Laser power auto control output
4	LPD	I	LD power monitor PD signal
5	GND	—	GND terminal
6	LDON	I	LD APC ON/OFF ("H": ON, "L": OFF)
7	AMP I	I	RF signal (X30 amp)
8	AMP O	O	
9	RF IN	I	RF AGC signal input
10	RF EQ	—	GND terminal
11	C. AGC	I	AGC detection capacitor input
12	ARF	O	RF signal output
13	C. SBDO	I	Dropout detection capacitor input
14	RF DET	O	RF detection signal ("L": detecting)
15	BDO	O	Dropout detection output
16	V <sub>CC</sub>	I	Power supply terminal
17	SDO	O	Dropout detection pulse output
18	VAD+	O	Power supply terminal for A/D converter (+)
19	VREF	O	Reference voltage output
20	VAD-	O	Power supply terminal for A/D converter (-)
21	OFTR	O	Off track detection ("H": det.)

Pin No.	Mark	I/O Division	Function
22	PLAY	I	Play signal ("H": ON, "L": OFF)
23	WVEL	I	Double velocity ("H": double, "L": single)
24	TES	I	Tracking error shunt ("H": shunt, "L": output)
25	PTO	O	Potential amp output
26	PTI	I	Potential amp input
27	PBO	O	Potential buffer output
28	POT	I	Potential buffer input
29	CROSS	O	Tracking error zero cross output
30	TE	O	Tracking error signal
31	TE BAL	I	Oscillation det. signal
32	TBAL	I	Tracking balance adj. input
33	VDET	O	Oscillation det. signal ("H": det.)
34	FE	O	Focusing error signal
35	FBL 2	I	Focusing balance 2
36	FBL 1	I	Focusing balance 1
37	V <sub>CC</sub>	I	Power supply terminal
38	GND	—	GND terminal
39	PDBD	I	Photo detector Bch input with delay
40	PDA	I	Photo detector Ach input without delay
41	PDB	I	Photo detector Ach input with delay
42	PDAD	I	Photo detector Bch input without delay

## • IC102 (MN6650A): Digital servo processor

Pin No.	Mark	I/O Division	Function
1	TES	O	Tracking error shunt signal ("H": shunt)
2	PLAY	O	Play signal ("H": play)
3	/RFDET	I	RF det. signal ("L": det.)
4	DO	I	Dropout signal ("H": dropout)
5	OFT	I	Off track signal ("H": off track)
6	ARF	I	RF signal input
7	WVEL	O	Double velocity status signal ("H": double)
8	PBO	I	Potensio buffer signal (analog input)
9	TE	I	Tracking error signal (analog input)
10	FE	I	Focus error signal (analog input)
11	VR2	I	Reference voltage for A/D (Low)
12	VR1	I	Reference voltage for A/D (High)
13	LDON	O	Laser power control ("H": ON)
14	V <sub>SS</sub>	—	GND terminal
15	AV <sub>SS</sub>	—	GND terminal
16	AV <sub>DD</sub>	I	Power supply terminal
17	V <sub>DD</sub>	I	Power supply terminal
18	TRV	O	Traverse servo control output
19	TVD	O	Traverse drive signal output
20	FOD	O	Focus drive signal output
21	TRD	O	Tracking drive signal output

Pin No.	Mark	I/O Division	Function
22	KICK	O	Kick pulse output
23	/TEST	I	Test terminal
24	V <sub>SS</sub>	—	GND terminal
25	CLVS	I	Spindle servo phase synchro signal ("H": CLV, "L": Rough servo)
26	/TRON	O	Tracking servo ON signal ("L": ON)
27	MDATA	I	Command data signal
28	MCLK	I	Command clock signal
29	MLD	I	Command load signal ("L": LOAD)
30	SENSE	O	Sense signal
31	/FLOCK	O	Optical servo condition (focus) output
32	/TLOCK	O	Optical servo condition (tracking) output
33	/RST	I	Reset signal ("L": reset)
34	XI	I	Clock input (f= 16.9344 MHz)
35 38	T0 T3	O	Test terminal (Ordinal: open)
39 41	T4 T6	I	Test terminal (Ordinal: L)
42	VDET	I	Oscillation det. signal ("H": det.)
43	TBAL	O	Tracking balance adj. output
44	TRCRS	I	Track cross signal input

• IC103 (AN8377N): Traverse motor drive

Pin No.	Mark	I/O Division	Function
1	P V <sub>CC</sub>	I	Drive power supply
2	V <sub>CC</sub>	I	Power supply terminal
3	TB	O	External transistor base driving output
4	VMON	O	Voltage output (connected to GND)
5	TVD1	I	Traverse error signal input
6	FD1	I	Focus error signal input
7	TD1	I	Tracking error signal input
8	VREF	I	Reference voltage input

Pin No.	Mark	I/O Division	Function
9	TD-	O	Non-inverting output of focus driver
10	TD+	O	Inverting output of focus driver
11	FD-	O	Non-inverting output of tracking driver
12	FD+	O	Inverting output of tracking driver
13	TVD-	O	Non-inverting output of traverse driver
14	TVD+	O	Inverting output of driver
15	RESET	O	Reset signal output (Not used, open)
16	PC	I	PC input (connect to GND)

• IC801 (MN6475A-T1): Digital filter & D/A converter

Pin No.	Mark	I/O Division	Function
1	LRCK	I	L/R discriminating signal
2	BCLK	I	Serial bit clock input
3	SRDATA	I	Serial data output (MSB first)
4	COT 1	I	Test terminal (Ordinaly: L)
5	COT 2		
6	TEST		
7	V <sub>DD</sub>	I	Digital power supply terminal
8	X2	O	Clock terminal (F=33.8688 MHz)
9	X1	I	
10	DV <sub>SS</sub>	—	Digital GND terminal
11	DV <sub>DD</sub> L	I	Analog power supply terminal 1
12	OUT. L	O	Analog signal output 1
13	AV <sub>SS</sub> L	—	Analog GND terminal
14	AV <sub>SS</sub> R		

Pin No.	Mark	I/O Division	Function
15	OUT. R	O	Analog signal output 2
16	AV <sub>DD</sub> R	I	Analog power supply terminal 2
17	/RST	I	Reset signal input (Active: L)
18	PWM	O	PWM output (TP... "H": output "L": High impedance) (Not used, open)
19	TP	I	Test terminal (ordinaly: L)
20	WVEL	I	Double velocity ("H": double, "L": single)
21	DEMPH	I	Digital de-emphasis ON/OFF ("H": ON)
22	CSEL	I	Clock frequency select of CK 192 (Not used, connected to GND)
23	192FS	O	192fs (8.4672 MHz) signal output (Not used, open)
24	384FS	O	Clock output terminal (384FS=16.9344 MHz)

## • IC301 (MN6626): Digital signal processor

Pin No.	Mark	I/O Division	Function
1	AVSS	—	GND terminal
2	IREF	I	Reference current input
3	ARF	I	RF signal input
4	DRF	I	DSL bias terminal (Not used, open)
5	DSLIF	I/O	DSL loop filter stermental
6	PLLIF	I/O	PLL loop filter terminal
7	AVDD	I	Power supply terminal
8	RSEL	I	RF signal polarity setting terminal (Not used, connected to VDD)
9 16	TBUS7 TBUS0	O	Test terminal
17	FLAG	O	Flag terminal (Not used, open)
18	IPFLAG	O	Interpolation flag terminal (Not used, open)
19	FCLK	O	Crystal frame clock (Not used, open)
20	BYTCK	O	Byte clock (Not used, open)
21	WDCK	O	Word clock (Not used, open)
22	/RST	I	Reset terminal
23	TX	O	Digital audio signal (Not used, open)
24	LDG	O	Lch deglitch signal (Not used, open)
25	RDG	O	Rch deglitch signal (Not used, open)
26	SRDATA	O	Serial data output (MSB first)
27	SCK	O	Serial bit clock output
28	LRCK	O	L/R discriminating signal
29	XCK	O	Crystal OSC terminal (f=16.9344MHz) (Not used, open)
30	PMCK	O	Frequency division clock signal (Not used, open) $(f = \frac{1}{192} \times CK = 88.2\text{kHz})$
31	CSEL	I	Test terminal (Connected to GND)
32	PSEL		
33	X1	I	Crystal OSC terminal (f=16.9344MHz)
34	X2	O	Crystal OSC terminal (f=16.9344MHz) (Not used, open)
35	VSS	—	GND terminal
36	SUBQ	O	Sub-code Q data
37	SQCK	I	Sub-code Q register clock

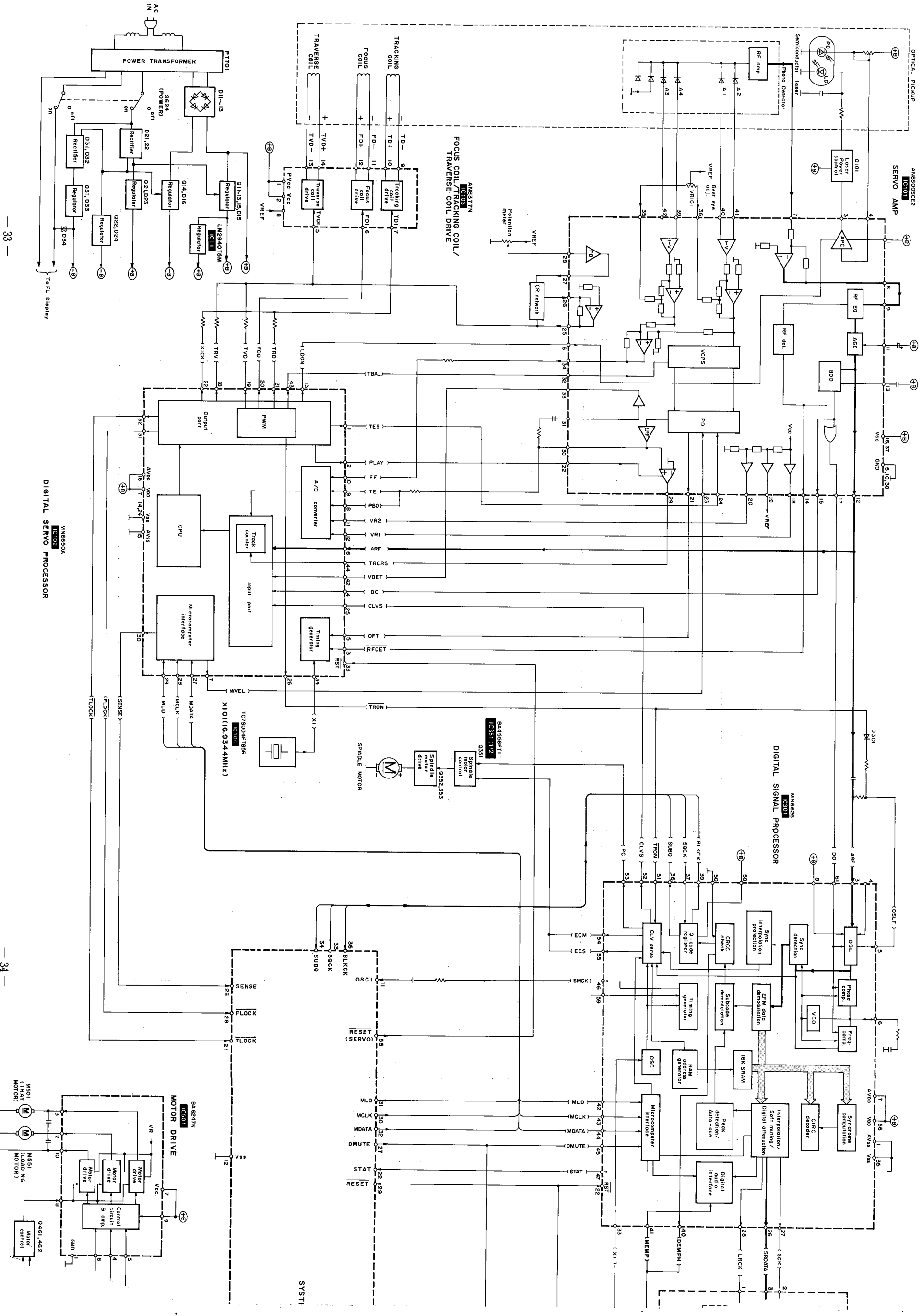
Pin No.	Mark	I/O Division	Function
38	/CLDCK	O	Sub-code frame clock (f=735kHz) (Not used, open)
39	BLKCK	O	Sub-code block clock (f=75Hz)
40	DEMPH	O	De-emphasis ON signal ("H": ON)
41	MEMP	I	Emphasis signal
42	MLD	I	Command load signal ("L": LOAD)
43	MCLK	I	Command clock signal
44	MDATA	I	Command data signal
45	D MUTE	I	Muting input ("H": MUTE)
46	SMCK	O	System clock (f=4.2336MHz)
47	STAT	O	Status signal (CRC, CUE, CLVS, TTSTOP, FCLV, SQOK)
48	CRC	O	Sub-code CRC check terminal ("H": OK, "L" NG) (Not used, open)
49	SUBC	O	Sub-code serial output data (Not used, open)
50	SBCK	I	Sub-code serial output clock (Not used, open)
51	/TRON	I	Tracking servo ON signal ("L": ON)
52	CLVS	O	Turntable servo phase synchro signal ("H": CLV, "L": Rough servo)
53	PC	O	Turntable motor ON signal ("L": ON)
54	ECM	O	Turntable motor drive signal (Forced mode)
55	ECS	O	Turntable motor drive signal (Servo error signal)
56	VDD	I	Power supply terminal
57	/TEST	I	Test terminal (Normal: "H")
58	SSEL	I	"SUBQ" terminal mode select ("H": Q code buffer)
59	MSEL	I	"SMCK" terminal frequency select ("L": SMCK=4.2336MHz)
60	RESY	O	Re-synchronizing signal of frame sync. (Not used, open)
61	DO	I	Drop-out detection signal ("H": Drop-out)
62	EFM	O	EFM signal (Not used, open)
63	PCK	O	PLL extract clock (f=4.3218MHz) (Not used, open)
64	PDO	O	Phase comparated signal of EFM and PCK (Not used, open)

## • IC401 (MN187164PME1): System control &amp; FL drive

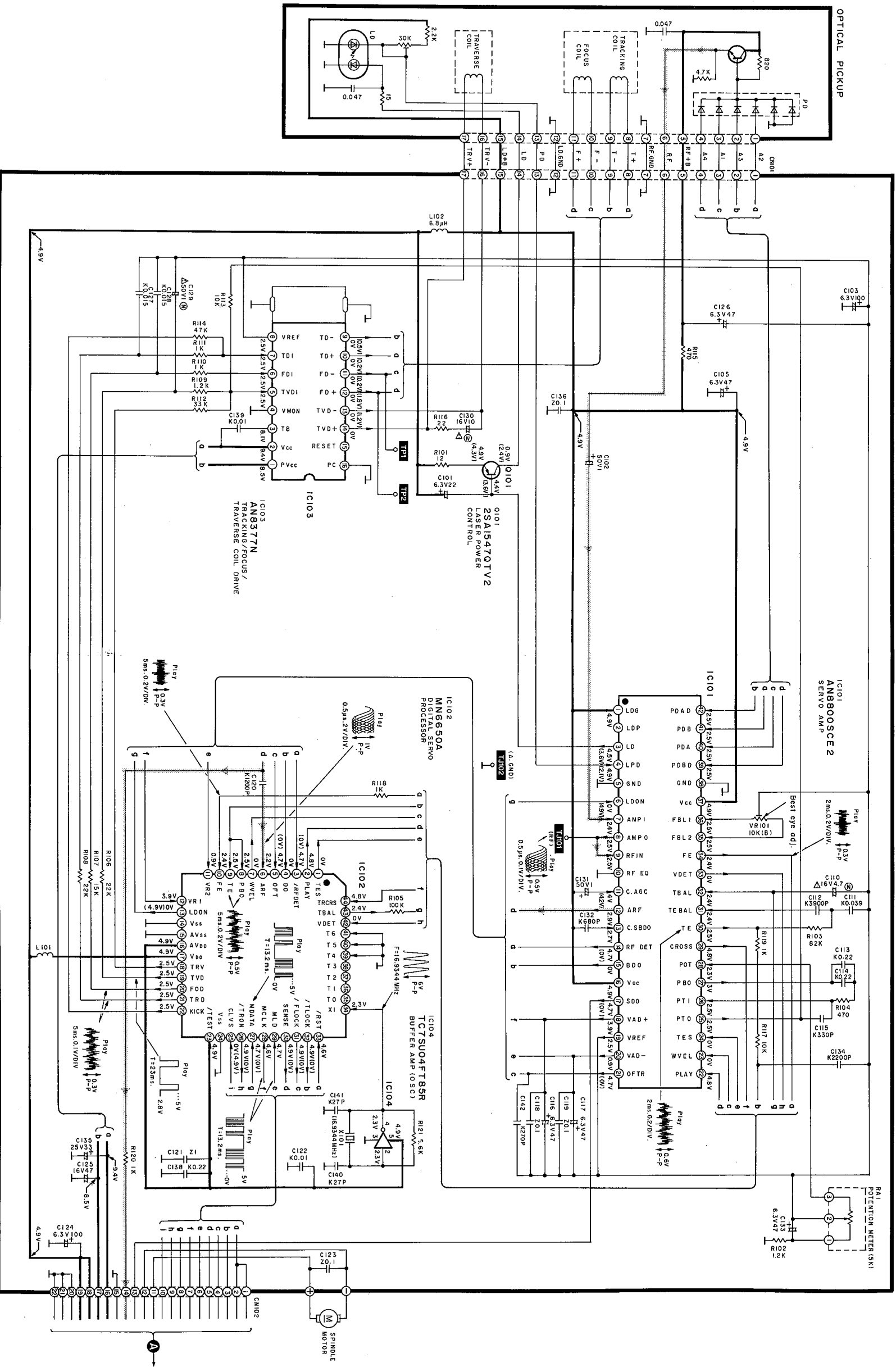
Pin No.	Mark	I/O Division	Function
1 } 7	S7 } S1	O	FL segment signal
8	V <sub>PP</sub>	I	Power supply terminal
9	V <sub>DD</sub>		
10	OSC2	I	(Not used, open)
11	OSC1	I	Clock input terminal (4.2336 MHz)
12	V <sub>SS</sub>	—	GND terminal
13	XI	I	(Not used, connected to GND)
14	XO	O	(Not used, open)
15	SYNC	O	Synchro edit control signal (Not used, open)
16	REC. E	I	Synchro edit control signal
17	LOAD	O	Motor control signal
18	TURN		
19	DIRECT		
20	DISC	I	Disc det. terminal
21	/TLOCK	I	Optical servo condition (tracking) input
22	STAT	I	Status signal (CRC, CUE, CLVS, TTSTOP, FCLV, SQOK)
23	REMOCON	I	Remote control signal
24	SPEED	I	Loading motor speed sensor signal
25	PWM	O	Motor control signal
26	SENSE	I	Sense signal

Pin No.	Mark	I/O Division	Function
27	DMUTE	O	Muting control signal
28	/FLOCK	I	Optical servo condition (focus) input
29	/RESET	I	Reset signal input
30	MCLK	O	Command clock signal
31	MLD	O	Command load signal ("L": LOAD)
32	MDATA	O	Command data signal
33	SQCK	O	Sub-code Q register clock
34	SUBQ	I	Sub-code Q data
35	BLKCK	I	Sub-code block (f=75 Hz)
36	NC	—	Not connected
37	CM	—	Not used, connected to GND
38 } 45	KEYIN8 } KEYIN1	I	Key return signal
46 } 54	G1 } G9	O	FL grid signal
55	/RESET	O	Reset signal for servo
56	OPEN	I	Open detect terminal
57	KEYOUT5	—	(Not used, open)
58 } 61	KEYOUT4 } KEYOUT1	O	Key scan signal
62 } 64	S10 } S8	O	FL segment signal



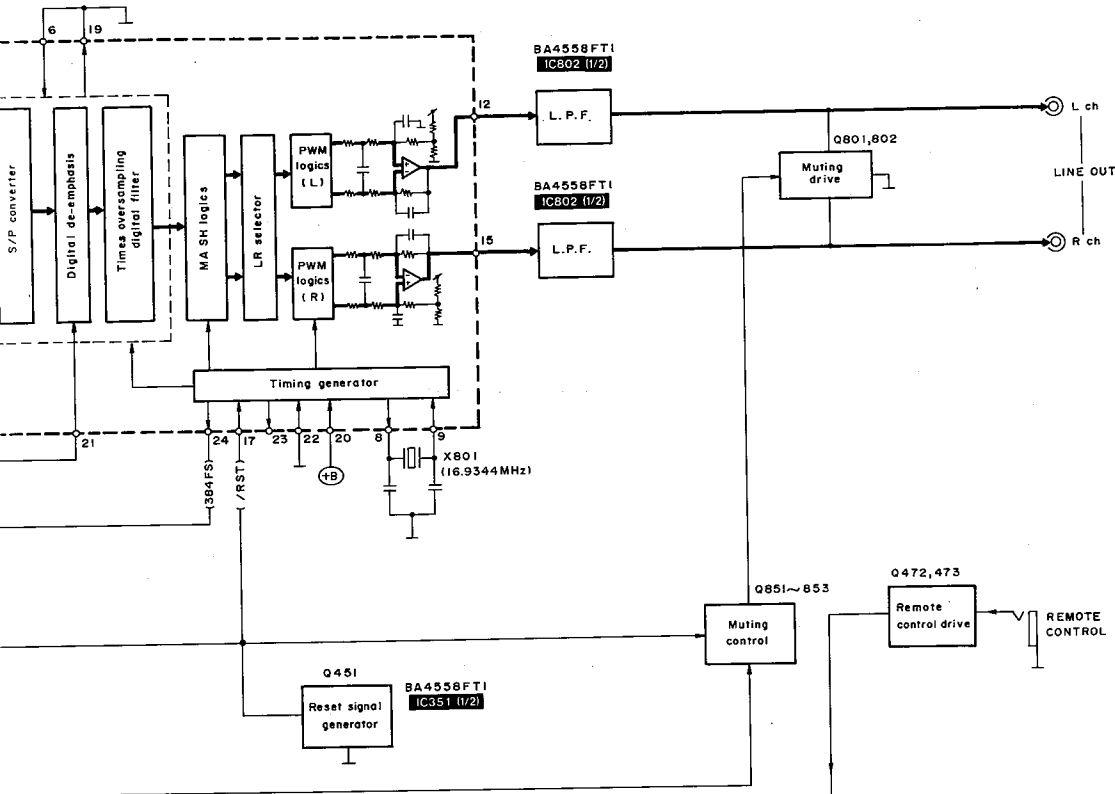


A SERVO CIRCUIT

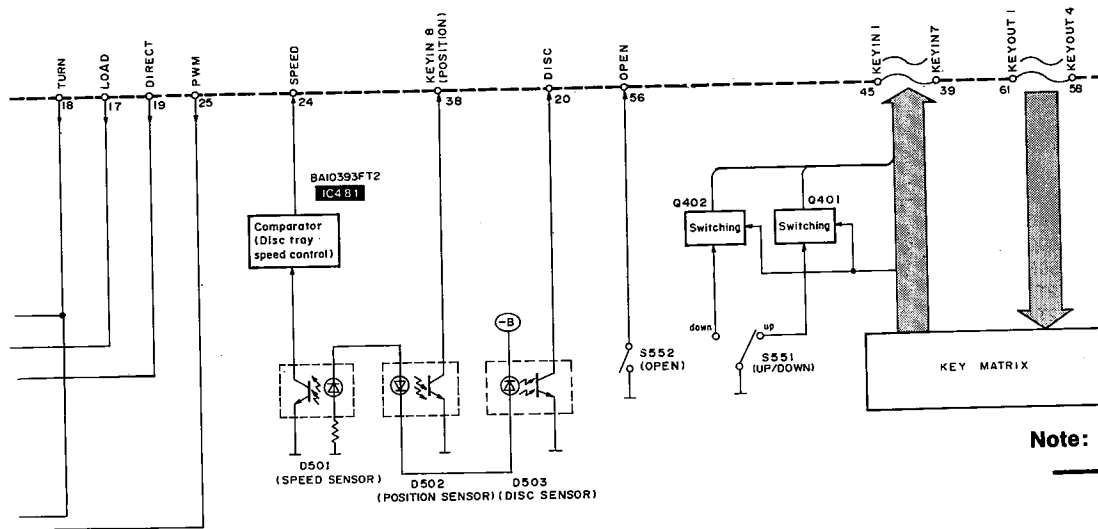




MN6475A-T1  
**IC301**  
 DIGITAL FILTER & D/A CONVERTER



MN187164PME1  
**IC401**  
 REM CONTROL & FL DRIVE



**Note:**  
 → Digital/audio signal

# SCHEMATIC DIAGRAM (Parts list on pages 48, 49, 55, 56.)

(This schematic diagram may be modified at any time with development of new technology.)

**Note:**

- S551 : Up/down det. switch.
  - S552 : Open det. switch.
  - S601 : Spiral (SPIRAL) switch.
  - S602 : One disc random (ONE DISC) switch.
  - S603 : Full random (FULL) switch.
  - S604 : Repeat (REPEAT) switch.
  - S605 : Time mode (TIME MODE) switch.
  - S608, 609 : Search (SEARCH) switches.  
[S608: ◀◀, S609: ▶▶]
  - S610~614 : Disc (DISC 1~5) switches.  
[S610: 1, S611: 2, S612: 3, S613: 4, S614: 5]
  - S615 : Program mode (PROGRAM MODE) switch.
  - S616, 617 : Skip (SKIP) switches.  
[S616: ◀◀, S617: ▶▶]
  - S618 : Disc skip (DISC SKIP) switch.
  - S619 : Loading drawer open/close  
(▲ OPEN/CLOSE) switch.
  - S620 : Stop (■ STOP) switch.
  - S621 : Pause (▢ PAUSE) switch.
  - S622 : Play (▶ PLAY) switch.
  - S624 : Power (POWER) switch in "on" position.
- The voltage value and waveforms are the reference voltage of this unit measured by DC electronic voltmeter (high impedance) and oscilloscope on the basis of chassis.
- Accordingly, there may arise some error in voltage values and waveforms depending upon the internal impedance of the tester or the measuring unit.
- \* The parenthesized are the values of voltage generated during playing (Test disc 1kHz, L+R, 0dB), others are voltage values in stop mode.

• Important safety notice:

Components identified by  $\Delta$  mark have special characteristics important for safety. When replacing and of these components, use only manufacturer's specified parts.

• The supply part number is described alone in the replacement parts.

Part No.	Production Part No.	Supply Part No.
IC11	LM2940T5M	LM2940T5
IC102	MN6650A	MN6650
IC351, 802	BA4558FT1	SVIBA4558F

- / : Positive voltage lines and negative voltage lines.
- : audio signal lines.

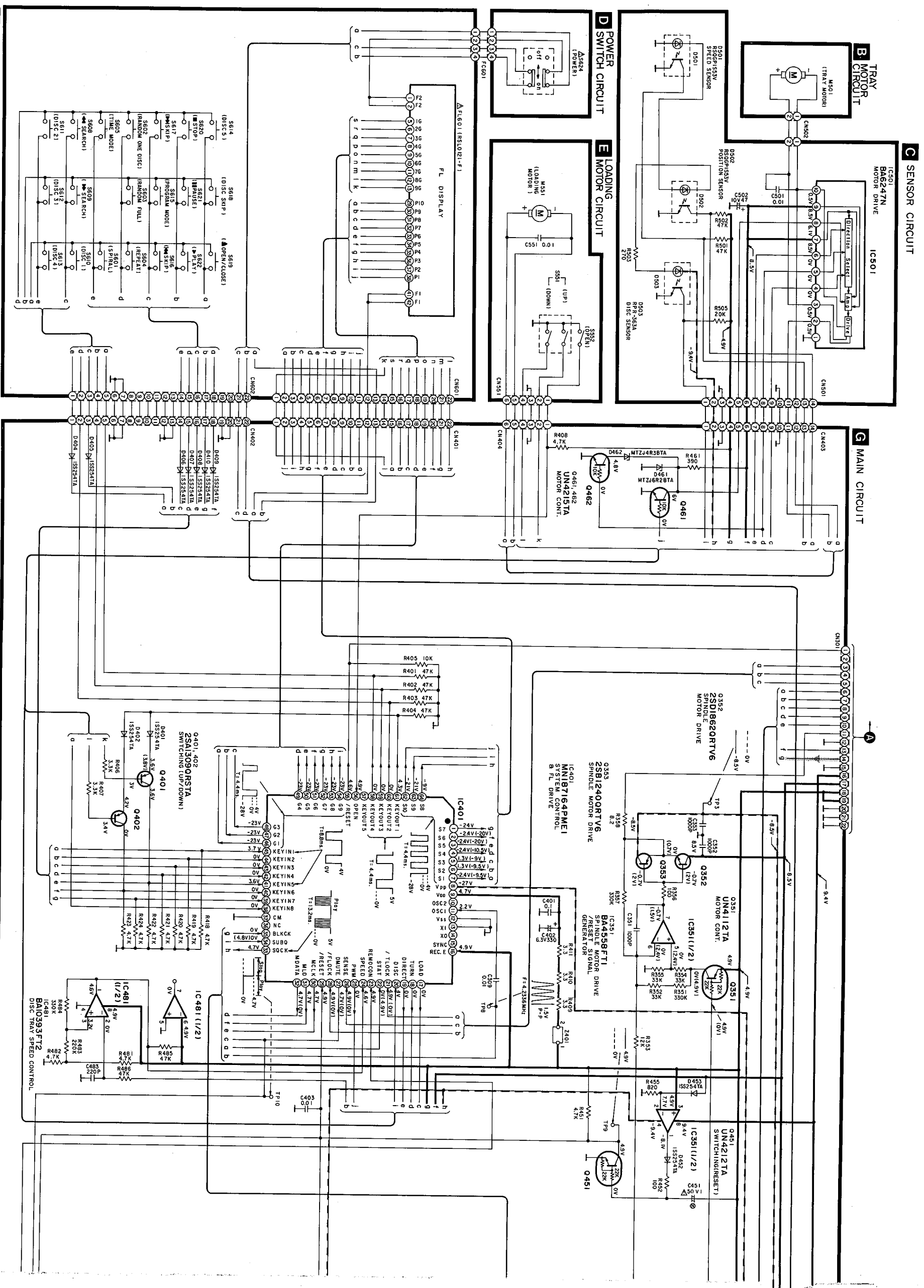
**Caution!**

IC and LSI are sensitive to static electricity. Secondary trouble can be prevented by taking care during repair.

- Cover the parts boxes made of plastics with aluminum foil.
- Ground the soldering iron.
- Put a conductive mat on the work table.
- Do not touch the pins of IC or LSI with fingers directly.

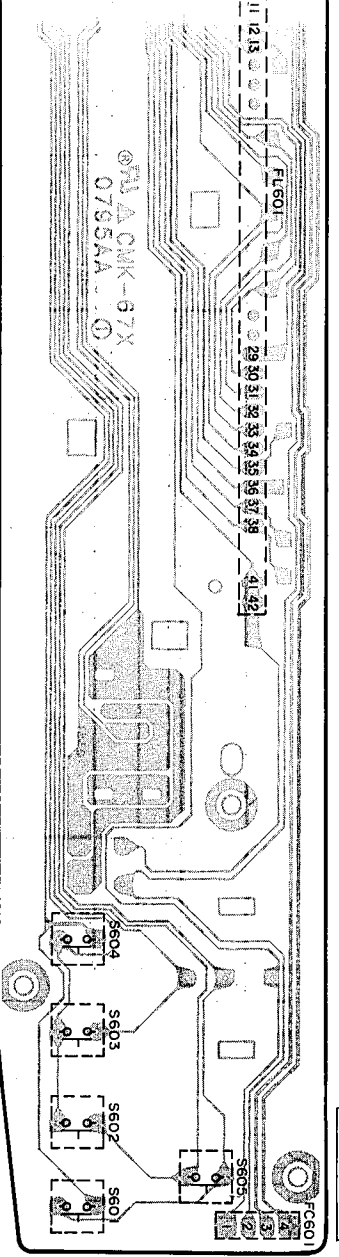
• Terminal guide of IC's, transistors and diodes

<p>BA4558FT1 BA10393FT2</p>	<table border="1"> <tr> <td>MN6475A-T1</td> <td>24 Pin</td> </tr> <tr> <td>AN8800SCE2</td> <td>42 Pin</td> </tr> </table>	MN6475A-T1	24 Pin	AN8800SCE2	42 Pin	<p>TC7SU04FT85R</p>	<p>AN8377N</p>	<p>BA6247N</p>		
MN6475A-T1	24 Pin									
AN8800SCE2	42 Pin									
<table border="1"> <tr> <td>MN6650A</td> <td>44 Pin</td> </tr> <tr> <td>MN6626</td> <td>64 Pin</td> </tr> <tr> <td>MN187164PME1</td> <td>64 Pin</td> </tr> </table>	MN6650A	44 Pin	MN6626	64 Pin	MN187164PME1	64 Pin	<p>LM2940T5M</p> <p>1. Vin 2. GND 3. Vout</p>	<p>1SS254TA SVD1SR35200V</p> <p>Anode Cathode</p>		<p>2SA1547QTV2 2SB1238QSTV6 2SB1240QRTV6 2SD1862QRTV6</p>
MN6650A	44 Pin									
MN6626	64 Pin									
MN187164PME1	64 Pin									
		<p>MTZJ4R3BTA MTZJ6R2BTA MTZJ8R2CTA MTZJ9R1CTA MTZJ10CTA MTZJ27DTA</p> <p>Anode Cathode</p>	<p>RSQGP1S53V</p>	<p>RPR-363A</p>						



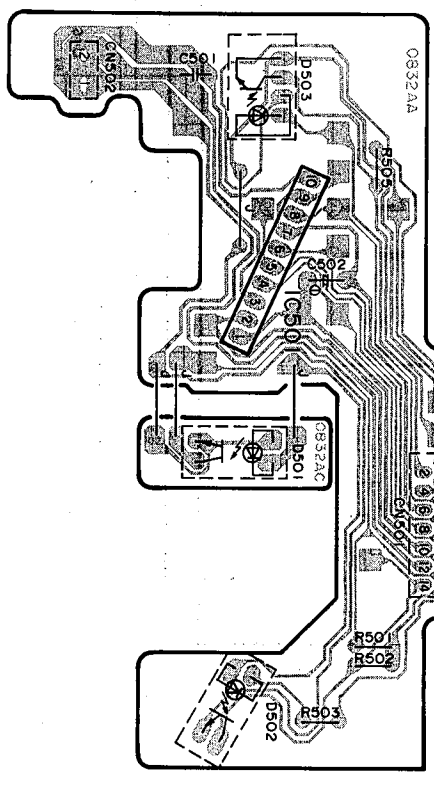
F OPERATION CIRCUIT

ON P.C.B.

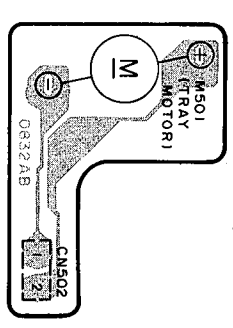


SL-PD627 SL-PD627

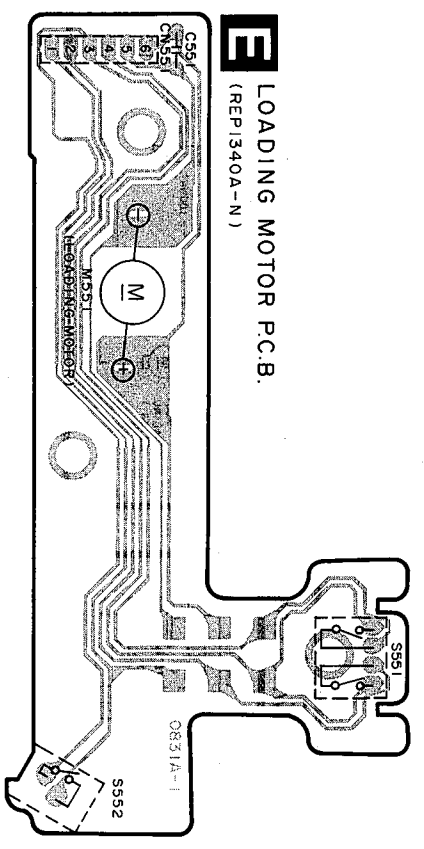
**C** SENSOR P.C.B.  
(REPI341A-N)



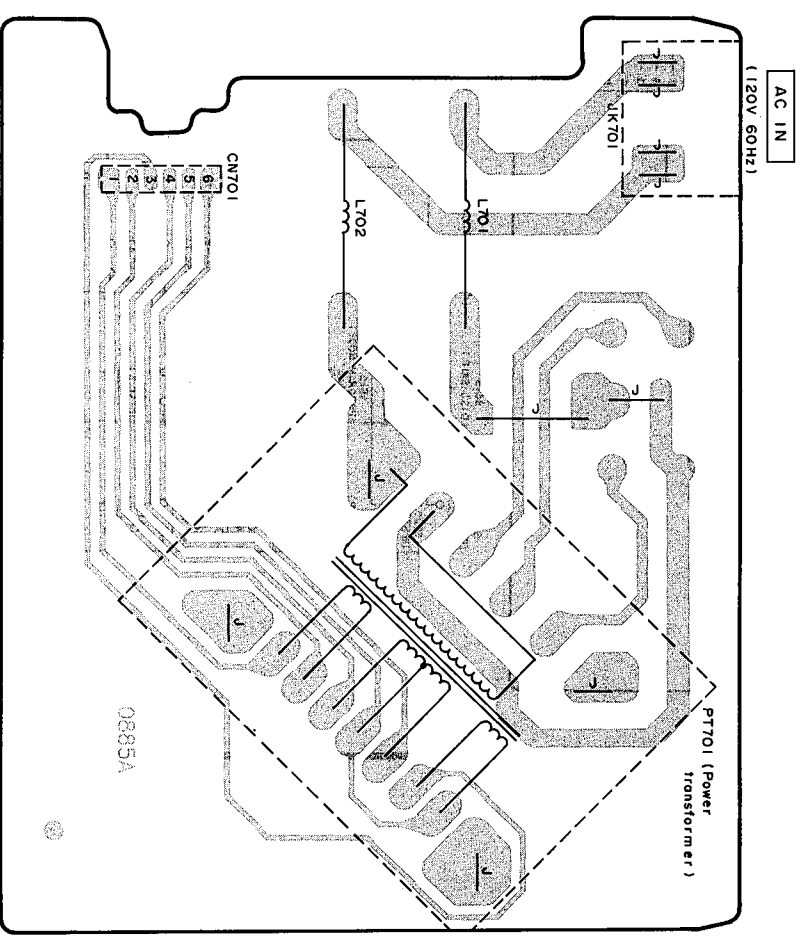
**B** TRAY MOTOR P.C.B.  
(REPI341A-N)



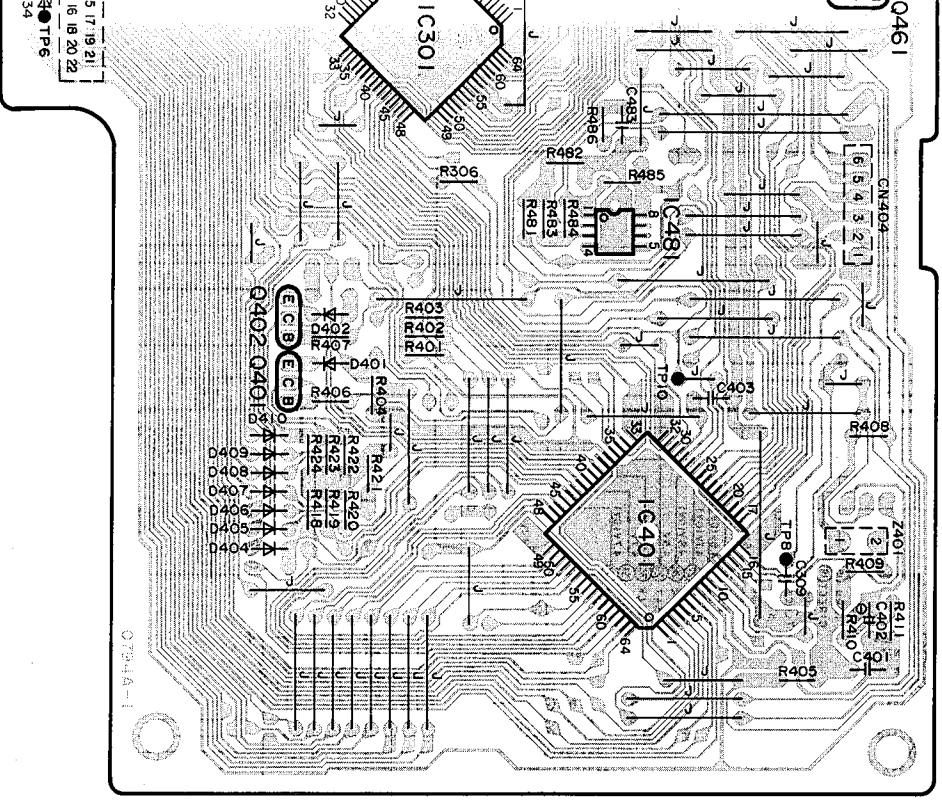
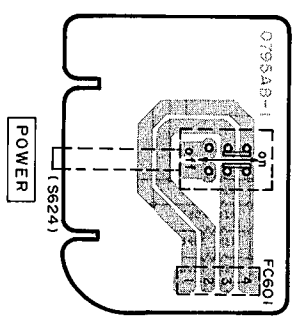
**E** LOADING MOTOR P.C.B.  
(REPI340A-N)



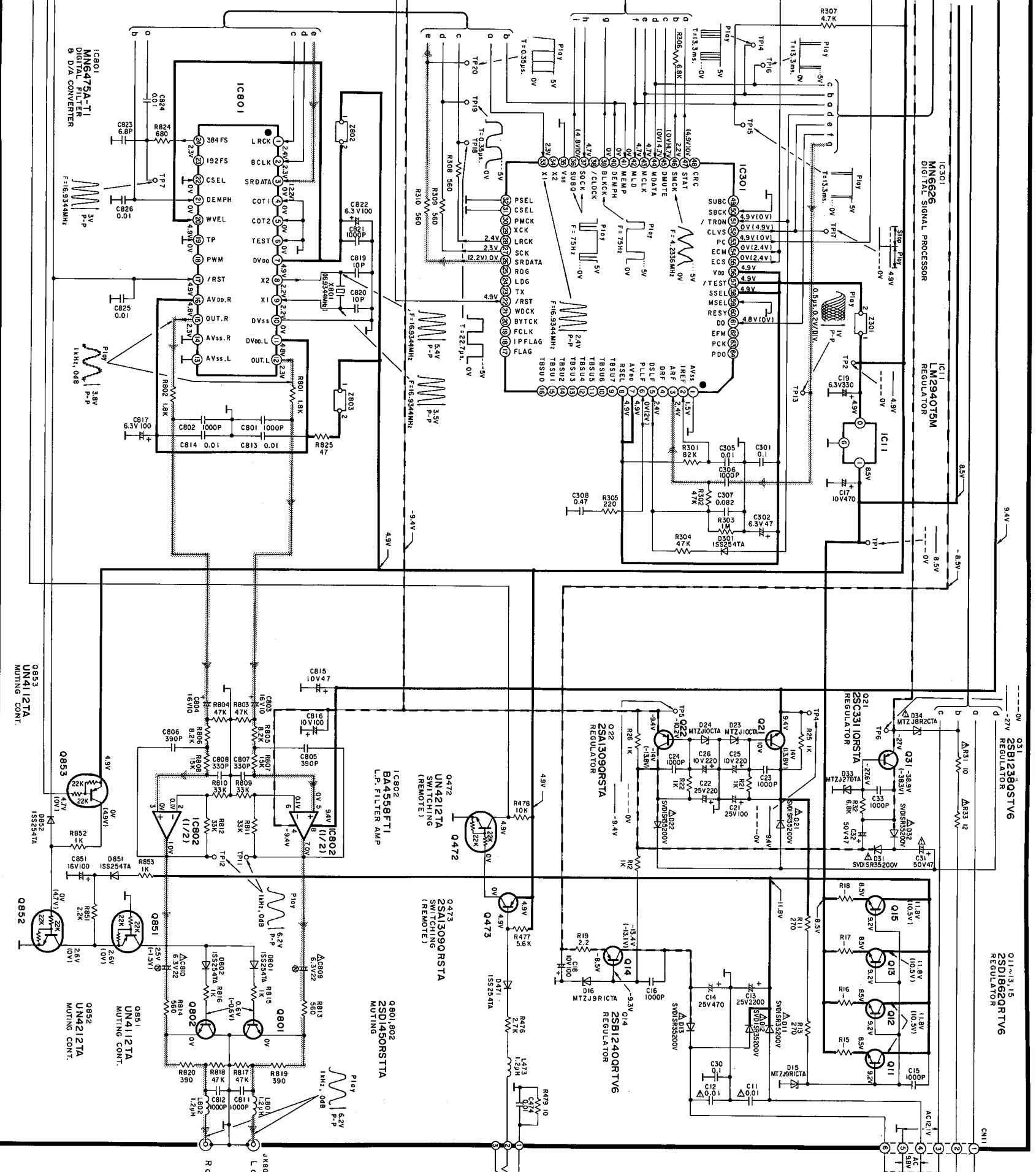
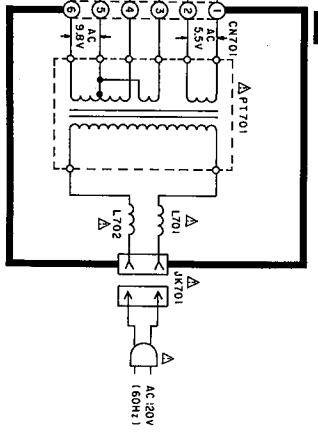
**H** POWER SUPPLY P.C.B.  
(REPI359A-P)



**D** POWER SWITCH P.C.B.  
(REPI274A-S)



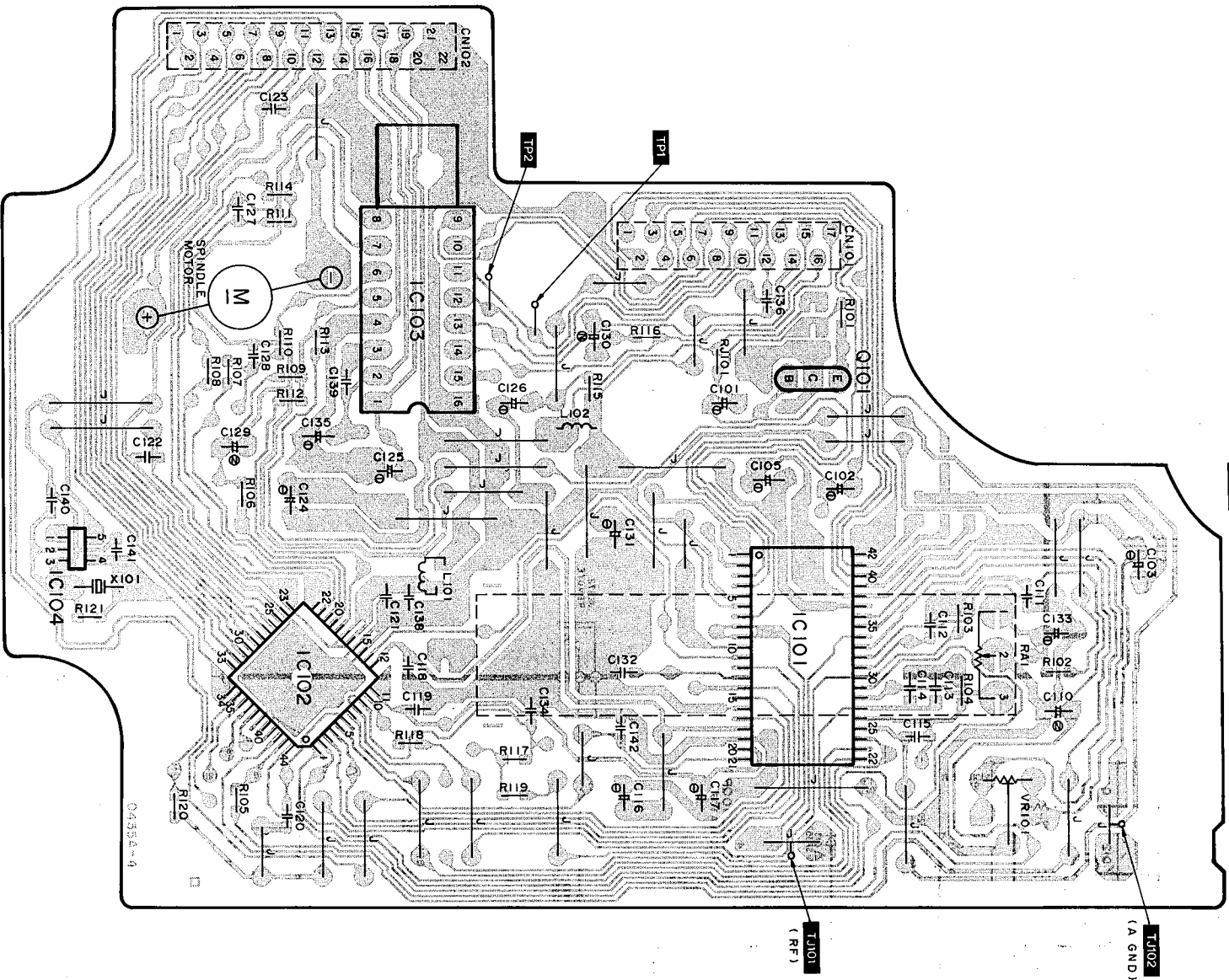
**H** POWER SUPPLY CIRCUIT



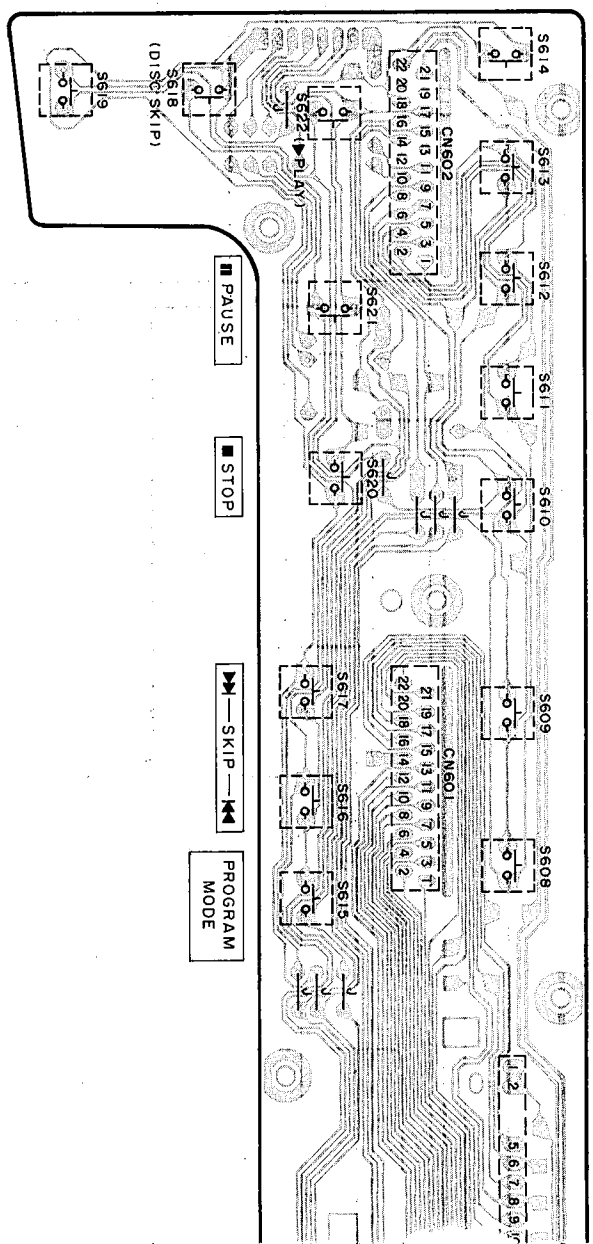
PRINTED CIRCUIT BOARDS

SL-PD627 SL-PD627

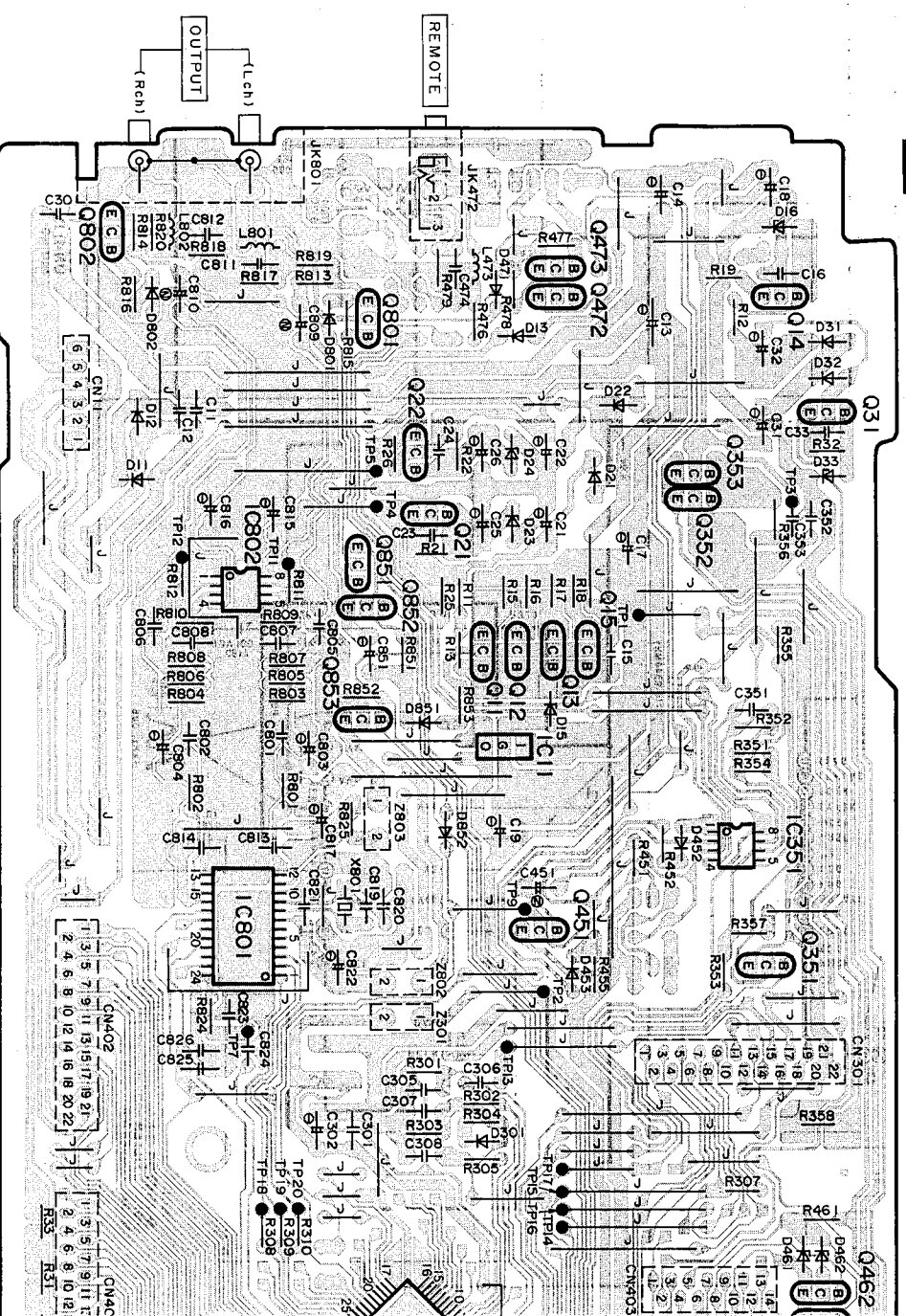
**A** SERVO P.C.B.  
(REP0766)



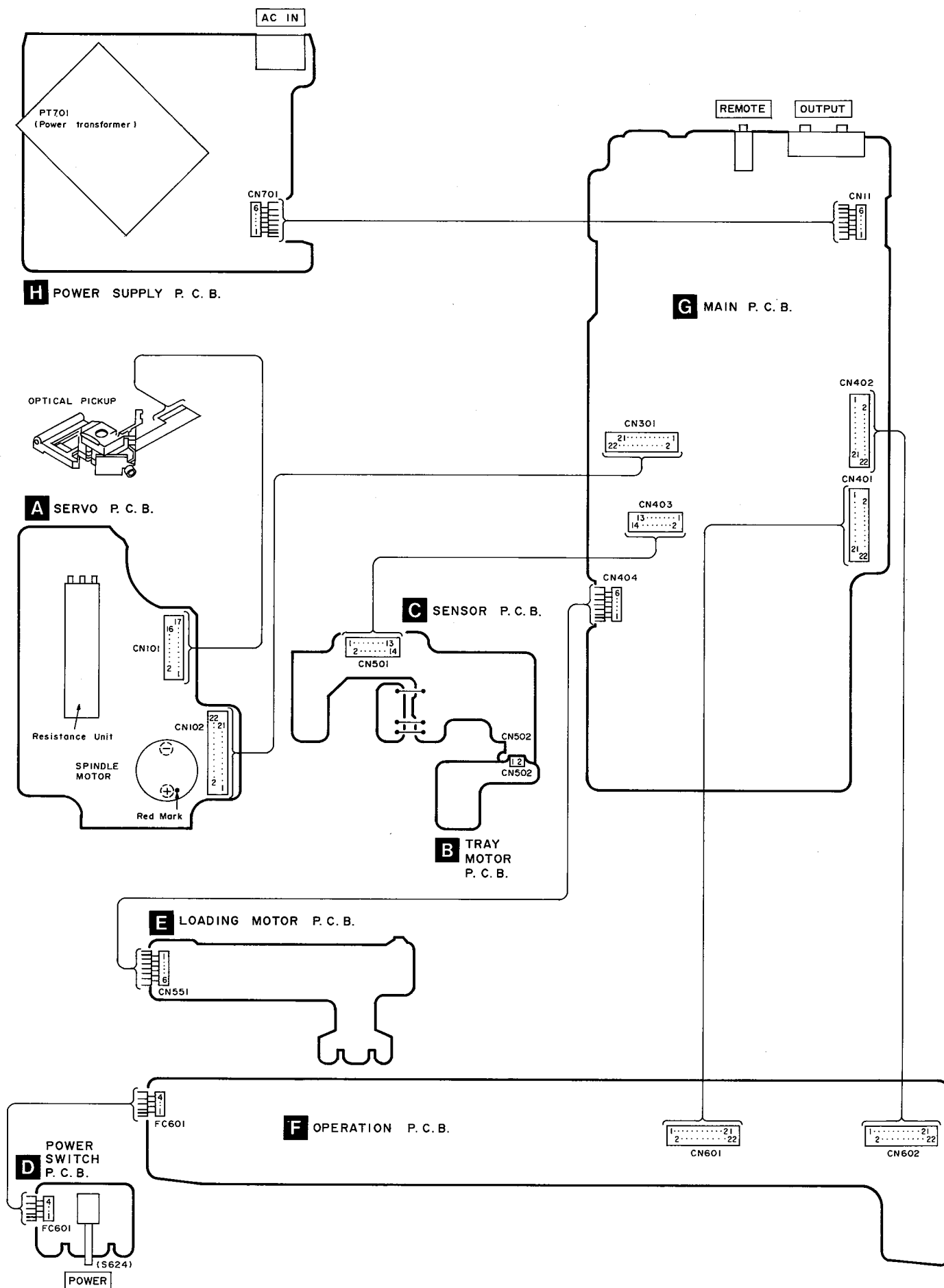
**E** OPERAT.  
(REP1274A-5)



**G** MAIN P.C.B.  
(REP1273H-M)



# WIRING CONNECTION DIAGRAM



# REPLACEMENT PARTS LIST

**Notes :** \* Important safety notice:

 Components identified by  $\Delta$  mark have special characteristics important for safety. When replacing any of these components use only manufacturer's specified parts.

 \* The parenthesized indications in the Remarks columns specify the areas. (Refer to the cover page for area.)  
 Parts without these indications can be used for all areas.

\* Warning: This product uses a laser diode. Refer to caution statements on page 2.

Ref. No.	Part No.	Part Name & Description	Remarks	Ref. No.	Part No.	Part Name & Description	Remarks
		INTEGRATED CIRCUIT(S)		D301	1SS254TA	DIODE	
				D401, 402	1SS254TA	DIODE	
				D404-410	1SS254TA	DIODE	
IC11	LM2940T5	IC, REGULATOR		D452, 453	1SS254TA	DIODE	
IC101	AN8800SCE2	IC, SERVO AMP		D461	MTZJ6R2BTA	DIODE	
IC102	MN6650	IC, DIGITAL SERVO PROCESSOR		D462	MTZJ4R3BTA	DIODE	
IC103	AN8377N	IC, COIL DRIVE		D471	1SS254TA	DIODE	
IC104	TC7SU04FT85R	IC, BUFFER AMP		D501, 502	RSQGP1S53V	DIODE	
IC301	MN6626	IC, DIGITAL SIGNAL PROCESSOR		D503	RPR-363A	DIODE	
IC351	SVIBA4558F	IC, SPINDLE MOTOR CONTROL		D801, 802	1SS254TA	DIODE	
IC401	MN187164PME1	IC, SYSTEM CONTROL&FL DRIVE		D851, 852	1SS254TA	DIODE	
IC481	BA10393FT2	IC, DISC TRAY SPEED CONTROL				VARIABLE RESISTOR(S)	
IC501	BA6247N	IC, MOTOR DRIVE					
IC801	MN6475A-T1	IC, DIGITAL FILTER&D/A CONV.		VR101	EVND3AA00B14	V. R. BEST EYE ADJUSTMENT	
IC802	SVIBA4558F	IC, L. P. F.				COIL(S)	
		TRANSISTOR(S)					
Q11-13	2SD1862QRTV6	TRANSISTOR		L101	RLB0003	COIL	
Q14	2SB1240-P	TRANSISTOR		L102	RELJHC6R8KTD	COIL	
Q15	2SD1862QRTV6	TRANSISTOR		L473	ELEXT1R2KA9	COIL	
Q21	2SC3311A-Q	TRANSISTOR		L701, 702	SLQX400-D	COIL	$\Delta$
Q22	2SA1309A-R	TRANSISTOR		L801, 802	ELEXT1R2KA9	COIL	
Q31	2SB1238QSTV6	TRANSISTOR				TRANSFORMER	
Q101	2SA1547QTV2	TRANSISTOR					
Q351	UN4112	TRANSISTOR		PT701	RTP1K4C011	POWER TRANSFORMER	$\Delta$
Q352	2SD1862QRTV6	TRANSISTOR				COMPONENT COMBINATION(S)	
Q353	2SB1240-P	TRANSISTOR					
Q401, 402	2SA1309A-R	TRANSISTOR					
Q451	UN4212TA	TRANSISTOR		Z301	BL02RN2R62T4	COMBINATION PART	
Q461, 462	UN4215	TRANSISTOR		Z401	BL02RN2R62T4	COMBINATION PART	
Q472	UN4212TA	TRANSISTOR		Z802, 803	BL02RN2R62T4	COMBINATION PART	
Q473	2SA1309A-R	TRANSISTOR				OSCILLATOR(S)	
Q801, 802	2SD1450RTA	TRANSISTOR					
Q851	UN4112	TRANSISTOR		X101	RSXZ16M9M01T	OSCILLATOR (16.9344MHz)	
Q852	UN4212TA	TRANSISTOR		X801	RSXZ16M9M01T	OSCILLATOR (16.9344MHz)	
Q853	UN4112	TRANSISTOR				DISPLAY TUBE(S)	
		DIODE(S)					
D11-13	SVD1SR35200A	DIODE	$\Delta$	FL601	RSL0121-F	DISPLAY TUBE	$\Delta$
D15, 16	MTZJ9R1CTA	DIODE				SWITCH(ES)	
D21, 22	SVD1SR35200A	DIODE	$\Delta$				
D23, 24	MTZJ10CTA	DIODE		S551	RSH2A001-2	SW, UP/DOWN DETECTOR	
D31, 32	SVD1SR35200A	DIODE	$\Delta$	S552	RSH1A017-U	SW, OPEN DETECTOR	
D33	MTZJ27DTA	DIODE					
D34	MTZJ8R2CTA	DIODE	$\Delta$				



Ref. No.	Part No.	Part Name & Description	Remarks	Ref. No.	Part No.	Part Name & Description	Remarks
S601	EVQ21405R	SW, SPIRAL				CABINET AND CHASSIS	
S602	EVQ21405R	SW, ONE DISC (RANDOM)					
S603	EVQ21405R	SW, FULL (RANDOM)		1	RKM0193-K	CABINET	
S604	EVQ21405R	SW, REPEAT		2	SNE2129-3	SCREW	
S605	EVQ21405R	SW, TIME MODE		3	XTBS3+8JFZ1	SCREW	
S608	EVQ21405R	SW, R. SEARCH		4	RDG0198	OPEN LOCK GEAR	
S609	EVQ21405R	SW, F. SEARCH		5	RDG0199	CLOSE LOCK GEAR	
S610	EVQ21405R	SW, DISC1		6	REZ0397-1	FPC BOARD(22P)	
S611	EVQ21405R	SW, DISC2		7	REZ0474	FPC BOARD(22P)	
S612	EVQ21405R	SW, DISC3		8	REZ0475	FPC BOARD(22P)	
S613	EVQ21405R	SW, DISC4		9	REZ0476	FPC BOARD(14P)	
S614	EVQ21405R	SW, DISC5		10	REZ0477	FLAT CABLE(6P)	
S615	EVQ21405R	SW, PROGRAM MODE		11	REZ0478	FLAT CABLE(6P)	
S616	EVQ21405R	SW, R. SKIP		12	RGRO140A-A	REAR PANEL	
S617	EVQ21405R	SW, F. SKIP		13	RGTO007	ROTARY TRAY	
S618	EVQ21405R	SW, DISC SKIP		14	RHW81001-1	WASHER	
S619	EVQ21405R	SW, OPEN/CLOSE		15	RKQ0089	P. C. B. SUPPORT	
S620	EVQ21405R	SW, STOP		16	RKQ0104	REAR COVER	
S621	EVQ21405R	SW, PAUSE		17	RMB0255	SPRING(DISC TRAY)	
S622	EVQ21405R	SW, PLAY		18	RME0111-1	SPRING(LOCK GEAR)	
S624	SSH1230	SW, POWER	△	19	RFKJLPD627PK	CHASSIS ASS'Y	
		CONNECTOR(S) & SOCKET(S)		19-1	RKA0053-A	FOOT	
CN11	RJS1A6606	CONNECTOR(6P)		20	RMR0540-K	TRAY BASE GUIDE(L)	
CN101	SJSD1727-1	CONNECTOR(17P)		21	RMR0541-K1	TRAY BASE GUIDE(R)	
CN102	SJSD2227-1	CONNECTOR(22P)		22	RMR0549-W	DISC GUARD	
CN301	RJS1A6822	CONNECTOR(22P)		23	RMR0551-W	GUARD CAM	
CN401, 402	RJS1A6822	CONNECTOR(22P)		24	RMR0575-W	SLIDER(B)	
CN403	RJS1A6814	CONNECTOR(14P)		25	RMR0577-W	ROLLER	
CN404	RJS1A6606	CONNECTOR(6P)		26	RMR0544-W	CLAMP PLATE	
CN501	RJS1A6714	CONNECTOR(14P)		27	SIRD51-1	CLAMPER	
CN502	RJR0094	SOCKET(2P)		28	SOMD4	MAGNET	
CN551	SJT30644-H	CONNECTOR(6P)		29	SOYD2	YOKE	
CN601, 602	RJS1A6222	CONNECTOR(22P)		30	RDV0024	BELT	
CN701	SJT30643-V	CONNECTOR(6P)		31	RMN0174	SENSOR HOLDER	
		FLAT CABLE(S)		32	RMR0547-K	WORM BASE	
FC601	REZ0455-1	FLAT CABLE(4P)		33	RXG0026	WORM ASS'Y	
		JACK(S)		34	REM0026	TRAY MOTOR ASS'Y(M501)	
JK472	RJJ33TR01	REMOTE CONTROL		35	RXQ0227-2	TRAY ASS'Y	
JK701	SJSD16	AC INLET	△	36	RMN0172	FL HOLDER	
JK801	RJH3201N	LINE OUT		37	RFKGLPD627PK	FRONT PANEL ASS'Y	
		MAGNET RESISTER ELEMENT		37-1	RGK0470	FRONT ORNAMENT PLATE	
RA1	EWS7M0A00Q53	RESISTANCE UNIT		38	RGU0030	POWER BUTTON	
				39	RGU0726	MAIN BUTTON	
				40	RGU0727	SUB BUTTON	
				41	XTB26+8J	SCREW	
				42	XTB3+10JFZ	SCREW	
				43	XTB3+20J	SCREW	
				44	XYES3+BJ10	SCREW	
				45	SHRD162	CORD HOLDER	
				46	RMAD606	GUIDE PLATE(R)	
				47	XTWS3+10Q	SCREW	
				48	XTB3+8JFZ	SCREW	

# REPLACEMENT PARTS LIST

**Notes :** \* Important safety notice:

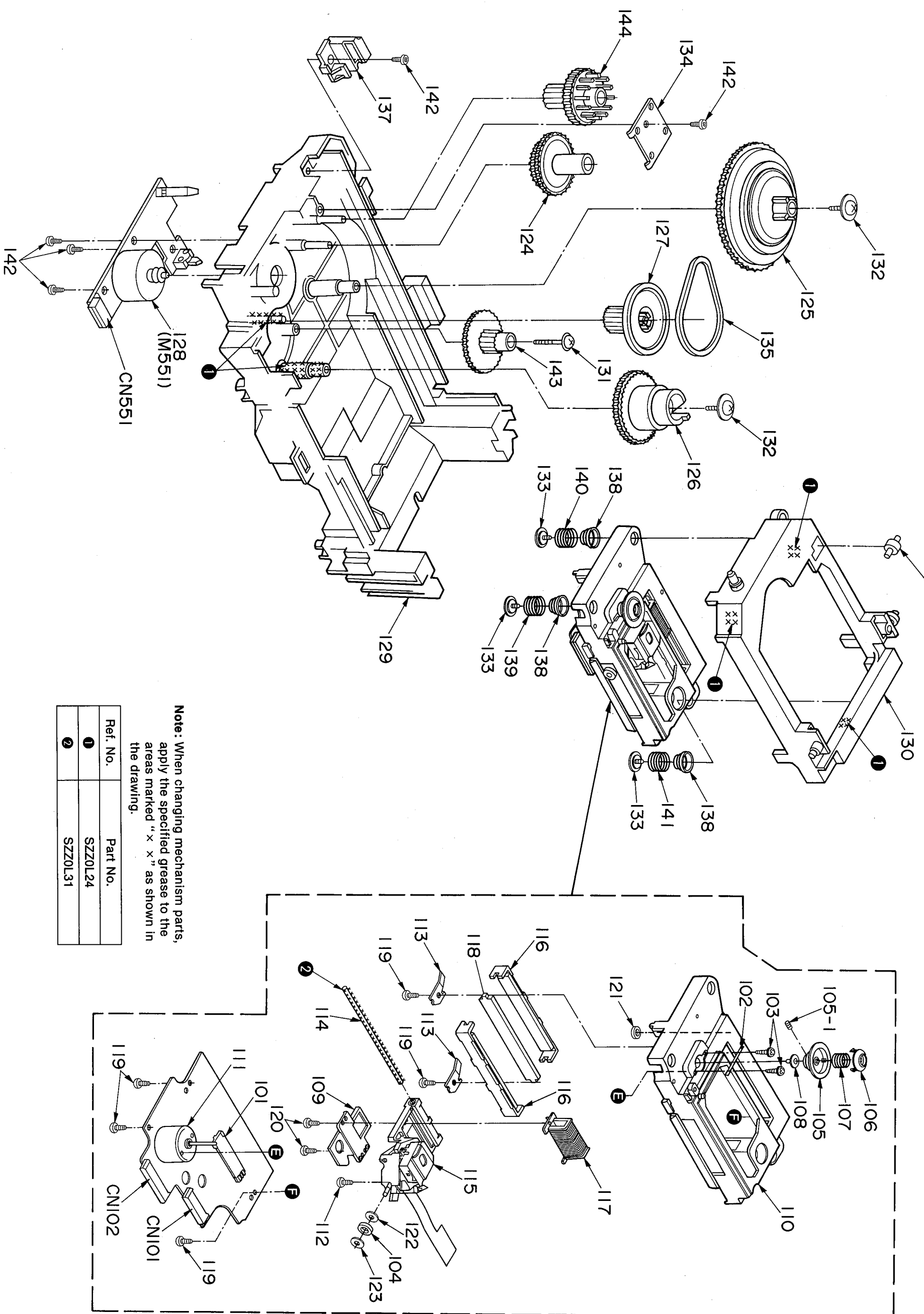
 Components identified by  $\Delta$  mark have special characteristics important for safety. When replacing any of these components use only manufacturer's specified parts.

 \* The parenthesized indications in the Remarks columns specify the areas. (Refer to the cover page for area.)  
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\* Warning: This product uses a laser diode. Refer to caution statements on page 2.

Ref. No.	Part No.	Part Name & Description	Remarks	Ref. No.	Part No.	Part Name & Description	Remarks
		TRAVERSE DECK		144	RDG0195	DRIVE GEAR(A)	
						PACKING MATERIAL	
101	SJED10	POTENTIOMETER HOLDER		P1	RPG1167	PACKING CASE	
102	RME0115	SIDE PRESSURE SPRING		P2	RPN0597	CUSHION	
103	RMQ0299	SCREW		P3	XZB60X65A01Z	PROTECTION BAG (UNIT)	
104	RMR0463	ROLLER		P4	XZB24X34C04	PROTECTION BAG (ACCESSORY)	
105	SD0D28-2E	TURNTABLE ASS'Y		P5	XZB26X17C03	PROTECTION BAG (CORD)	
105-1	XXE26D5	SCREW		P6	RPQ0164	PAD	
106	SD0D29-2	TURNTABLE RING				ACCESSORIES	
107	SRQA010N04	TURNTABLE SPRING		A1	RQT1453-P	INSTRUCTION MANUAL	(P)
108	RXQ0232	SIDE PRESSURE PULLEY		A1	RFKSLPD627PC	INST. MANUAL ASS'Y	(PC)
109	SHRD176-E	BRUSH HOLDER		A2	SQX7179	WARRANTY CARD	(P)
110	SISD22-7	TRAVERSE BASE		A2	SQX7183	WARRANTY CARD	(PC)
111	SJGDRF310T-2	SPINDLE MOTOR		A3	SQX9129-1	SERVICENTER LIST	(P)
112	SNSD31	SCREW		A4	SJA172-1	AC POWER SUPPLY CORD	(P) $\Delta$
113	SUWD112-2	SHAFT HOLDER		A4	SJA172	AC POWER SUPPLY CORD	(PC) $\Delta$
114	SUXD123-1	GUIDE SHAFT		A5	SJP2249-3	STEREO CONNECTION CABLE	
115	SOAD70A	OPTICAL PICKUP		A6	SJP2257T	REMOTE CONTROL CABLE	
116	RFKNLPC363P	YOKE (A) ASS'Y					
117	SORD46-E	COIL ASS'Y					
118	SOYD22-1	YOKE (B)					
119	XTB3+10G	SCREW					
120	SNSD39	SCREW					
121	SHGD148	STOPPER RUBBER					
122	SHWD33	WASHER					
123	SHWD34	WASHER					
124	RDG0196	DRIVE GEAR(B)					
125	RDK0017	DRIVE CAM					
126	RDK0018	ELEVATION CAM					
127	RDPO050	PULLEY GEAR					
128	RXQ0252	LOADING MOTOR ASS'Y (M551)					
129	RXQ0250	MECHANISM BASE ASS'Y					
130	RXQ0251	SUB BASE ASS'Y					
131	RHD30029	SCREW					
132	RHD30030	SCREW					
133	RHD30031	SCREW					
134	RMA0581	REINFORCING PLATE					
135	RMG0268-K	BELT					
136	RMR0564-W2	ROLLER(A)					
137	RMR0565-W1	SLIDER					
138	SHGD153-1	FLOATING RUBBER					
139	SUSD136-3	FLOATING SPRING (A)					
140	SUSD137-1	FLOATING SPRING (B)					
141	SUSD145-1	FLOATING SPRING (C)					
142	XTB3+10JFZ	SCREW					
143	RDG0194	SLOWING DOWN GEAR					

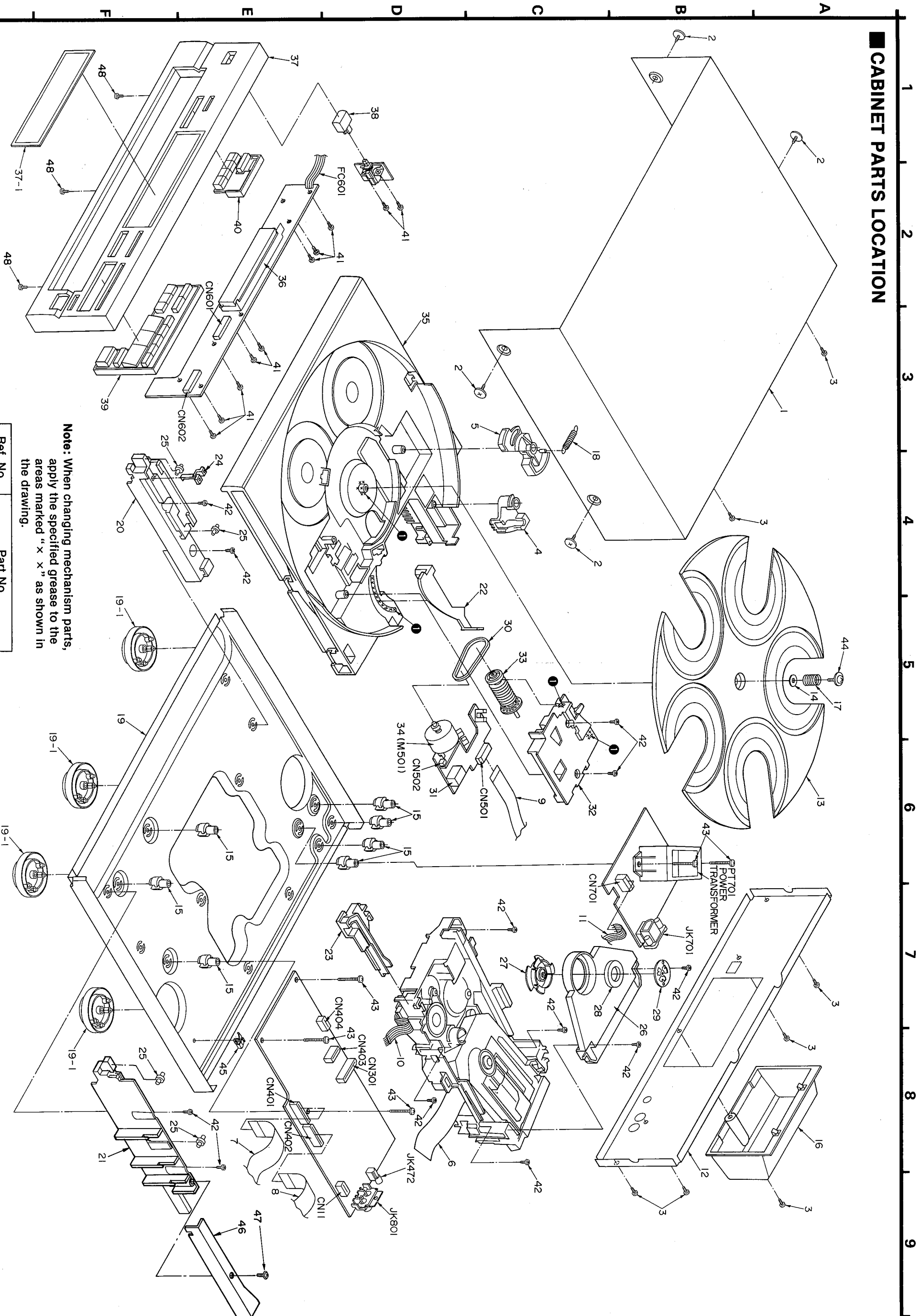
TRAVERSE DECK PARTS LOCATION



**Note:** When changing mechanism parts, apply the specified grease to the areas marked "x x x" as shown in the drawing.

Ref. No.	Part No.
1	SZZ0L24
2	SZZ0L31

CABINET PARTS LOCATION



**Note:** When changing mechanism parts, apply the specified grease to the areas marked "x x" as shown in the drawing.

Ref. No.	Part No.
①	SZ0124

# RESISTORS & CAPACITORS

Notes : \* Capacity values are in microfarads (uF) unless specified otherwise, P=Pico-farads (pF) F=Farads (F)  
 \* Resistance values are in ohms, unless specified otherwise, 1K=1,000 (OHM) , 1M=1,000k(OHM)

Ref. No.	Part No.	Values & Remarks	Ref. No.	Part No.	Values & Remarks	Ref. No.	Part No.	Values & Remarks
		RESISTORS	R408	ERDS2TJ472	1/4W 4.7K	C25, 26	ECEA1AKA221Q	10V 220U
			R409-411	ERDS2TJ3R3T	1/4W 3.3	C30	ECFR1E104ZF5	25V 0.1U
			R418-424	ERDS2TJ472	1/4W 4.7K	C31	ECA1HM470B	50V 47U Δ
R11	ERDS2TJ271	1/4W 270	R451	ERDS2TJ472	1/4W 4.7K	C32	ECA1HM470B	50V 47U
R12	ERDS2TJ102	1/4W 1K	R452	ERDS2TJ101	1/4W 100	C33	ECBT1H102KB5	50V 1000P
R13	ERDS2TJ271	1/4W 270	R455	ERDS2TJ821	1/4W 820	C101	ECEAOJKA220	6.3V 22U
R15-18	ERDS2TJ1R0	1/4W 1.0	R461	ERDS2TJ391	1/4W 390	C102	ECEA1HKS010	50V 1U
R19	ERDS2TJ2R2T	1/4W 2.2	R476	ERDS2TJ272T	1/4W 2.7K	C103	ECAOJKF1011	6.3V 100U
R21, 22	ERDS2TJ102	1/4W 1K	R477	ERDS2TJ562	1/4W 5.6K	C105	ECEAOJKS470	6.3V 47U
R25, 26	ERDS2TJ102	1/4W 1K	R478	ERDS2TJ103	1/4W 10K	C110	ECEA1CSM4R7I	16V 4.7U Δ
R31	ERDS2TJ100	1/4W 10 Δ	R479	ERDS2TJ100	1/4W 10	C111	ECUV1C393KBN	16V 0.039U
R32	ERDS2TJ682T	1/4W 6.8K	R481, 482	ERDS2TJ472	1/4W 4.7K	C112	ECUV1H392KBN	50V 3900P
R33	ERDS2TJ120T	1/4W 12 Δ	R483	ERDS2TJ224T	1/4W 220K	C113, 114	ECUV1C224KBM	16V 0.22U
R101	ERJ6GEYJ120V	1/10W 12	R484	ERDS2TJ334	1/4W 330K	C115	ECUV1H331KBN	50V 330P
R102	ERJ6GEYJ122V	1/10W 1.2K	R485, 486	ERDS2TJ473	1/4W 47K	C116, 117	ECEAOJKA470I	6.3V 47U
R103	ERJ6GEYJ823	1/10W 82K	R501, 502	ERDS2TJ473	1/4W 47K	C118, 119	ECUV1C104ZFN	16V 0.1U
R104	ERJ6GEYJ471V	1/10W 470	R503	ERDS2TJ271	1/4W 270	C120	ECUV1H122KBN	50V 1200P
R105	ERJ6GEYJ104V	1/10W 100K	R505	ERDS2TJ203T	1/4W 20K	C121	ECUV1C105ZFM	16V 1U
R106	ERJ6GEYJ223V	1/10W 22K	R801, 802	ERDS2TJ182	1/4W 1.8K	C122	ECUV1E103KBN	25V 0.01U
R107	ERJ6GEYJ153V	1/10W 15K	R803, 804	ERDS2TJ473	1/4W 47K	C123	ECUV1C104ZFN	16V 0.1U
R108	ERJ6GEYJ223V	1/10W 22K	R805, 806	ERDS2TJ822	1/4W 8.2K	C124	ECAOJKF1011	6.3V 100U
R109	ERJ6GEYJ122V	1/10W 1.2K	R807, 808	ERDS2TJ153	1/4W 15K	C125	ECEA1CKS470I	16V 47U
R110, 111	ERJ6GEYJ102V	1/10W 1K	R809-812	ERDS2TJ333	1/4W 33K	C126	ECEAOJKS470	6.3V 47U
R112	ERJ6GEYJ333V	1/10W 33K	R813, 814	ERDS2TJ561	1/4W 560	C127, 128	ECUV1E153KBN	25V 0.015U
R113	ERJ6GEYJ103V	1/10W 10K	R815, 816	ERDS2TJ102	1/4W 1K	C129	ECEA1HSN010I	50V 1U Δ
R114	ERJ6GEYJ473V	1/10W 47K	R817, 818	ERDS2TJ473	1/4W 47K	C130	ECEA1CSN100I	16V 10U Δ
R115	ERJ6GEYJ471V	1/10W 470	R819, 820	ERDS2TJ391	1/4W 390	C131	ECEA1HKS010	50V 1U
R116	ERJ6GEYJ220	1/10W 22	R824	ERDS2TJ681	1/4W 680	C132	ECUV1H681KBN	50V 680P
R117	ERJ6GEYJ103V	1/10W 10K	R825	ERDS2TJ470	1/4W 47	C133	ECEAOJKS470	6.3V 47U
R118-120	ERJ6GEYJ102V	1/10W 1K	R851	ERDS2TJ222	1/4W 2.2K	C134	ECUV1H222KBN	50V 2200P
R121	ERJ6GEYJ562V	1/10W 5.6K	R852, 853	ERDS2TJ102	1/4W 1K	C135	ECEA1EKS330I	25V 33U
R301	ERDS2TJ823T	1/4W 82K			CHIP JUMPER(S)	C136	ECUV1C104ZFN	16V 0.1U
R302	ERDS2TJ473	1/4W 47K				C138	ECUV1C224KBM	16V 0.22U
R303	ERDS2TJ105T	1/4W 1M				C139	ECUV1E103KBN	25V 0.01U
R304	ERDS2TJ473	1/4W 47K	RJ101	ERJ6GEYOR00V	CHIP JUMPER	C140, 141	ECUV1H270KCN	50V 27P
R305	ERDS2TJ221	1/4W 220	TJ101, 102	ERD25VOR00T	CHIP JUMPER	C142	ECUV1H271KN	50V 270P
R306	ERDS2TJ682T	1/4W 6.8K				C301	ECFR1E104ZF5	25V 0.1U
R307	ERDS2TJ472	1/4W 4.7K			CAPACITORS	C302	ECEAOJKA470B	6.3V 47U
R308-310	ERDS2TJ561	1/4W 560				C305	ECBT1C103NS5	16V 0.01U
R351	ERDS2TJ334	1/4W 330K	C11, 12	ECBT1E103ZF	25V 0.01U Δ	C306	ECBT1H102KB5	50V 1000P
R352	ERDS2TJ333	1/4W 33K	C13	ECEA1EU222B	25V 2200U	C307	ECQV1H823JZ	50V 0.082U
R353	ERDS2TJ123	1/4W 12K	C14	ECA1EM471B	25V 470U	C308	ECQV1H474JZ3	50V 0.47U
R354, 355	ERDS2TJ333	1/4W 33K	C15, 16	ECBT1H102KB5	50V 1000P	C309	ECBT1C103NS5	16V 0.01U
R356	ERDS2TJ101	1/4W 100	C17	ECEA1AU471	10V 470U	C351-353	ECBT1H102KB5	50V 1000P
R357	ERDS2TJ334	1/4W 330K	C18	ECEA1AKA101B	10V 100U	C401	ECBT1H104ZF5	50V 0.1U
R358	ERDS2TJ8R2T	1/4W 8.2	C19	ECEAOJKA331Q	6.3V 330U	C402	ECEAOJKA331Q	6.3V 330U
R401-404	ERDS2TJ473	1/4W 47K	C21	ECA1EM101B	25V 100U	C403	ECBT1E103ZF	25V 0.01U
R405	ERDS2TJ103	1/4W 10K	C22	ECEA1EU221	25V 220U	C451	ECEA1HKN010B	50V 1U Δ
R406, 407	ERDS2TJ332	1/4W 3.3K	C23, 24	ECBT1H102KB5	50V 1000P	C474	ECBT1C103NS5	16V 0.01U

Ref. No.	Part No.	Values & Remarks					
C483	ECBT1H221KB5	50V 220P					
C501	ECBT1C103NS5	16V 0.01U					
C502	ECEA1AKA470E	10V 47U					
C551	ECBT1C103NS5	16V 0.01U					
C801, 802	ECBT1H102KB5	50V 1000P					
C803, 804	ECEA1CKA100B	16V 10U					
C805, 806	ECCR1H391J5	50V 390P					
C807, 808	ECCR1H331J5	50V 330P					
C809, 810	ECEAOJKN220B	6.3V 22U $\Delta$					
C811, 812	ECBT1H102KB5	50V 1000P					
C813, 814	ECBT1C103NS5	16V 0.01U					
C815	ECEA1AKA470B	10V 47U					
C816	ECEA1AKA101B	10V 100U					
C817	ECEAOJKA101B	6.3V 100U					
C819, 820	ECBT1H100JC5	50V 10P					
C821	ECBT1H102KB5	50V 1000P					
C822	ECEAOJKA101B	6.3V 100U					
C823	ECBT1H6R8K5	50V 6.8P					
C824-826	ECBT1C103NS5	16V 0.01U					
C851	ECA1CM101B	16V 100U					

**PACKAGING**

